

Signal Encoding Techniques

Raj Jain

Washington University

Saint Louis, MO 63131

Jain@cse.wustl.edu

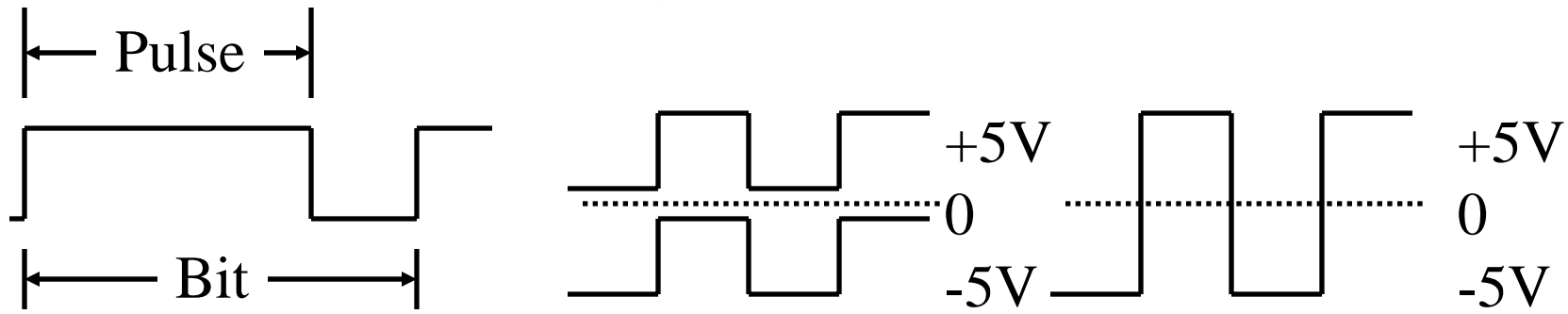
These slides are available on-line at:

<http://www.cse.wustl.edu/~jain/cse473-05/>



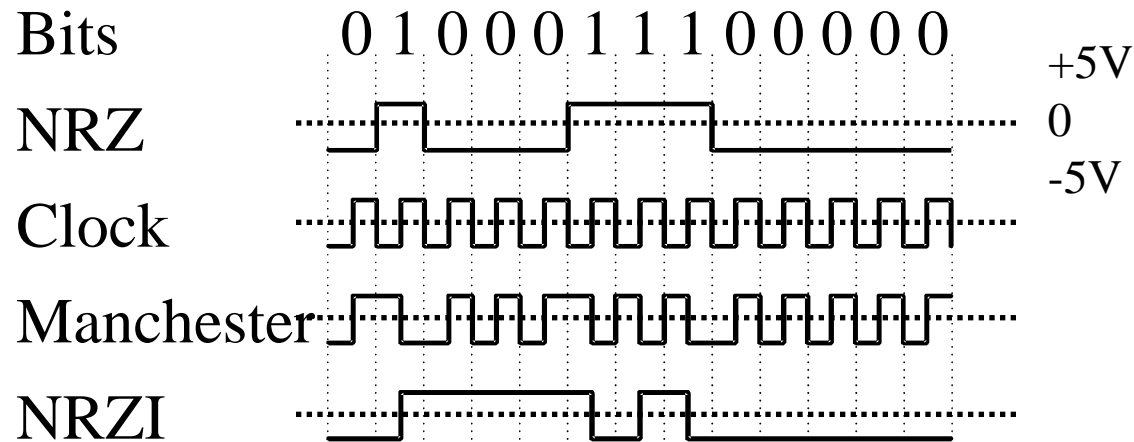
1. Coding Terminology and Design issues
2. Digital Data, Digital Signal: AMI, Manchester, etc.
3. Digital Data, Analog Signals: ASK, FSK, PSK, QAM
4. Analog Data, Digital Signals: PCM, Companding
5. Analog Data, Analog Signals: AM, FM

Coding Terminology



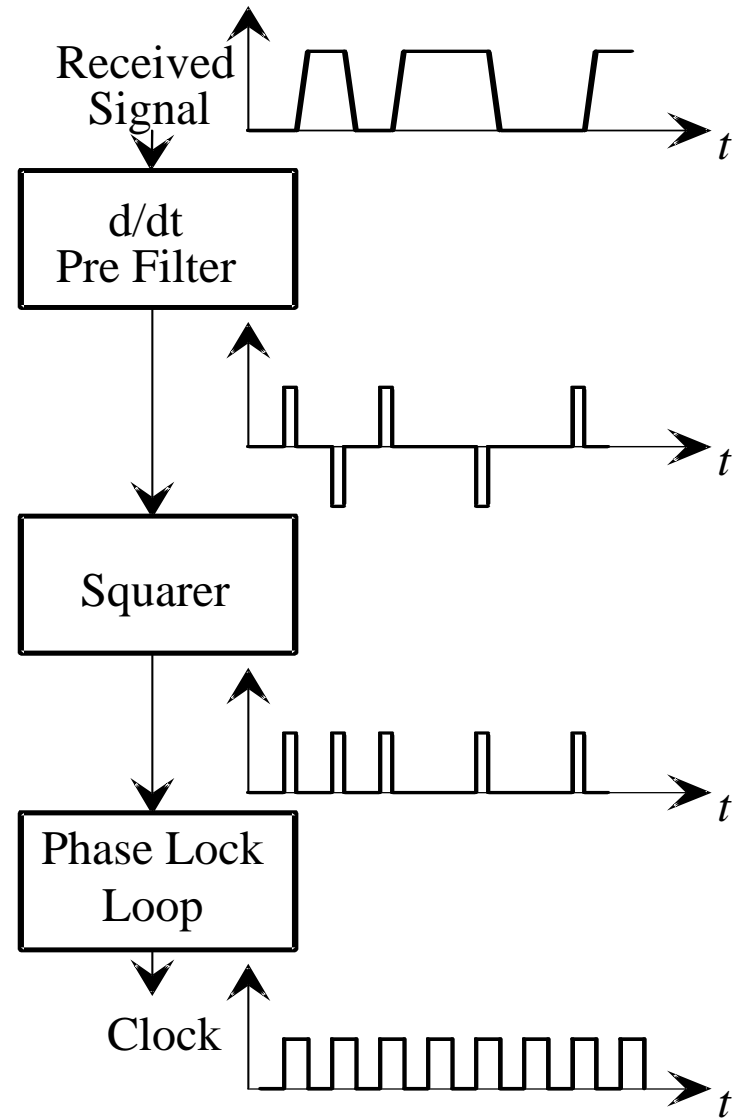
- ❑ **Signal element:** Pulse (of constant amplitude, frequency, phase)
- ❑ **Unipolar:** All positive or All negative voltage
- ❑ **Bipolar:** Positive and negative voltage
- ❑ **Mark/Space:** 1 or 0
- ❑ **Modulation Rate:** 1/Duration of the smallest element
=Baud rate
- ❑ **Data Rate:** Bits per second
- ❑ **Data Rate = F_n** (Bandwidth, signal/noise ratio, encoding)

Coding Design



1. Pulse width indeterminate: Clocking
2. DC, Baseline wander
3. No line state information
4. No error detection/protection
5. No control signals
6. High bandwidth
7. Polarity mix-up \Rightarrow Differential (compare polarity)

Clock Recovery Circuit



Digital Signal Encoding Formats

- Return-to-Zero (RZ)

0 = Remain at zero, 1 = +ve for $\frac{1}{2}$ bit duration

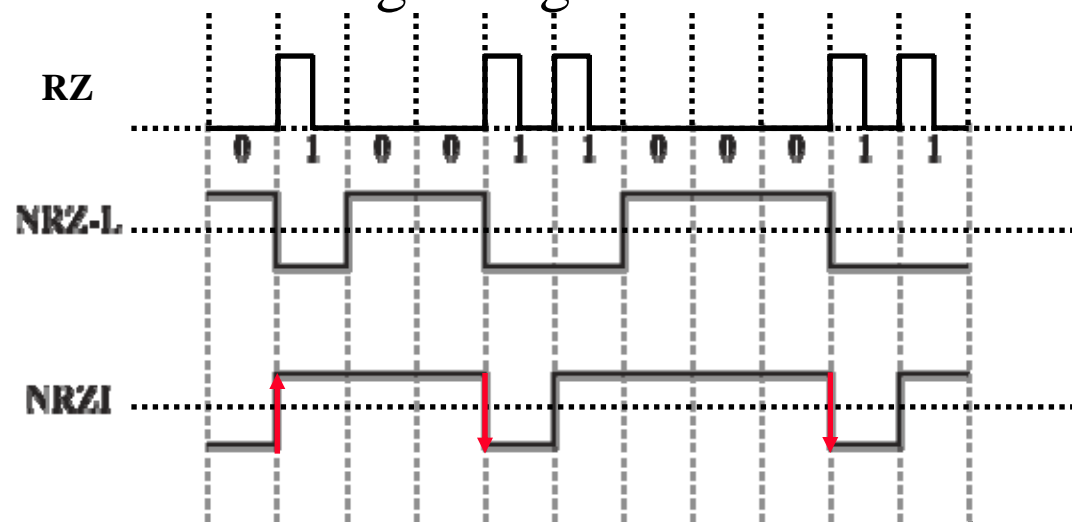
- Nonreturn-to-Zero-Level (NRZ-L)

0 = high level, 1 = low level

- Nonreturn to Zero Inverted (NRZI)

0 = no transition at beginning of interval (bit time)

1 = transition at beginning of interval



Multi-level Binary Encoding

❑ Bipolar-AMI:

0 = no line signal

1 = +ve or -ve for successive 1's

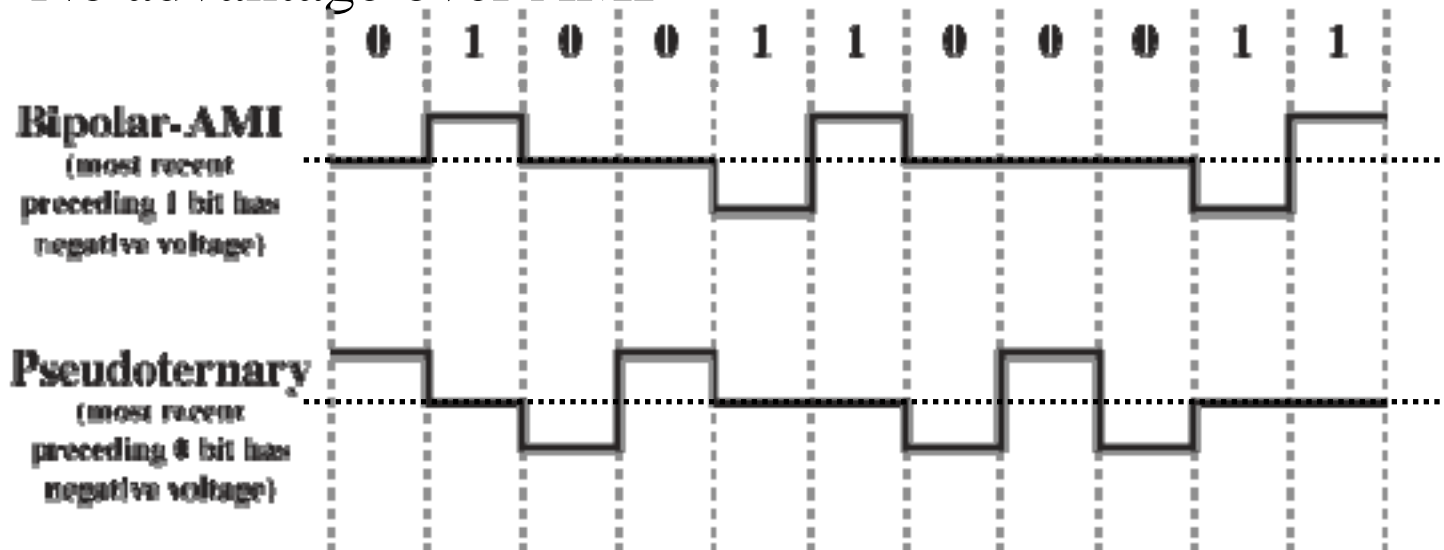
❑ Pseudo-ternary:

0 = +ve or -ve for successive 0's

1 = no line signal

No advantage over AMI

1. No loss of sync with 1's
2. zeros are a problem
3. No net dc component
4. Error detection
Noise \Rightarrow violation
5. Two bits/Hz
6. 3 dB higher S/N
7. 2b/Hz. Not 3.16 b/Hz



Bi-phase

□ Manchester: Used in Ethernet

0 = High to low transition in middle

1 = Low to high transition in middle

□ Differential Manchester:

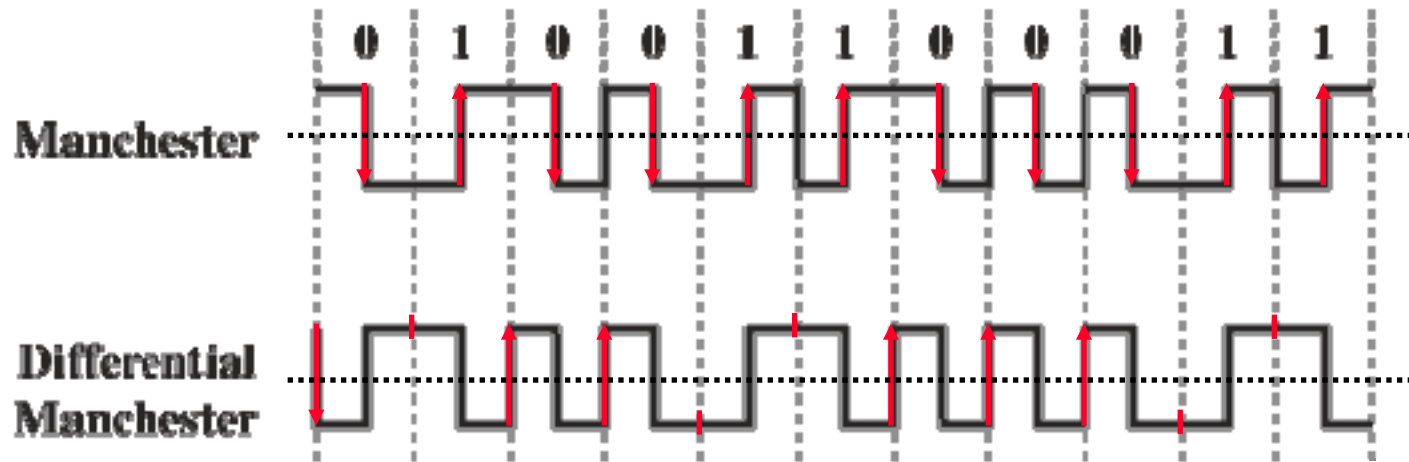
Used in Token Ring

Always a transition in middle

0 = transition at beginning

1 = no transition at beginning

1. No DC
2. Clock sync
3. Error detection
4. 1 bit/Hz,
5. baud rate
= $2 \times$ bit rate



Scrambling

□ Bipolar with 8-Zero Substitution (B8ZS):

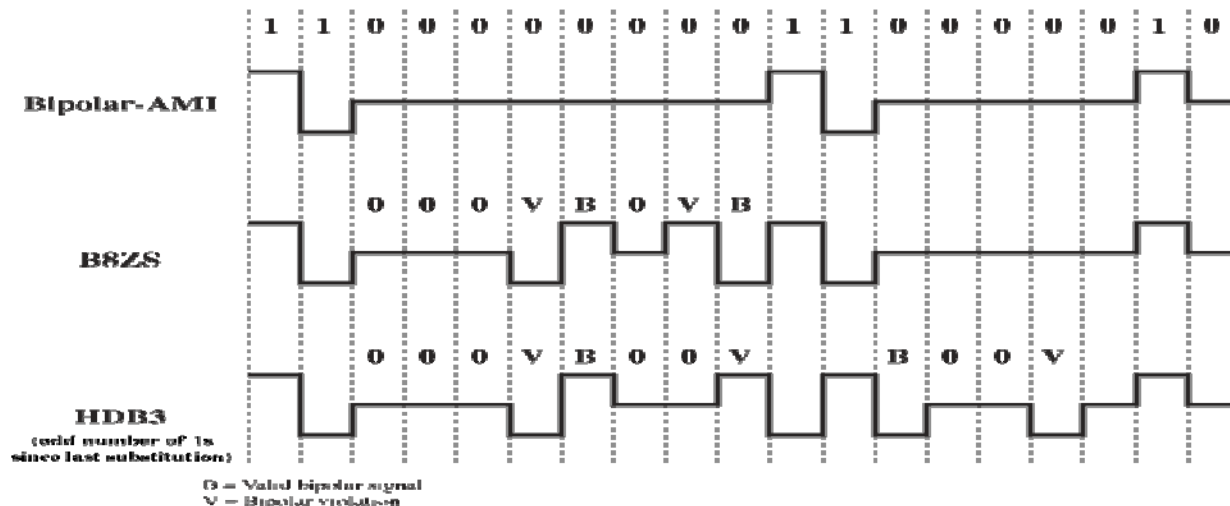
Same as AMI, except eight 0's replaced w two code violations

$$0000\ 0000 = 000V\ 10V1$$

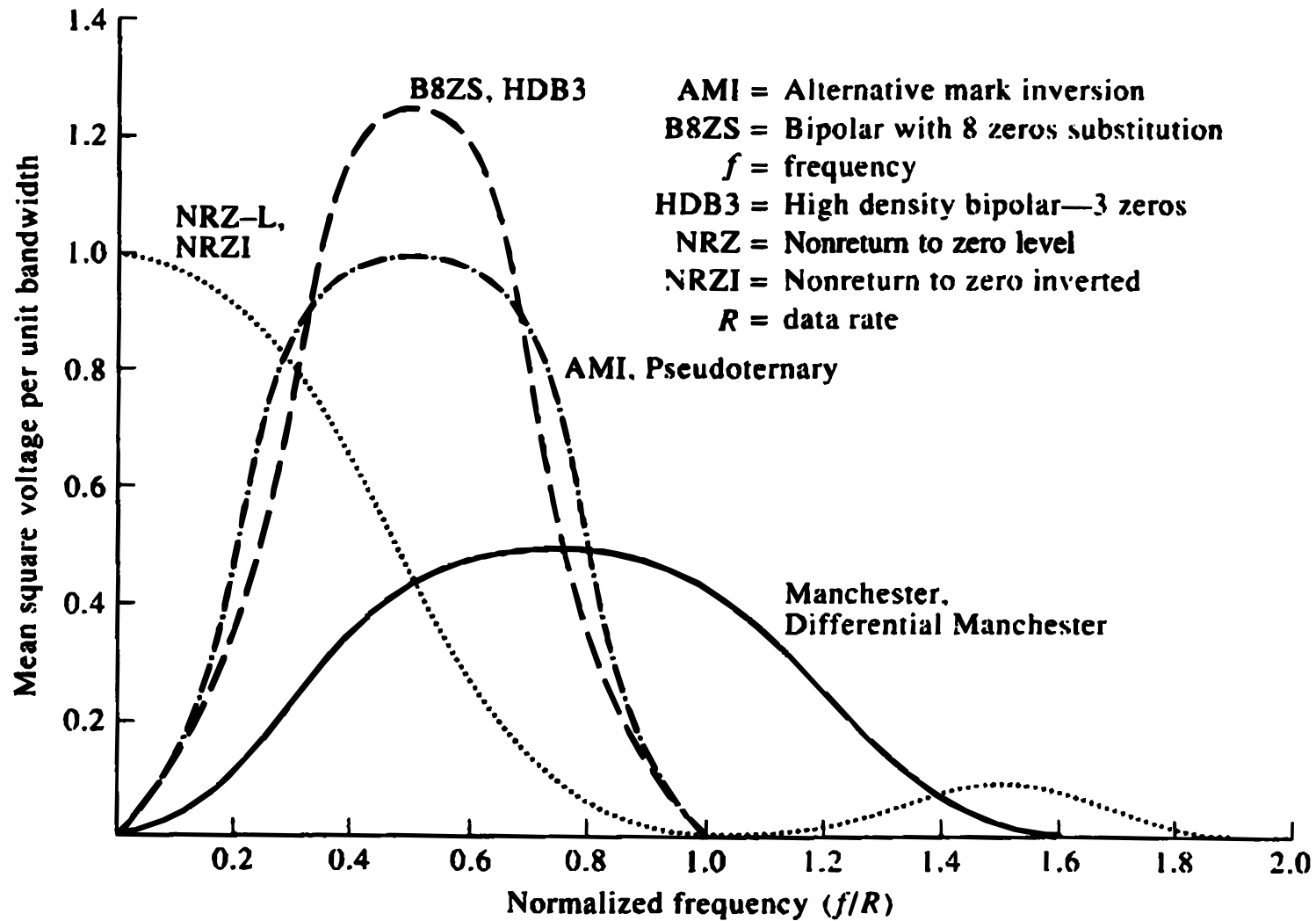
□ High Density Bi-polar w 3 Zeros (HDB3): Same as AMI, except that four 0's replaced with one code violation

0000 = 000V if odd number of ones since last substitution

100V otherwise

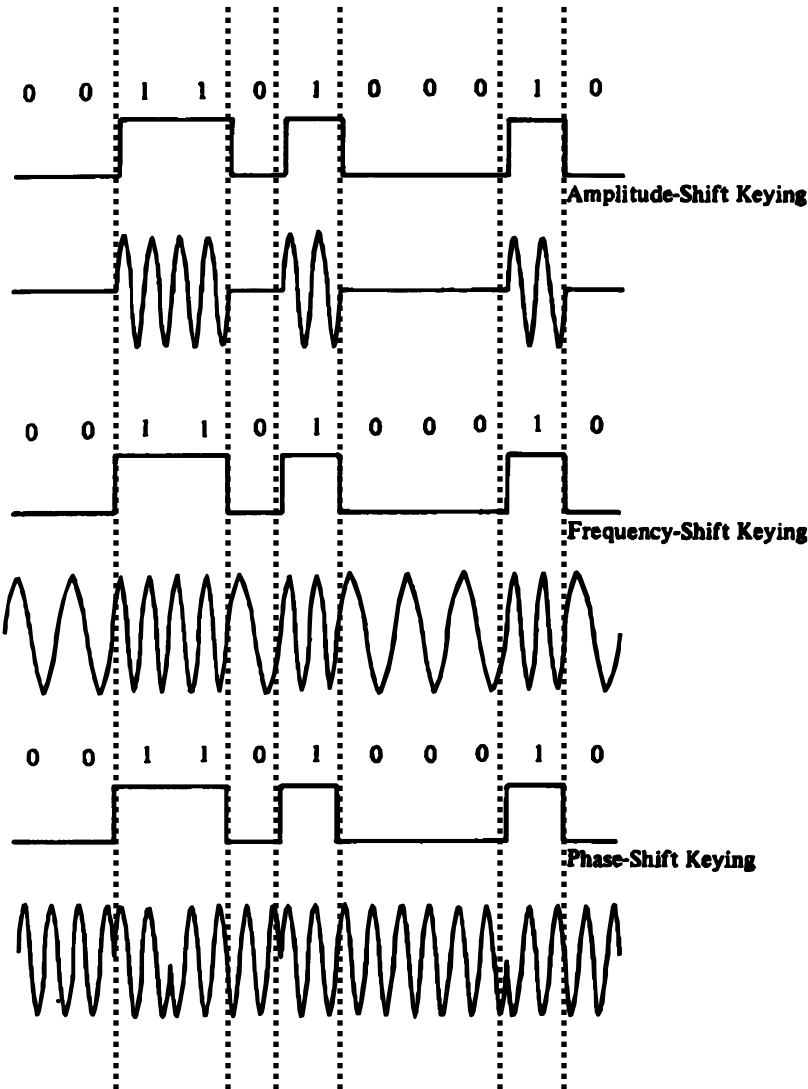


Signal Spectrum



Digital Data Analog Signals

ASK



$$A \sin(2\pi ft + \theta)$$

Used in
Optical Nets

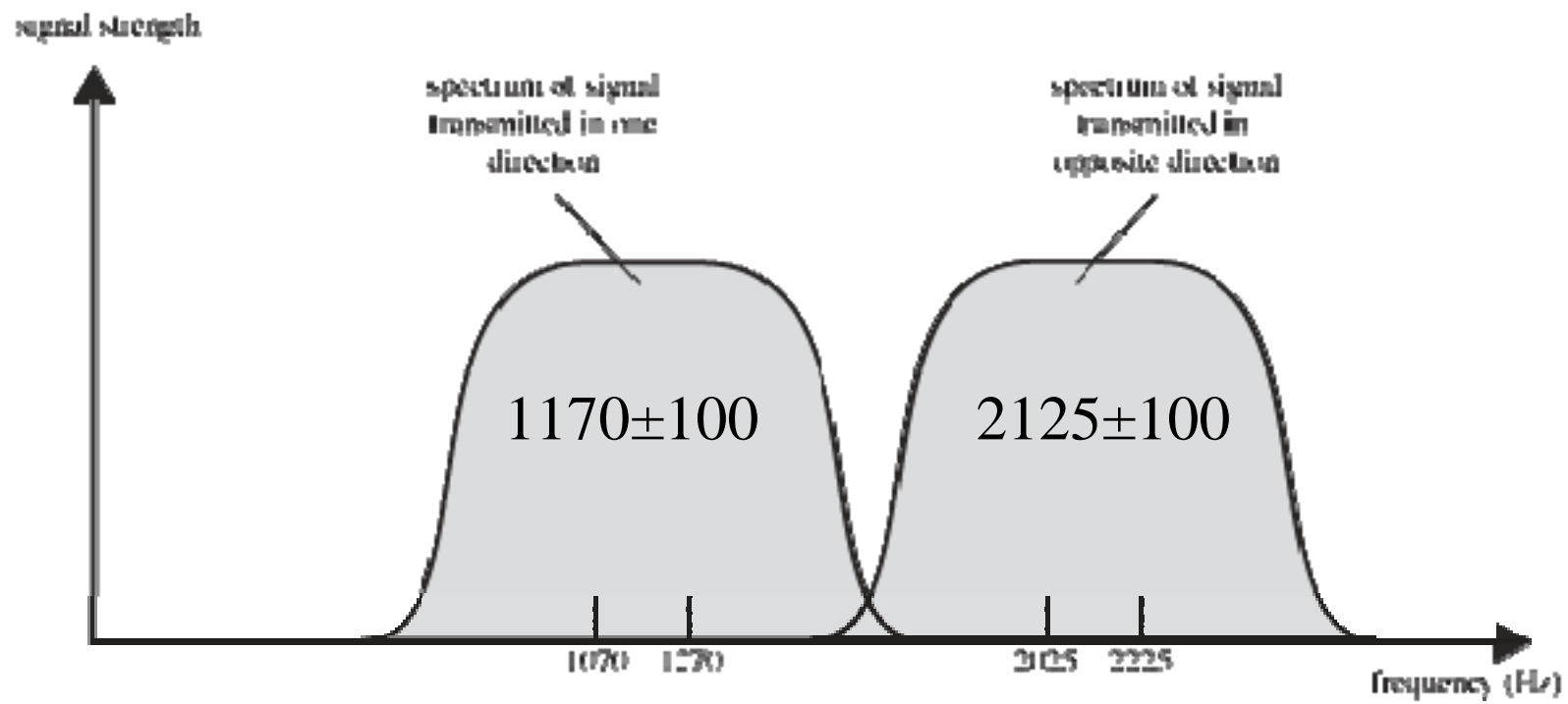
Used in
300-1200 bps
modems

FSK

FSK

Frequency Shift Keying (FSK)

- ❑ Less susceptible to errors than ASK
- ❑ Used in 300-1200 bps on voice grade lines



Phase-Shift Keying (PSK)

□ Differential PSK:

0 = Same phase, 1=Opposite phase

$A \cos(2\pi ft)$, $A \cos(2\pi ft + \pi)$

□ Quadrature PSK (QPSK): Two bits

11= $A \cos(2\pi ft + 45^\circ)$, 10= $A \cos(2\pi ft + 135^\circ)$,

00= $A \cos(2\pi ft + 225^\circ)$, 01= $A \cos(2\pi ft + 315^\circ)$

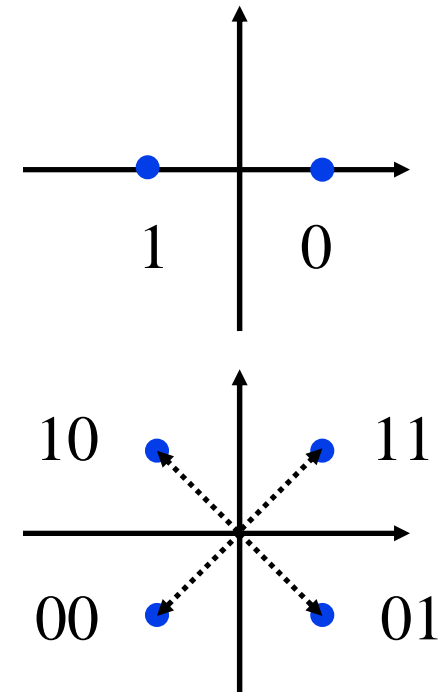
Sum of two signals 90° apart in phase

(In-phase I, Quadrature Q),

Up to 180° phase difference between successive intervals

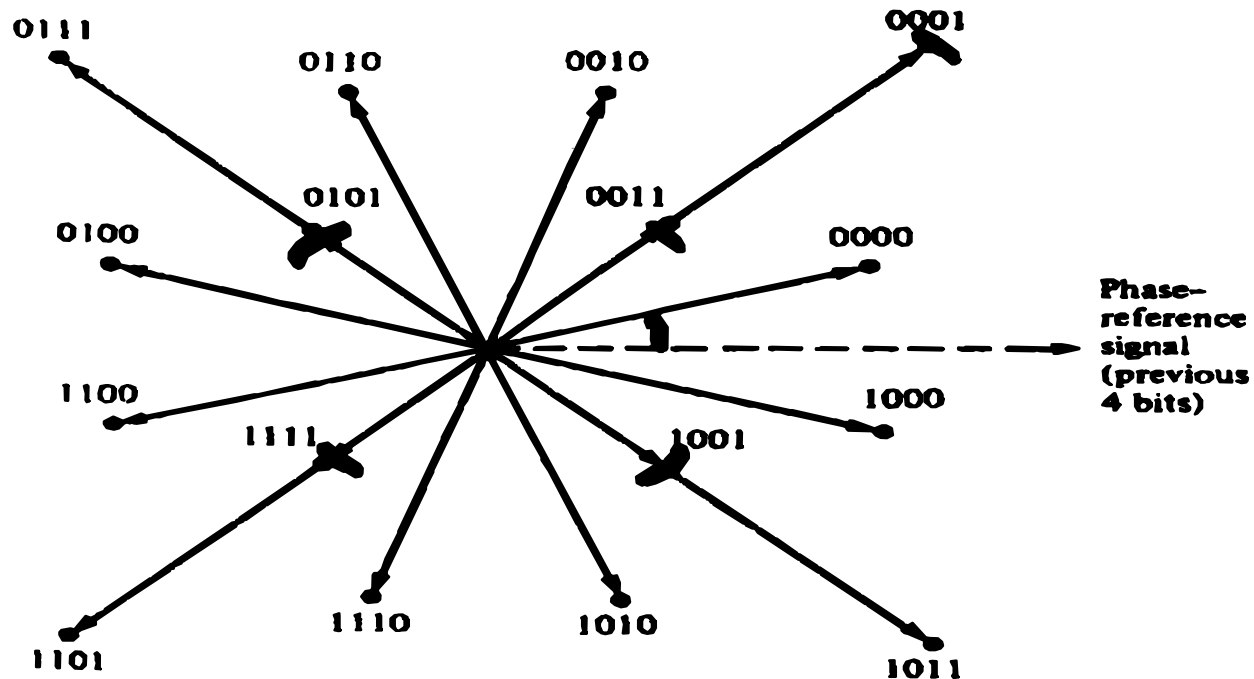
□ Orthogonal QPSK (OQPSK): Q stream delayed by 1 bit

Phase difference between successive bits limited to 90°



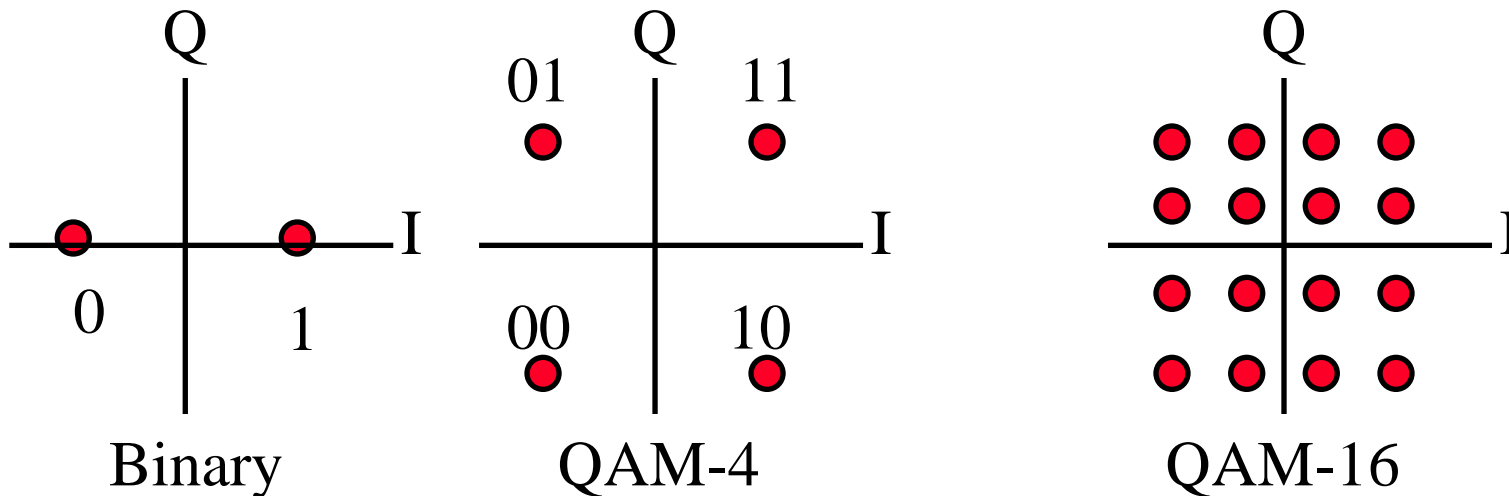
Multi-level PSK

- ❑ 9600 bps Modems use PSK with 4 bits
- ❑ 4 bits \Rightarrow 16 combinations
- ❑ 4 bits/element \Rightarrow 1200 baud
- ❑ 12 Phases, 4 with two amplitudes



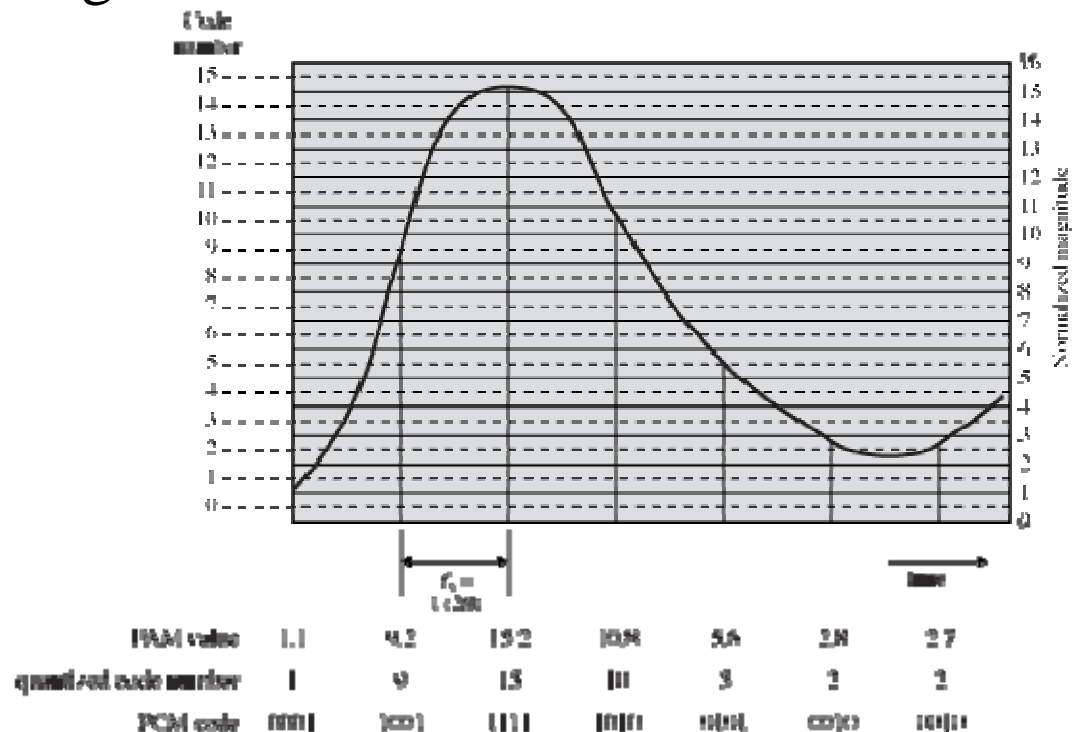
QAM

- ❑ Quadrature Amplitude and Phase Modulation
- ❑ QAM-4, QAM-16, QAM-64, QAM-256
- ❑ Used in DSL and wireless networks



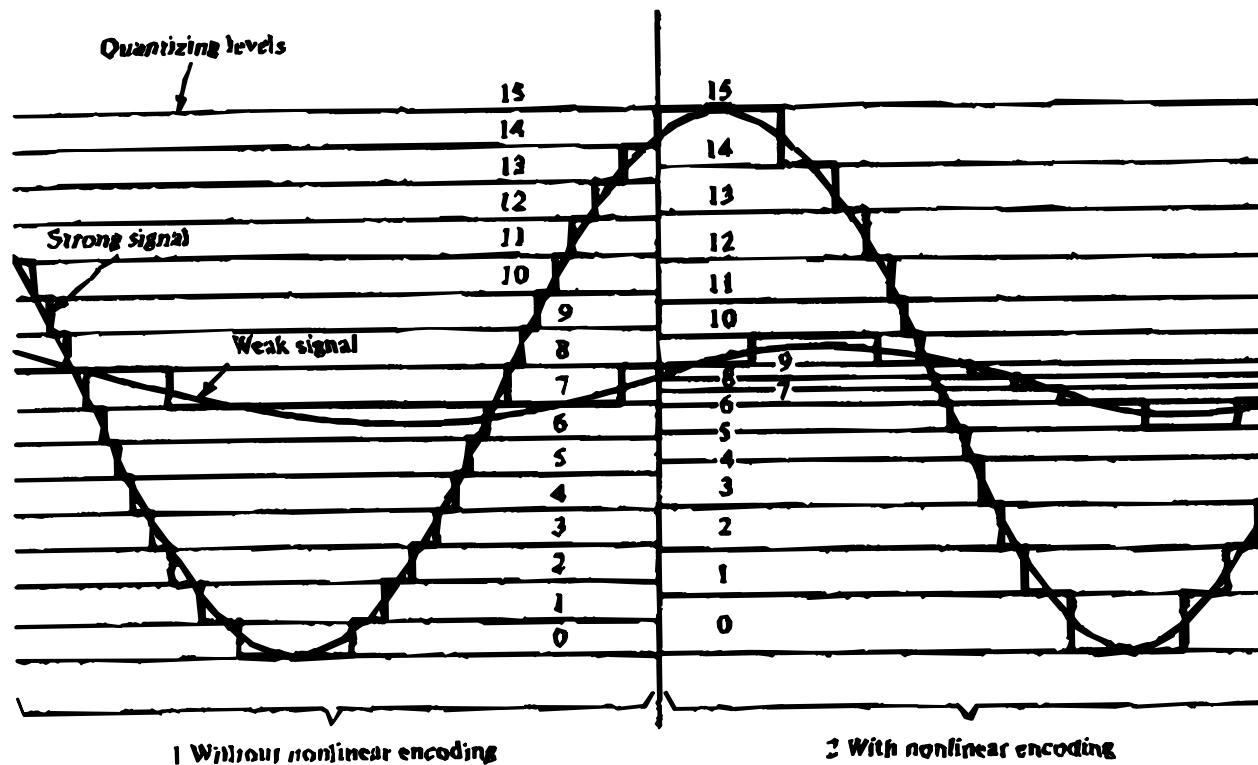
Analog Data, Digital Signals

- ❑ **Sampling Theorem:** $2 \times$ Highest Signal Frequency
- ❑ 4 kHz voice = 8 kHz sampling rate
8 k samples/sec \times 8 bits/sample = 64 kbps
- ❑ Quantizing Error with n bits: $S/N = 6.02n + 1.76$ dB



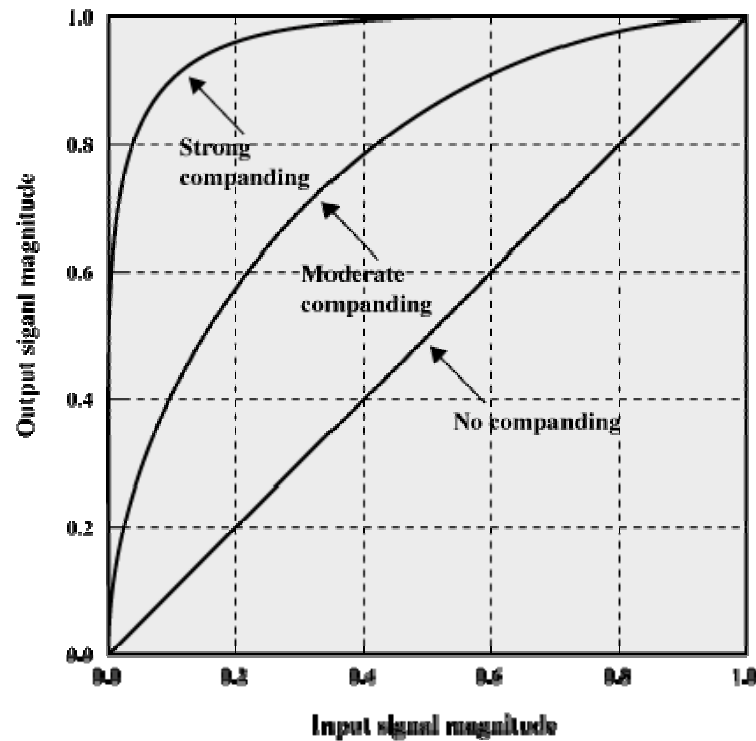
Nonlinear Encoding

- ❑ Linear: Same absolute error for all signal levels
- ❑ Non-linear: More steps for low signal levels



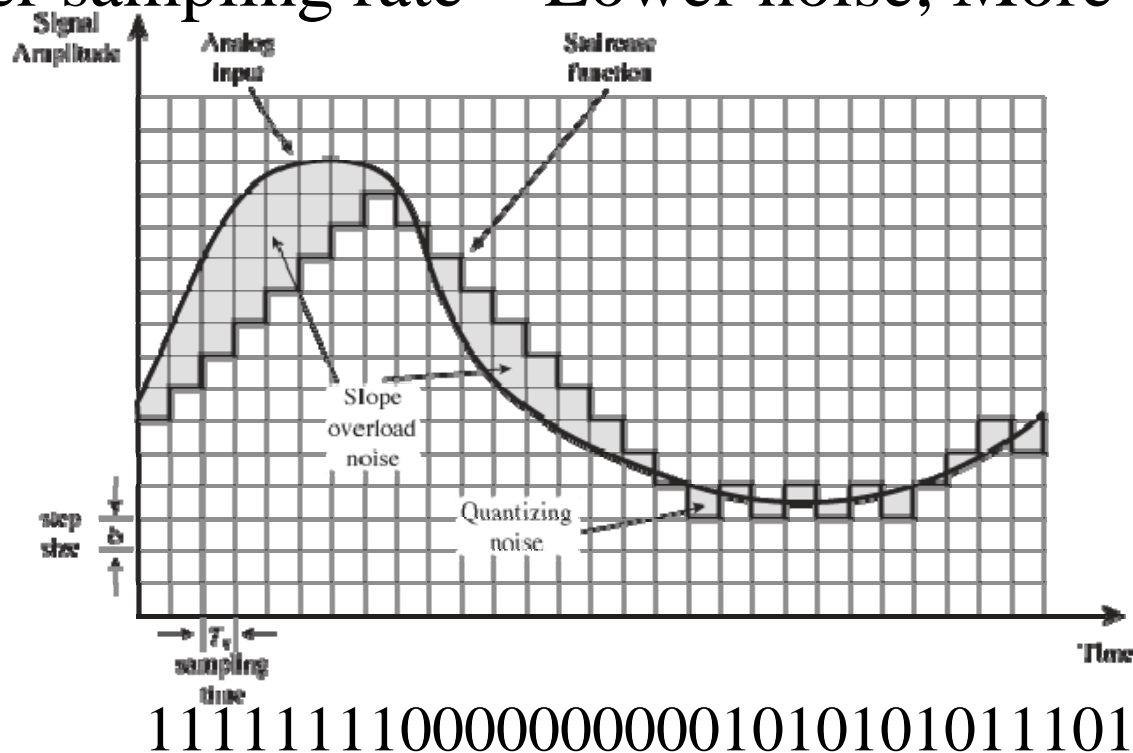
Companing

- ❑ Reduce the intensity range by amplifying weak signals more than the strong signals input
- ❑ Opposite is done at output



Delta Modulation

- ❑ 1 = Signal up one step, 0 = Signal down one step
- ❑ Larger steps \Rightarrow More quantizing noise,
Less slope overhead noise
- ❑ Higher sampling rate = Lower noise, More bits

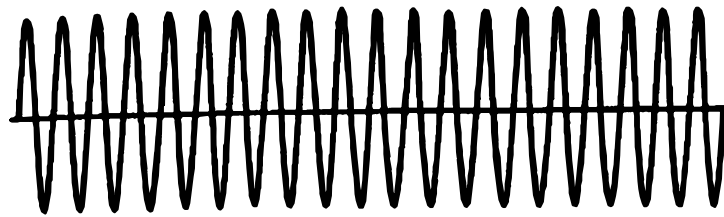


Analog Data, Analog Signals

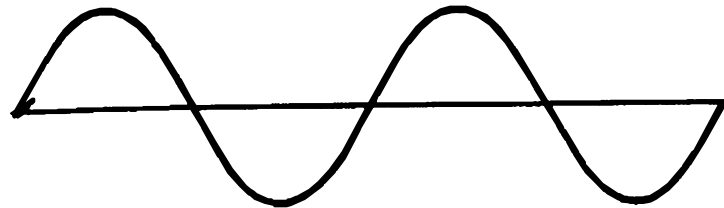
Amplitude Modulation (AM)

Frequency Modulation (FM)

Phase Modulation (PM)

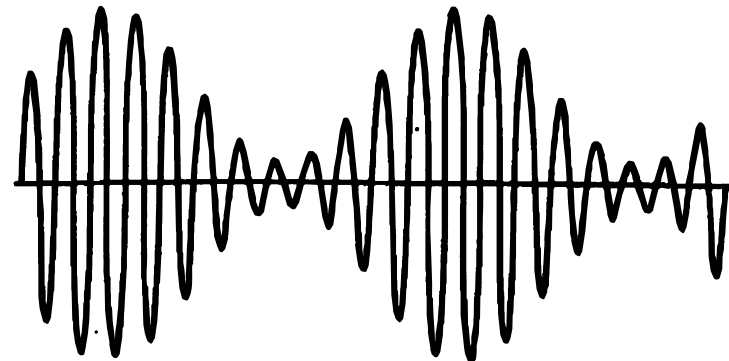


Carrier

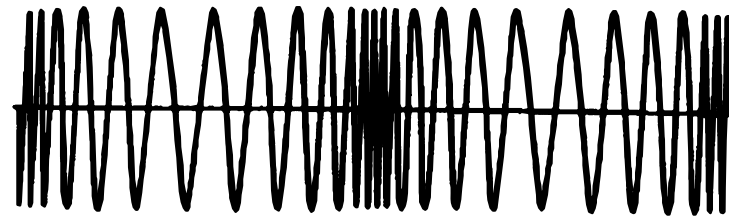


Modulating sine-wave signal

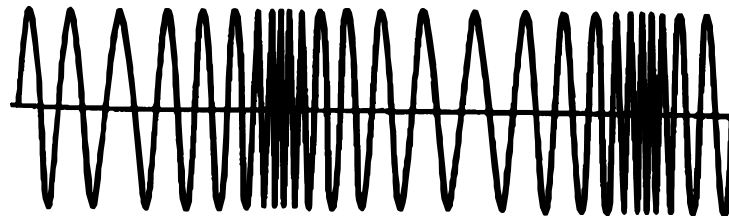
Both FM and PM are special cases of angle modulation



Amplitude-modulated (DSB-TC) wave

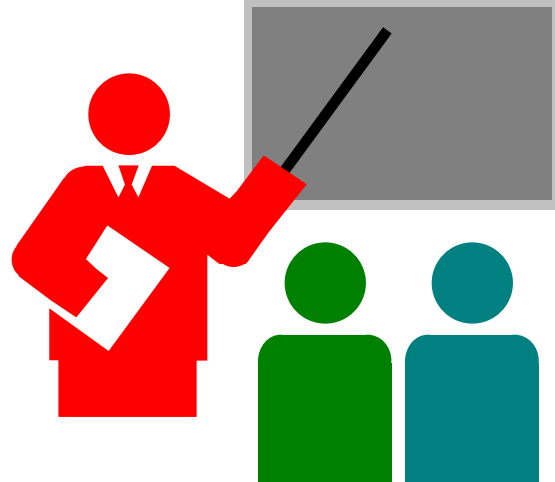


Phase-modulated wave



Frequency-modulated wave

Summary



- ❑ **Coding**: Higher data rate, error control, clock synchronization, line state indication, control signal
- ❑ **D-to-D**: RZ, NRZ-L, NRZI, Manchester, Bipolar, Biphasic
- ❑ **D-to-A**: ASK, FSK, PSK, BPSK, QPSK, OQPSK, QAM
- ❑ **A-to-D**: PCM, Delta Modulation, Sampling theorem
- ❑ **A-to-A**: Amplitude, angle, frequency, phase modulation

Reading Assignment

- Read Chapter 5 of Stallings 7th edition.

Homework

- Submit answers to 5.10 (Bipolar violations) from Stallings 7th edition.