



# Visualization of Tomorrow

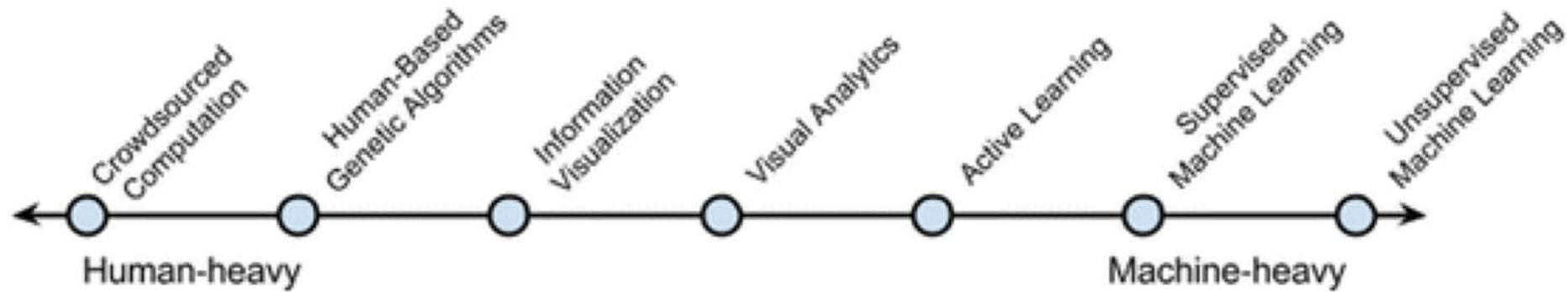
Alvitta Ottley

*Washington University in St. Louis*

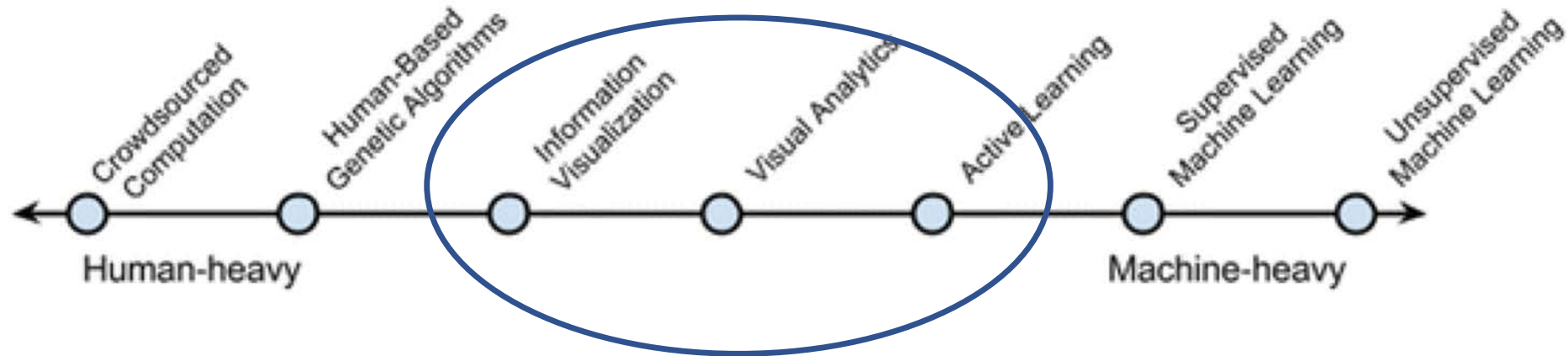
What does  
visualization  
mean to you?



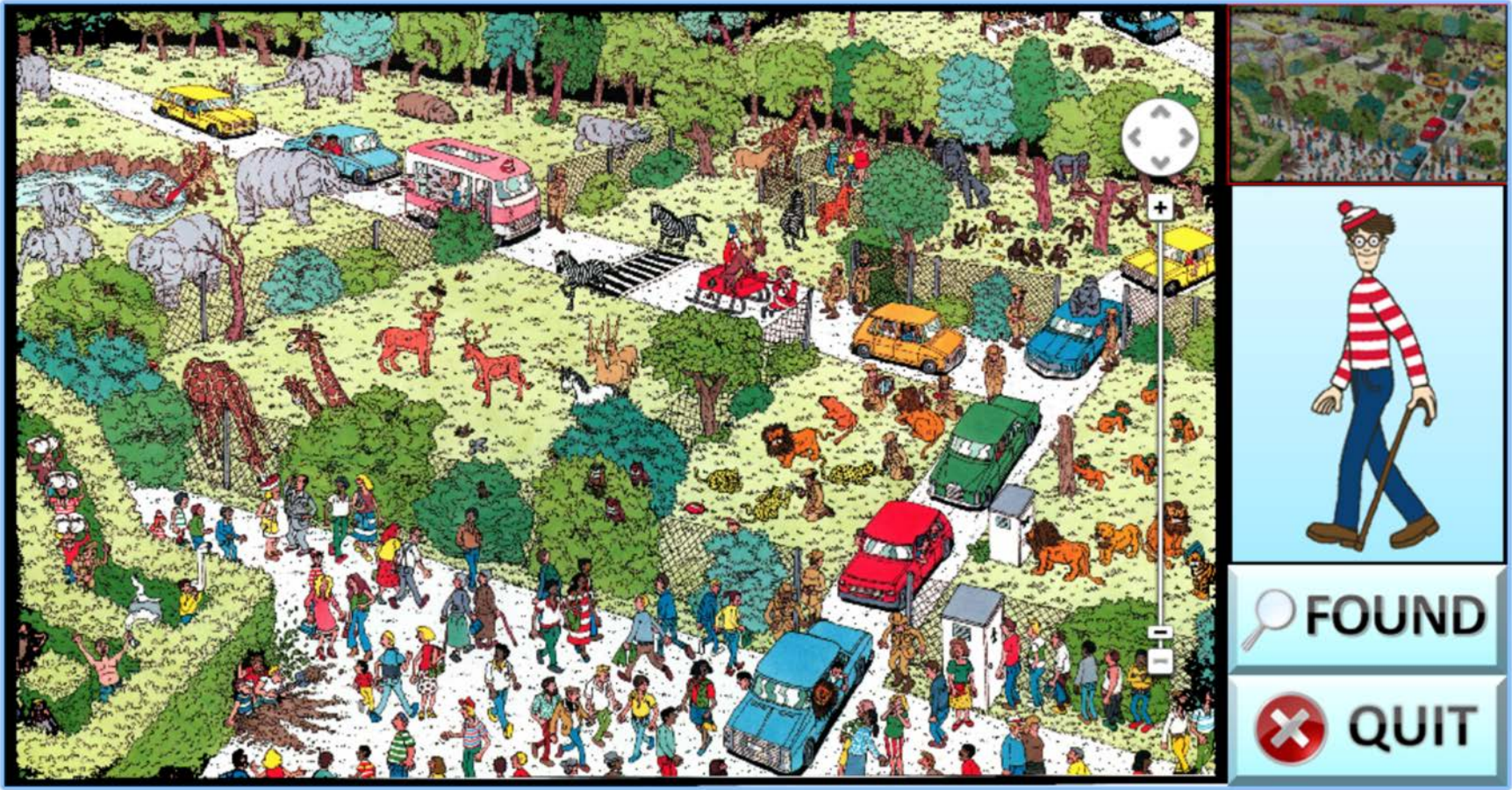
# Human-machine collaboration continuum



# Human-machine collaboration continuum



<https://classes.engineering.wustl.edu/cse557/waldo>



What are the  
possibilities for  
tomorrow?

The machine  
must know  
what you are  
trying to do



Research questions:

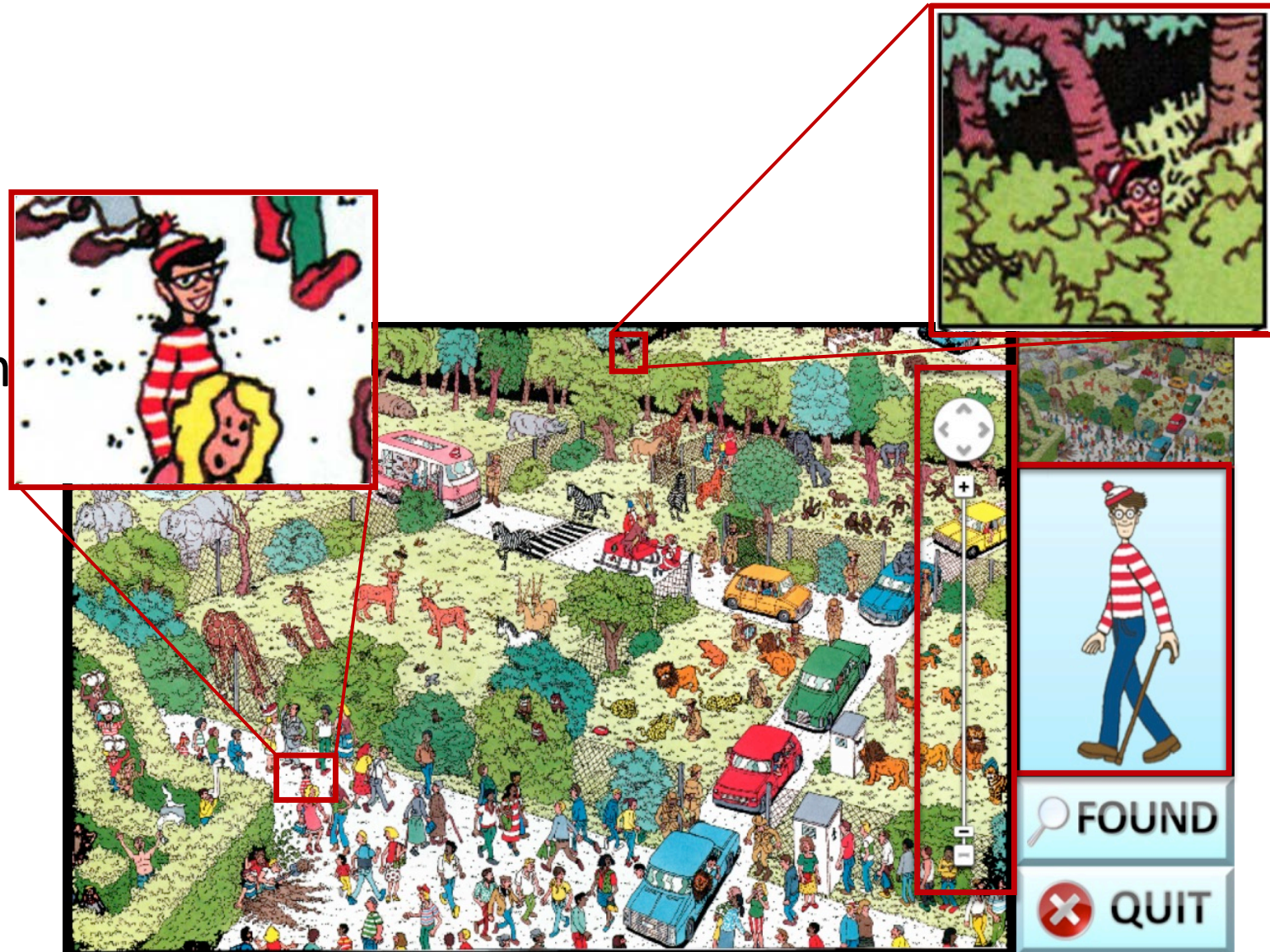
What can we infer through  
observing interactions?

# Finding Waldo

7 control buttons:

Up, Down, Left, Right, Zoom In, Zoom Out, Found

We logged interactions as users search for Waldo



*Finding Waldo: Learning about users from their interactions.*

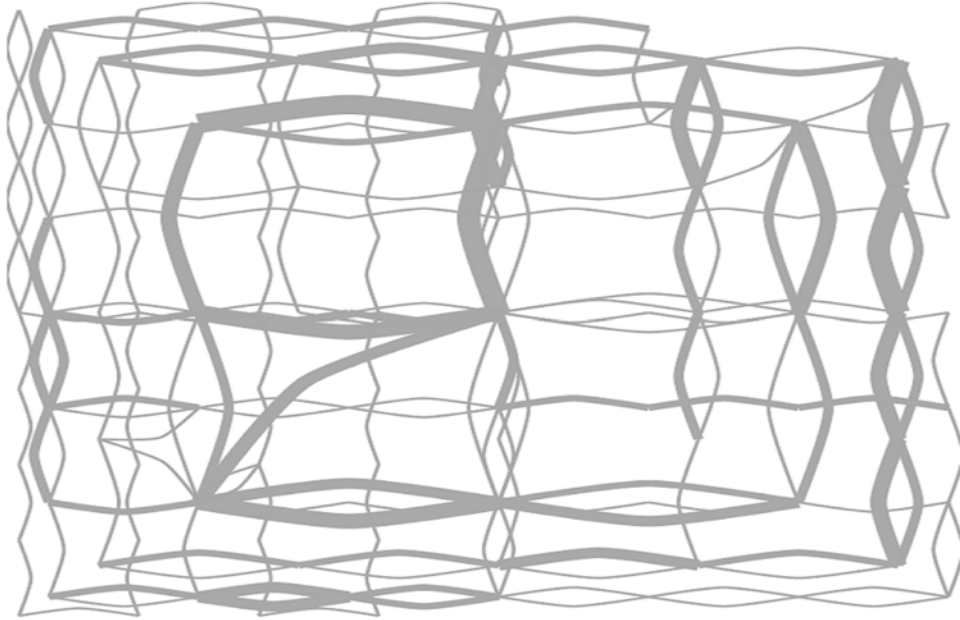
E. Brown, **A. Ottley**, J. Zhao, Q. Lin, R. Souvenir, A. Endert, and R. Chang, VAST 2015.

# Experiment Design

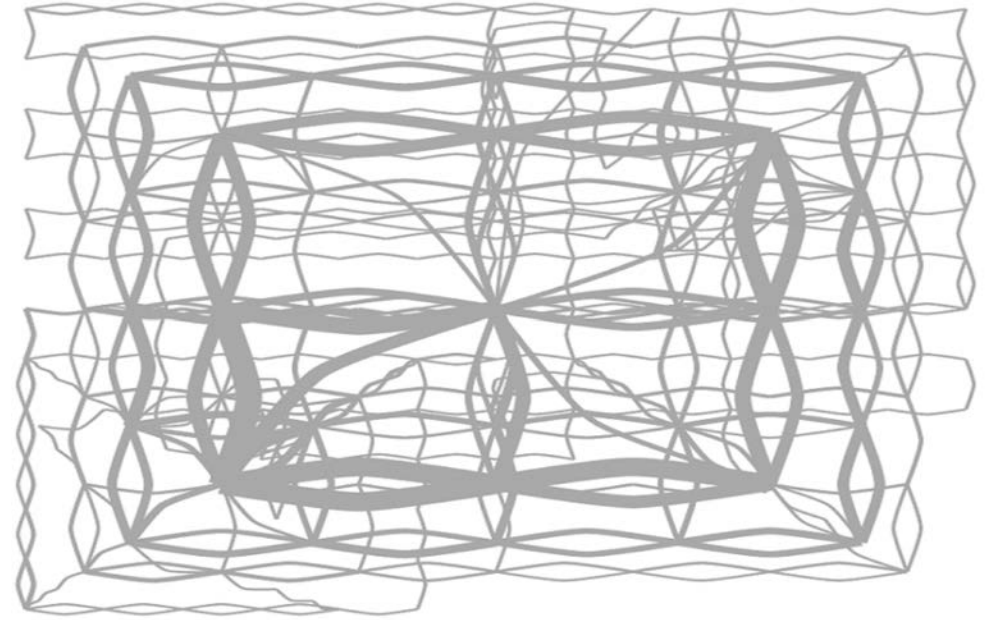
- 90 online participants
- Mean completion time was 469.5 seconds (stdev = 351.9)
- We captured:
  - Mouse clicks and mouse moves
  - Collected personality data



# Visualizing Interactions



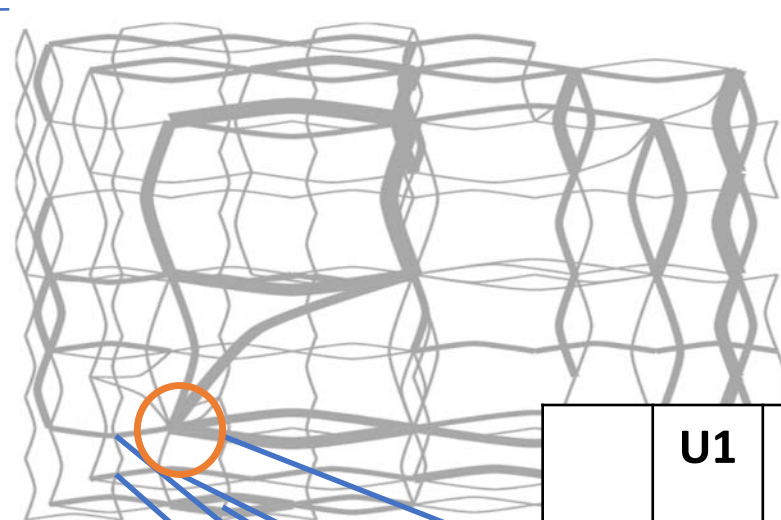
Quick completion time



Slow completion time

F,1,0,0,852,401,0,380826  
C,1,0,0,234,494,0,382768  
C,1,0,0,409,286,0,384276  
C,1,0,0,88,120,0,400513  
C,1,0,0,199,486,0,411208  
C,1,0,0,595,183,0,444478  
F,1,0,0,860,406,0,468280  
C,1,0,0,652,288,0,469906  
C,1,0,0,500,323,0,473823  
F,1,0,0,876,398,0,497403  
C,1,0,0,98,237,0,503475

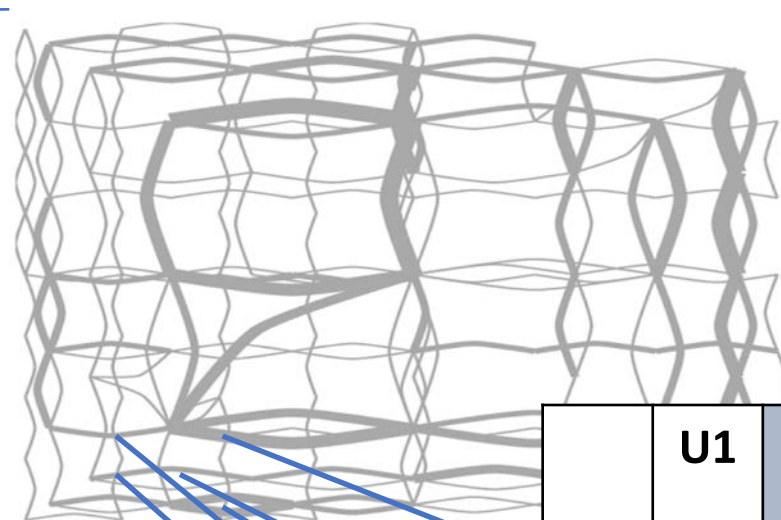
State space



	U1	U2	U3	
	1	0	1	
	2	0	0	
	1	1	1	
	0	0	0	...
	1	5	1	
	1	0	0	
	...			

F,1,0,0,852,401,0,380826  
C,1,0,0,234,494,0,382768  
C,1,0,0,409,286,0,384276  
C,1,0,0,88,120,0,400513  
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State space



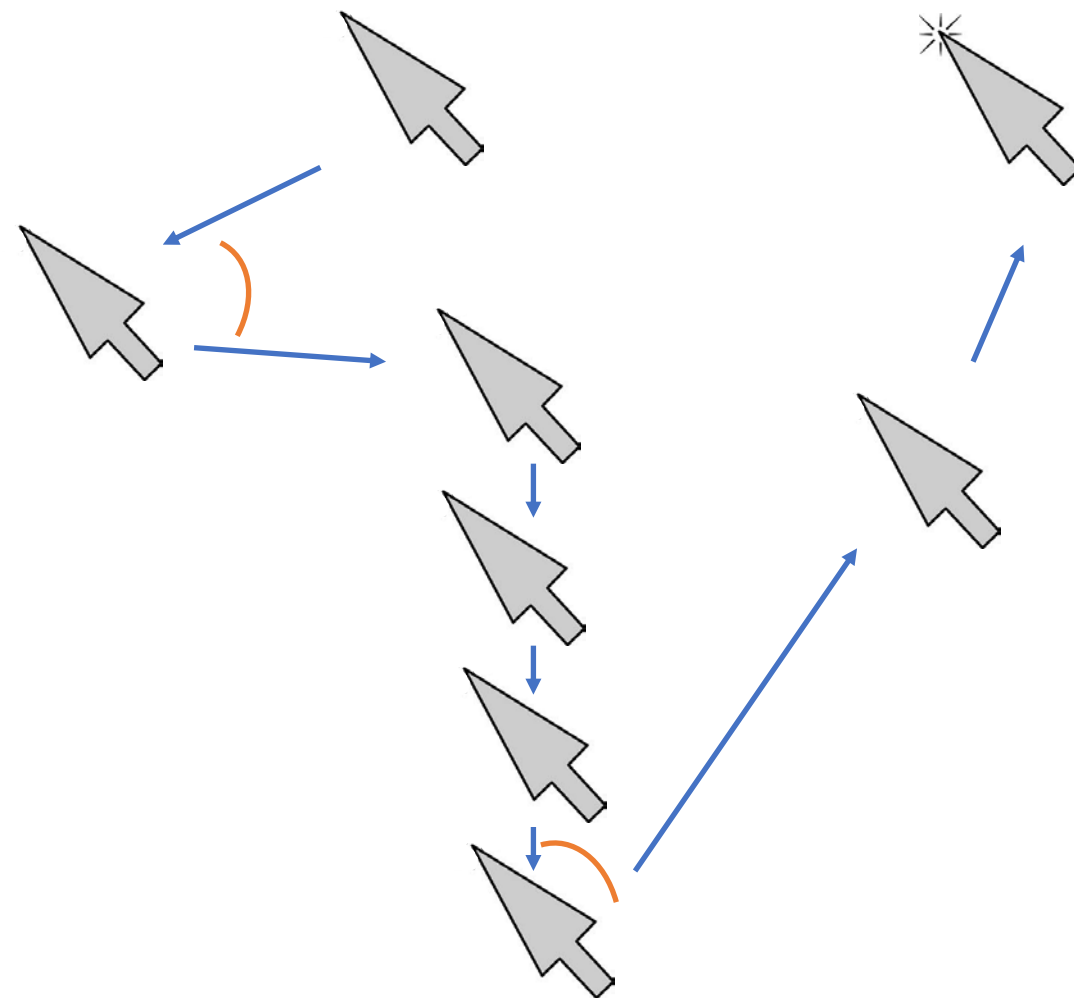
	U1	U2	U3	
	1	0	1	
	2	0	0	
	1	1	1	
	0	0	0	...
	1	5	1	
	1	0	0	
		...		

F,1,0,0,852,401,0,380826  
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C,1,0,0,500,323,0,473823  
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State space

Mouse event





F,1,0,0,852,401,0,380826  
 C,1,0,0,234,494,0,382768  
 C,1,0,0,409,286,0,384276  
 C,1,0,0,88,120,0,400513  
 C,1,0,0,199,486,0,411208  
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 F,1,0,0,876,398,0,497403  
 C,1,0,0,98,237,0,503475

State space  
 Mouse event  
 Sequences

U1: LIIDLURRUUIRRDD...  
 U2: URDIIDDLLOLO...  
 U3: LLIIDDORRRURIII...

	U 1	U2	U3
LI	1	0	2
LII	1	0	0
IID	3	1	1
IDI	0	0	0
DD	1	2	1
IRR	1	0	0

L = Left, R = Right, U = Up, D = Down,  
 I = Zoom In, O = Zoom Out

F,1,0,0,852,401,0,380826  
 C,1,0,0,234,494,0,382768  
 C,1,0,0,409,286,0,384276  
 C,1,0,0,88,120,0,400513  
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 C,1,0,0,500,323,0,473823  
 F,1,0,0,876,398,0,497403  
 C,1,0,0,98,237,0,503475

State space

Mouse event

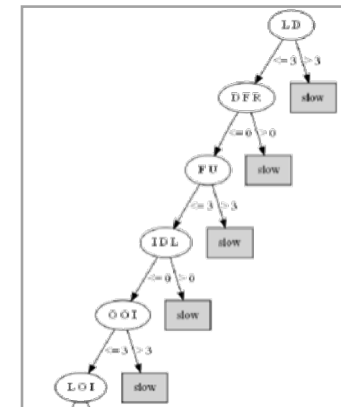
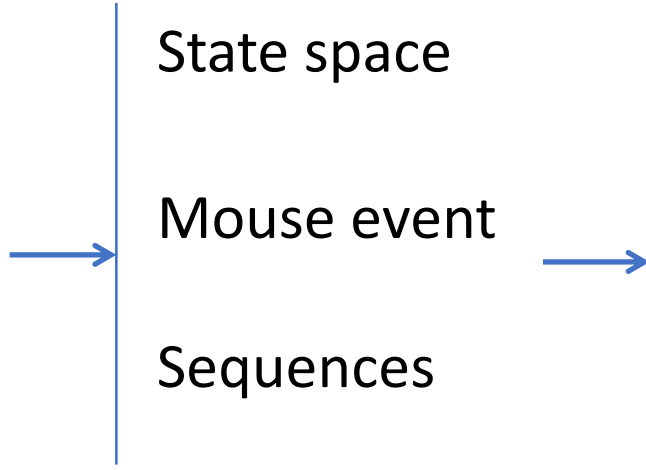
Sequences

U1: LIIDLURRUUIRRDD...  
 U2: URDIIDDLLOLO...  
 U3: LLIIDDORRRURIII...  
 ───────────  
 †

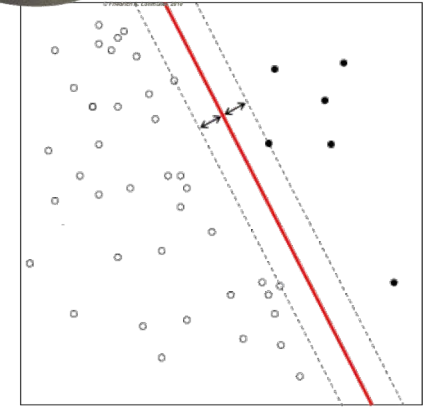
	U	U2	U3	
	1			
LI	1	0	2	
LII	1	0	0	
IID	3	1	1	
IDI	0	0	0	...
DD	1	2	1	
IRR	1	0	0	
		...		

L = Left, R = Right, U = Up, D = Down,  
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F,1,0,0,852,401,0,380826  
C,1,0,0,234,494,0,382768  
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C,1,0,0,500,323,0,473823  
F,1,0,0,876,398,0,497403  
C,1,0,0,98,237,0,503475



decision tree



SVM

# Performance Prediction Accuracy

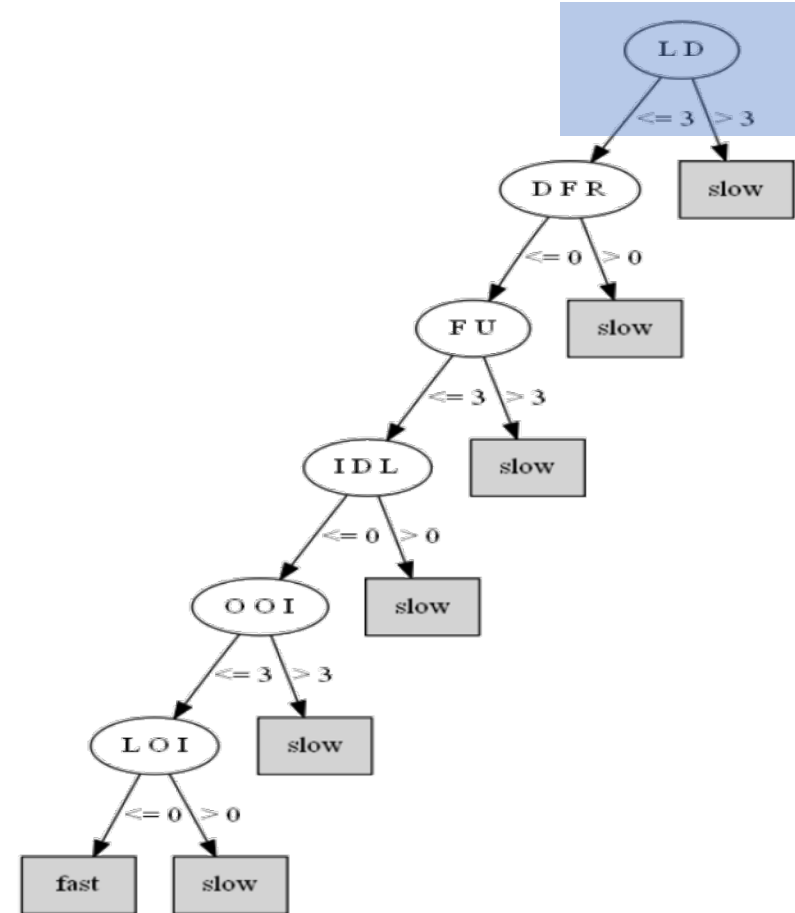
state space (SVM)	83 %
mouse events (SVM)	79 %
sequences (decision tree)	79 %

# Interpreting Decision Trees

Decision tree on sequences encoding

Left, Down too much => slow

Waldo is in upper right



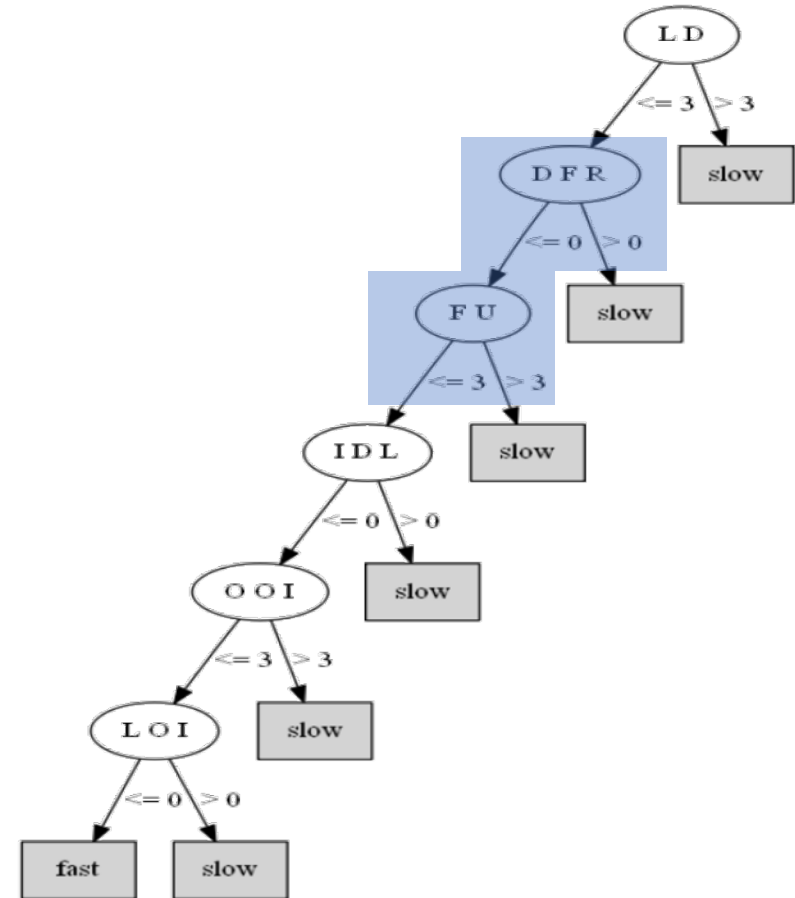
# Interpreting Decision Trees

Decision tree on sequences encoding

*Found*, Up and

Down, *Found*, Right => slow

Clicking Found incorrectly



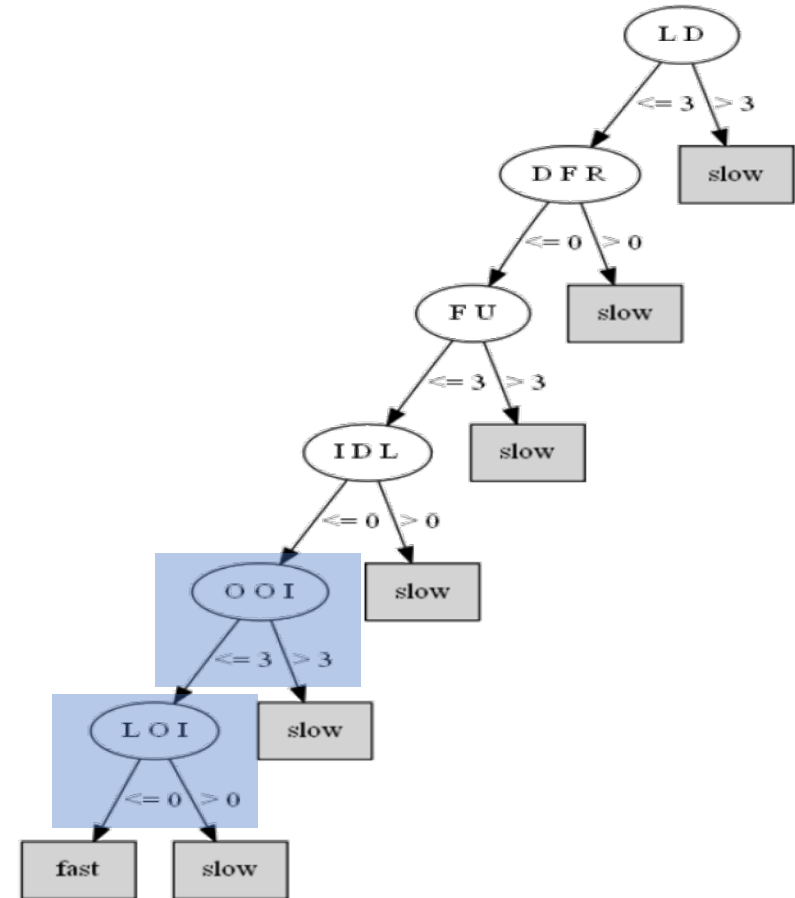
# Interpreting Decision Trees

Decision tree on sequences encoding

Out, Out, In and

Left, Out, In => slow

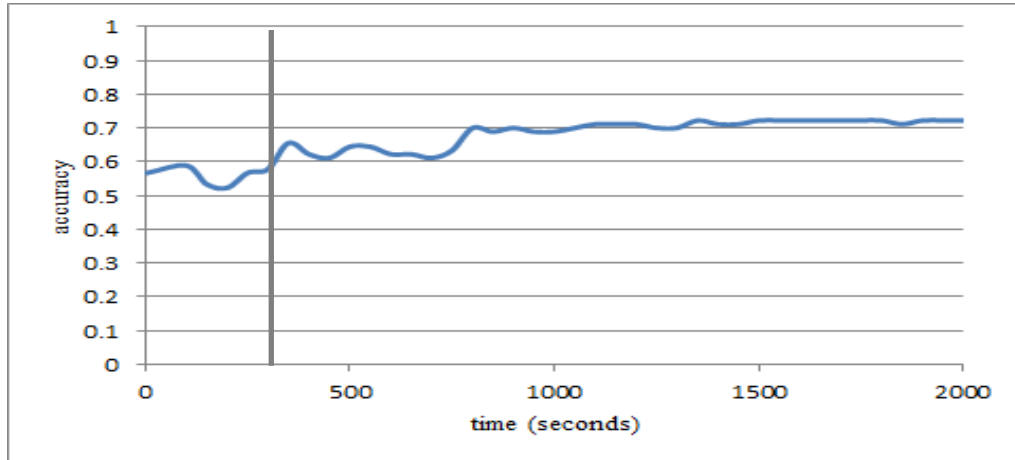
Out then in, null move?



Can we do this real time?

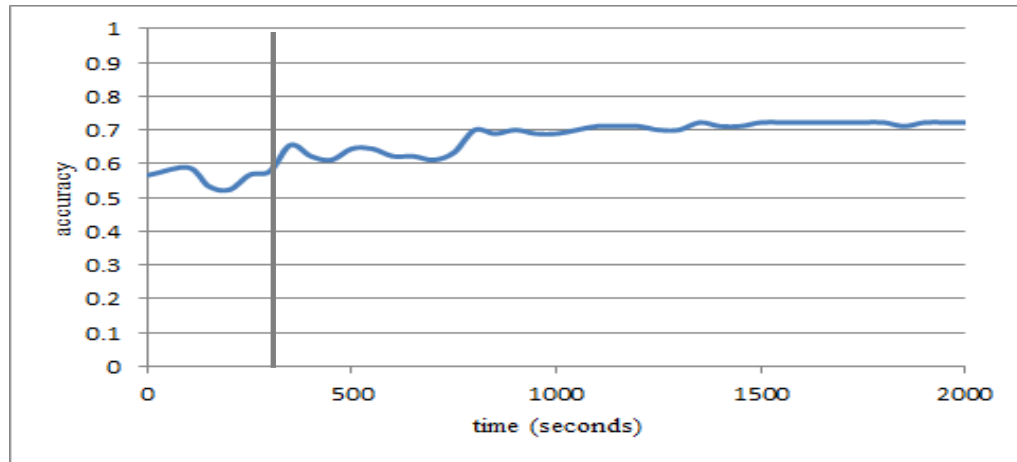


# Can we do this real time?

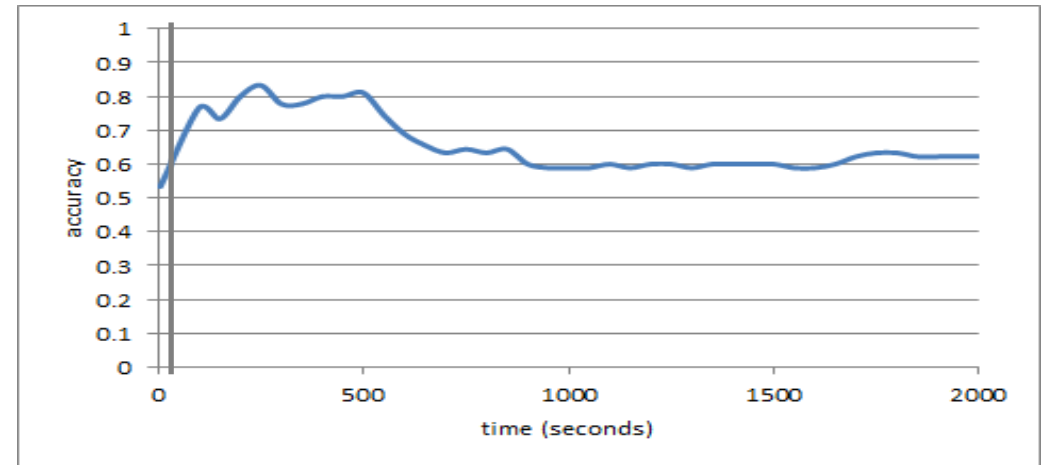


State Space

# Can we do this real time?

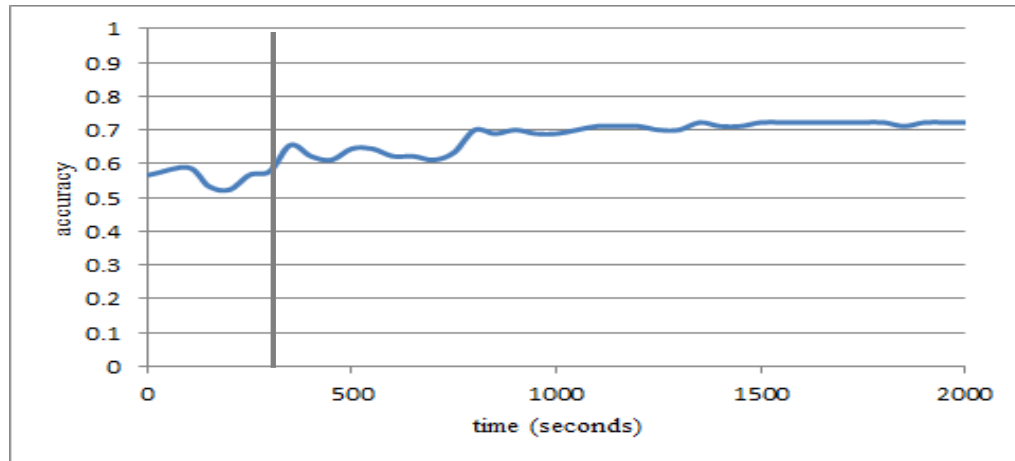


State Space

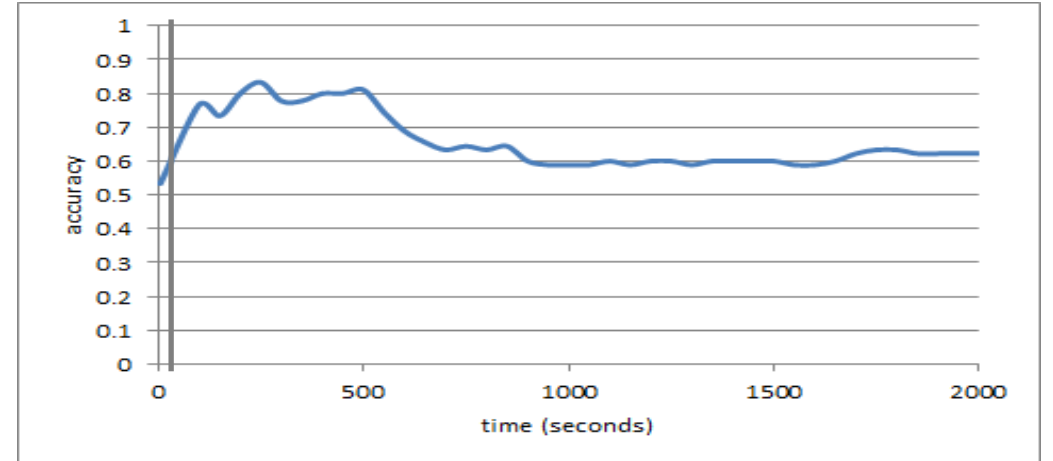


Mouse Events

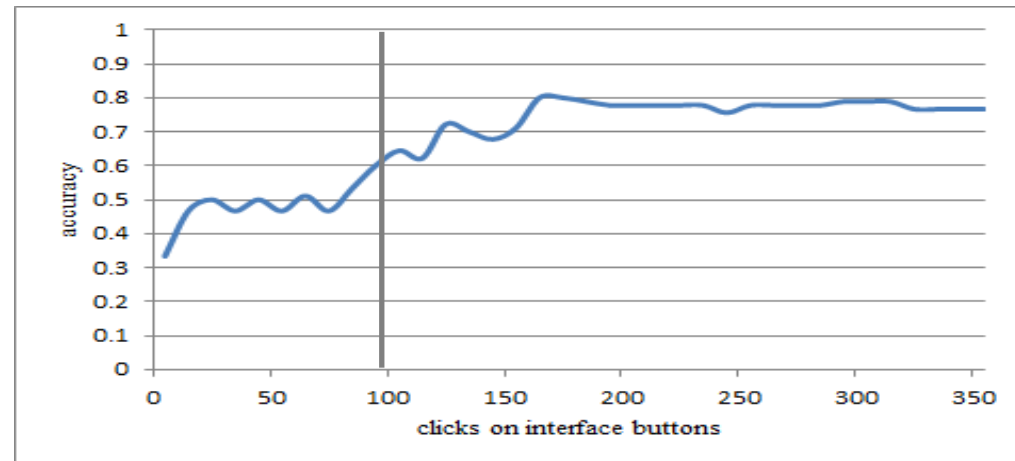
# Can we do this real time?



State Space

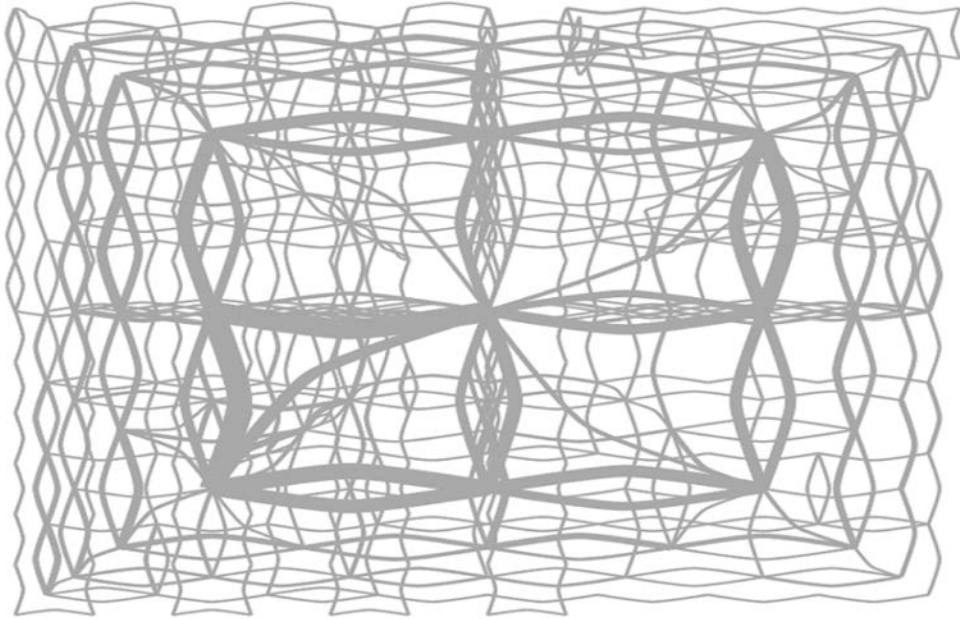


Mouse Events

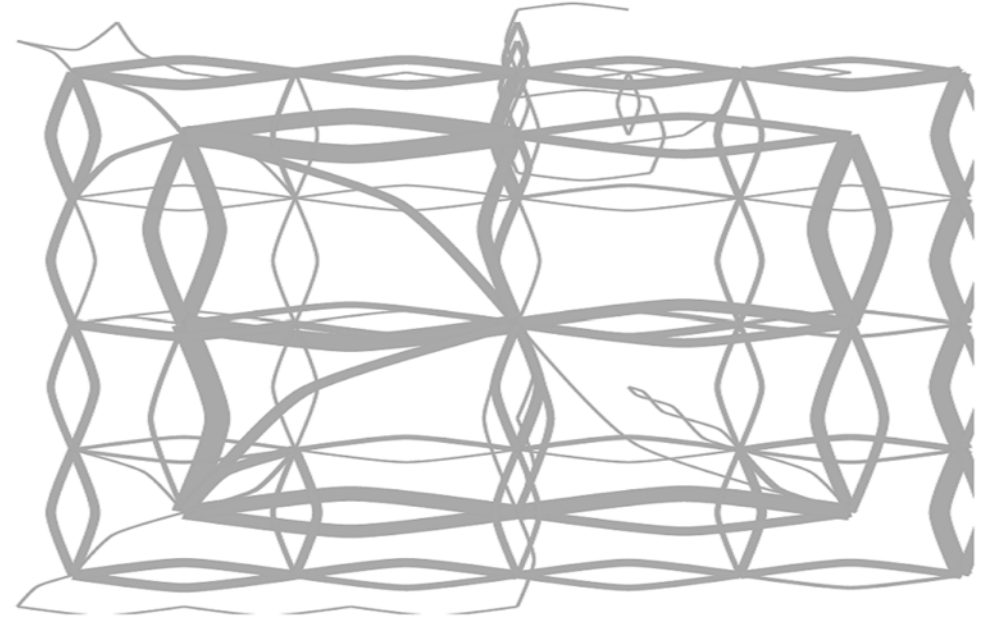


Sequences

# What about individual differences?



External Locus of Control

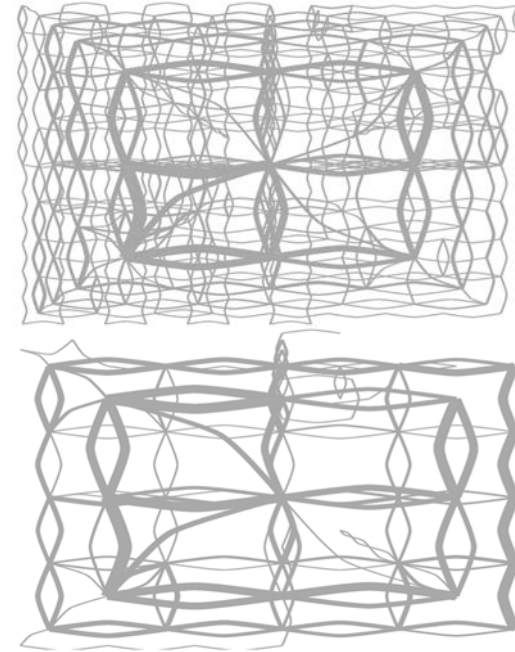


Internal Locus of Control

**We were able to detect Extraversion, Neuroticism, and Locus of Control each at ~60% accuracy.**

# Summary

- It is possible to automatically extract information about users from their interacts
  - Performance
  - Individual traits

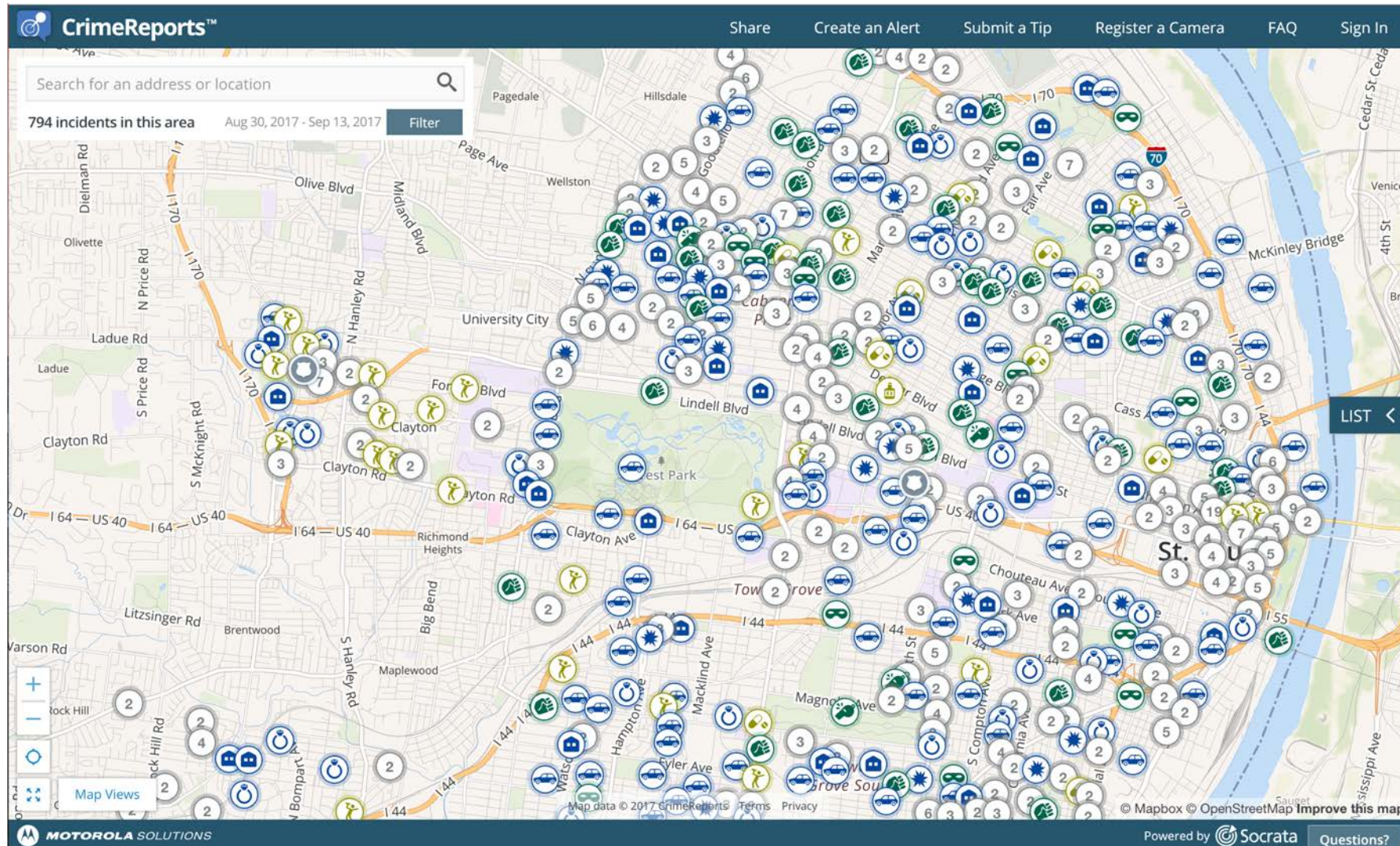


Questions or Comments?

Research questions:

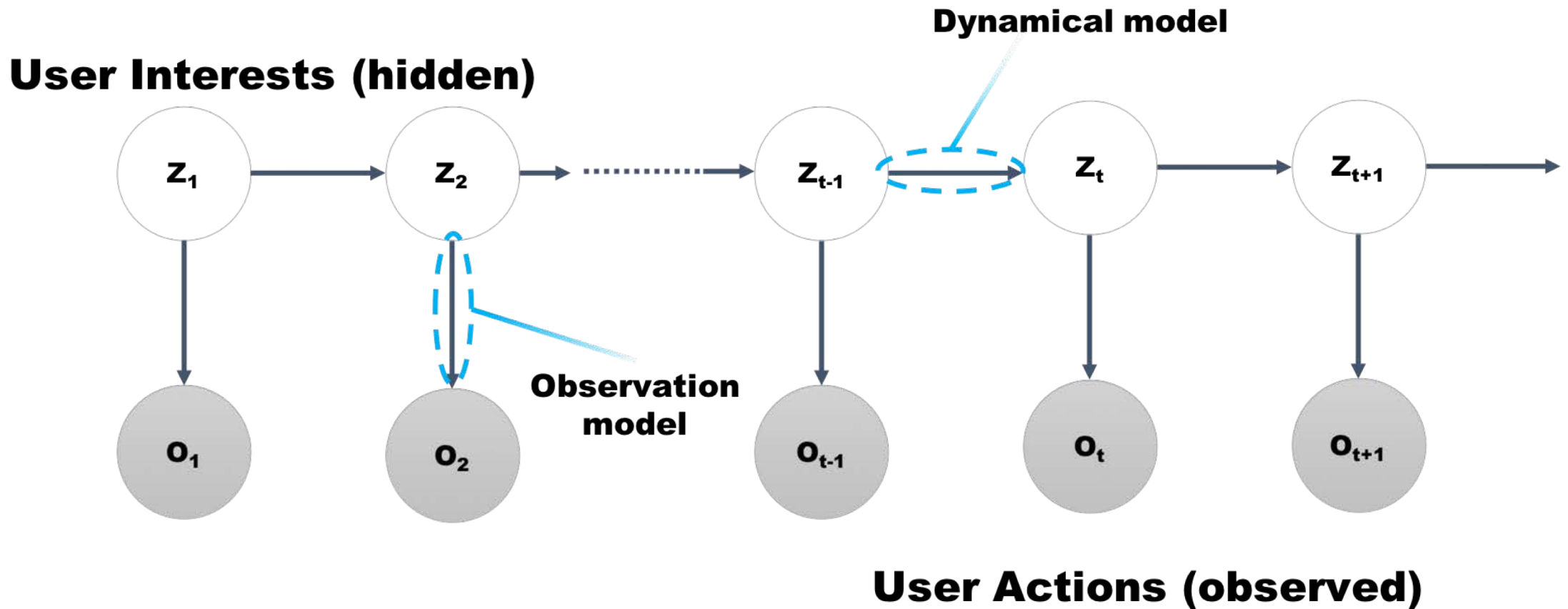
**WHAT:** Can we learn what the analyst is doing?

# Can we predict moves on a crime map?

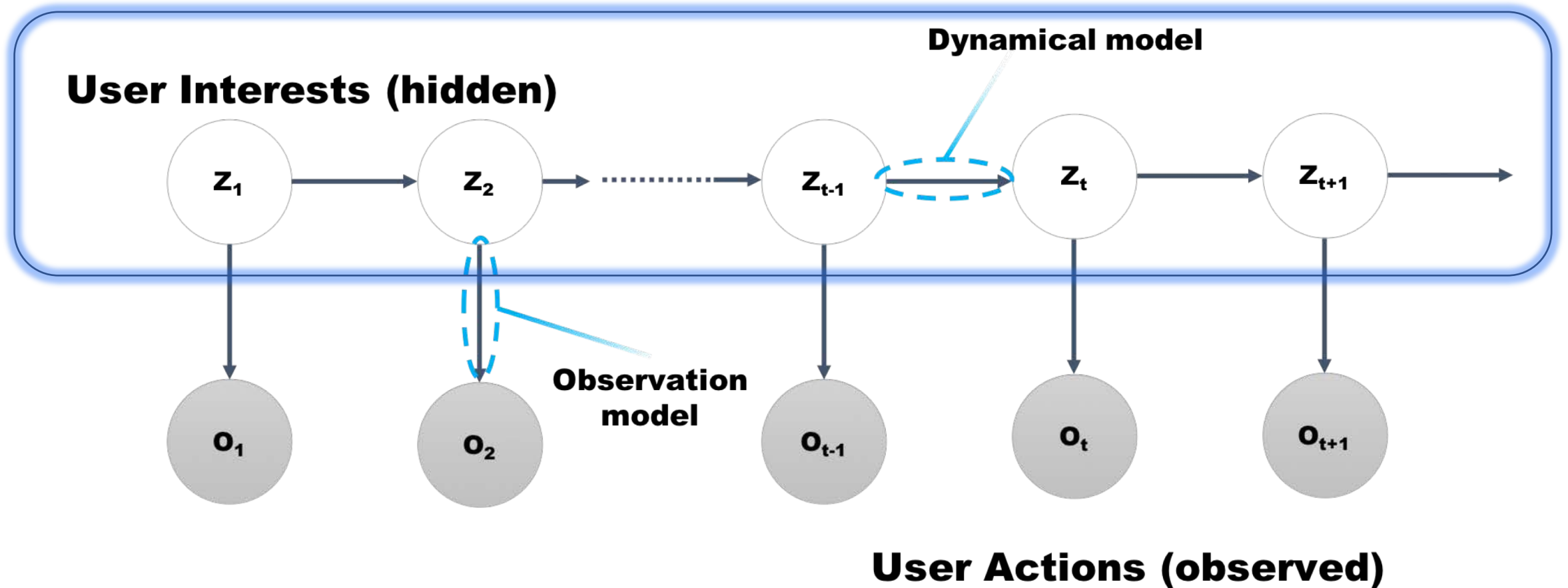




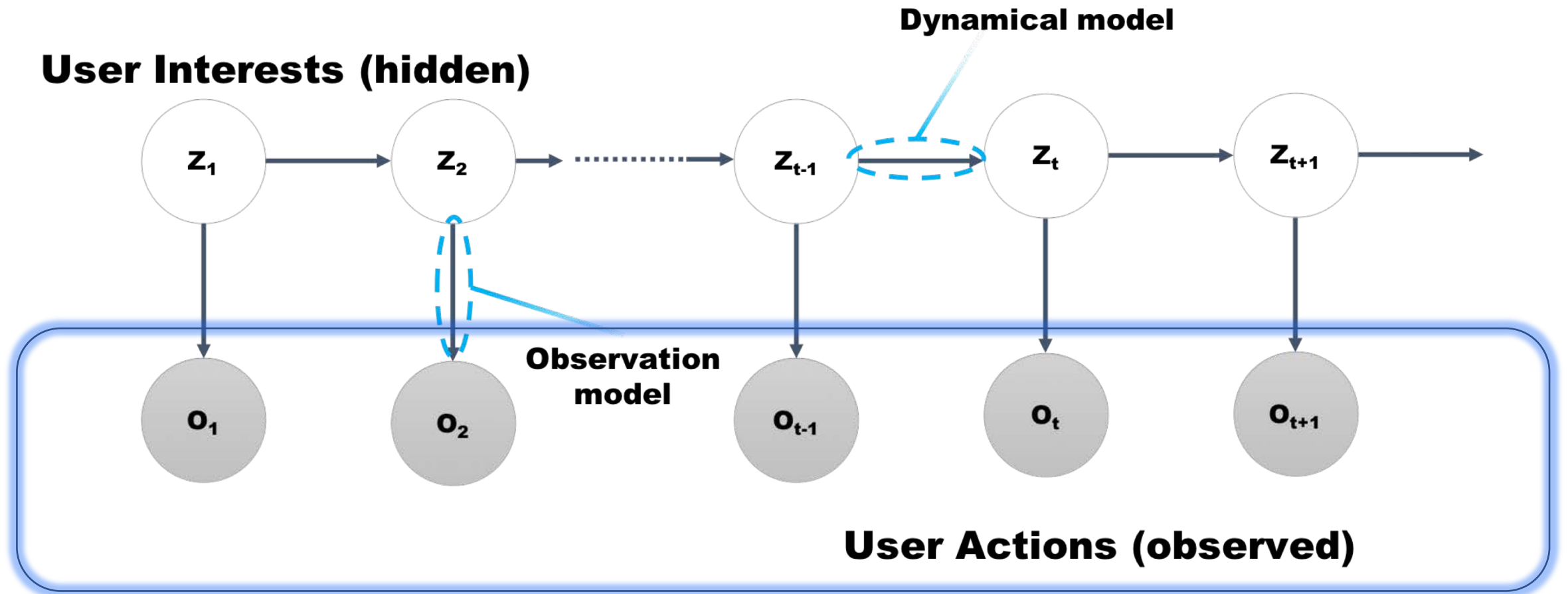
# First: Hidden Markov Models



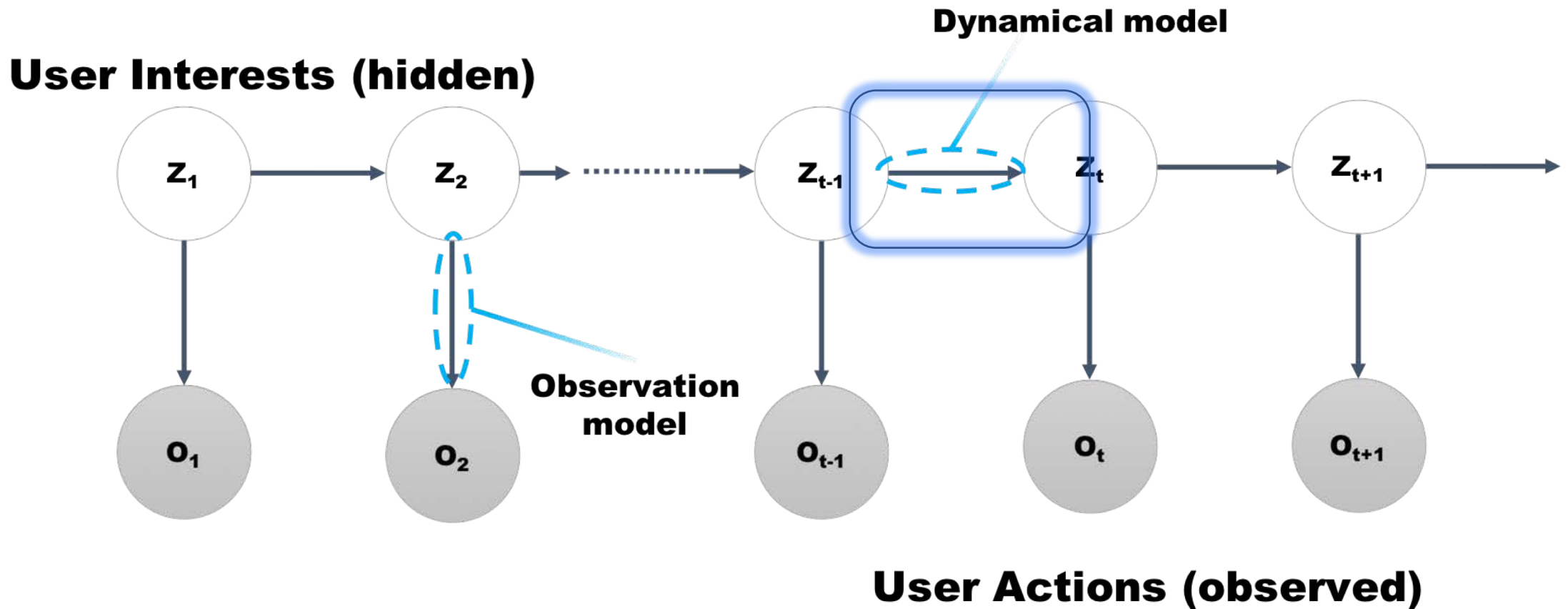
# First: Hidden Markov Models



# First: Hidden Markov Models



# First: Hidden Markov Models





# Example

```
states = ('Rainy', 'Sunny')
```

# Example

```
states = ('Rainy', 'Sunny')
```

```
observations = ('walk', 'shop', 'clean')
```

# Example

```
states = ('Rainy', 'Sunny')
```

```
observations = ('walk', 'shop', 'clean')
```

```
start_probability = {'Rainy': 0.6, 'Sunny': 0.4}
```



# Example

```
states = ('Rainy', 'Sunny')

observations = ('walk', 'shop', 'clean')

start_probability = {'Rainy': 0.6, 'Sunny': 0.4}

transition_probability = {
    'Rainy' : {'Rainy': 0.7, 'Sunny': 0.3},
    'Sunny' : {'Rainy': 0.4, 'Sunny': 0.6},
}
```

# Example

```
states = ('Rainy', 'Sunny')

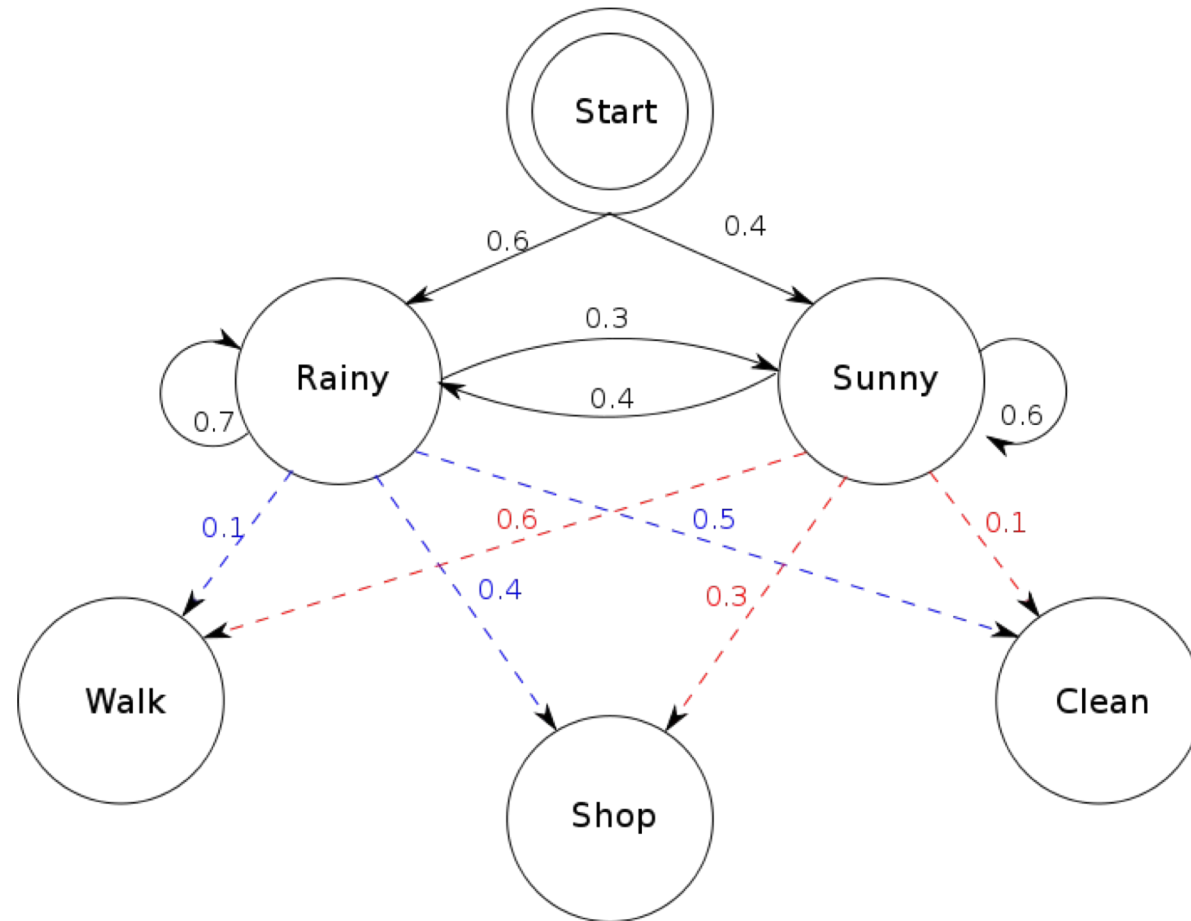
observations = ('walk', 'shop', 'clean')

start_probability = {'Rainy': 0.6, 'Sunny': 0.4}

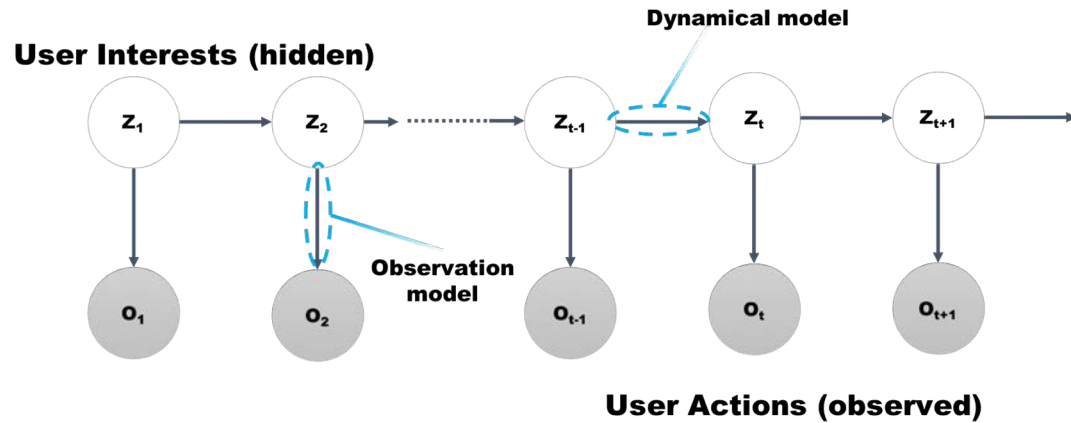
transition_probability = {
    'Rainy' : {'Rainy': 0.7, 'Sunny': 0.3},
    'Sunny' : {'Rainy': 0.4, 'Sunny': 0.6},
}

emission_probability = {
    'Rainy' : {'walk': 0.1, 'shop': 0.4, 'clean': 0.5},
    'Sunny' : {'walk': 0.6, 'shop': 0.3, 'clean': 0.1},
}
```

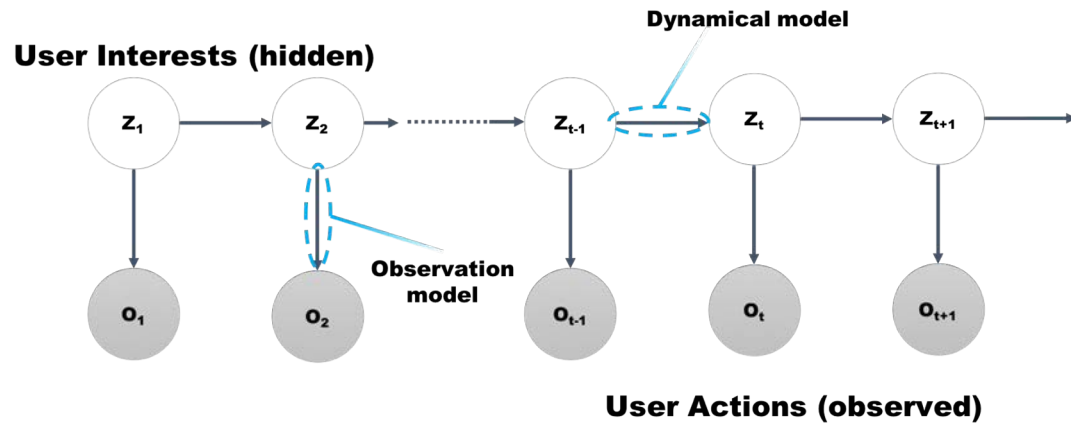
# Example



# Apply hidden Markov model to visualizations



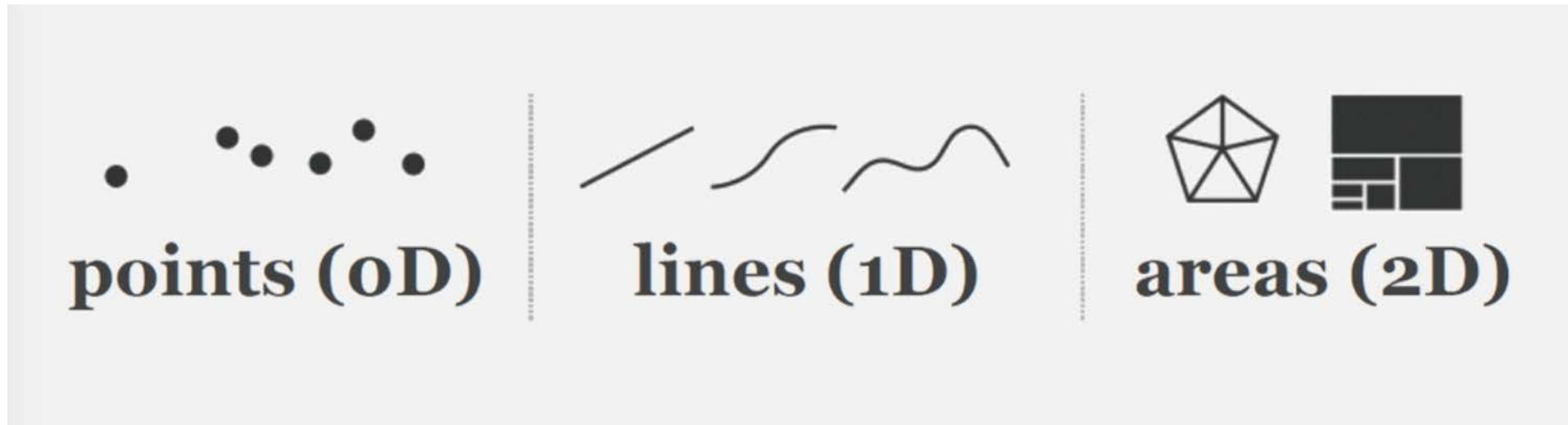
# Apply hidden Markov model to visualizations



1. Define hidden states
2. Define observations
3. Define Dynamical model
4. Define Observational model

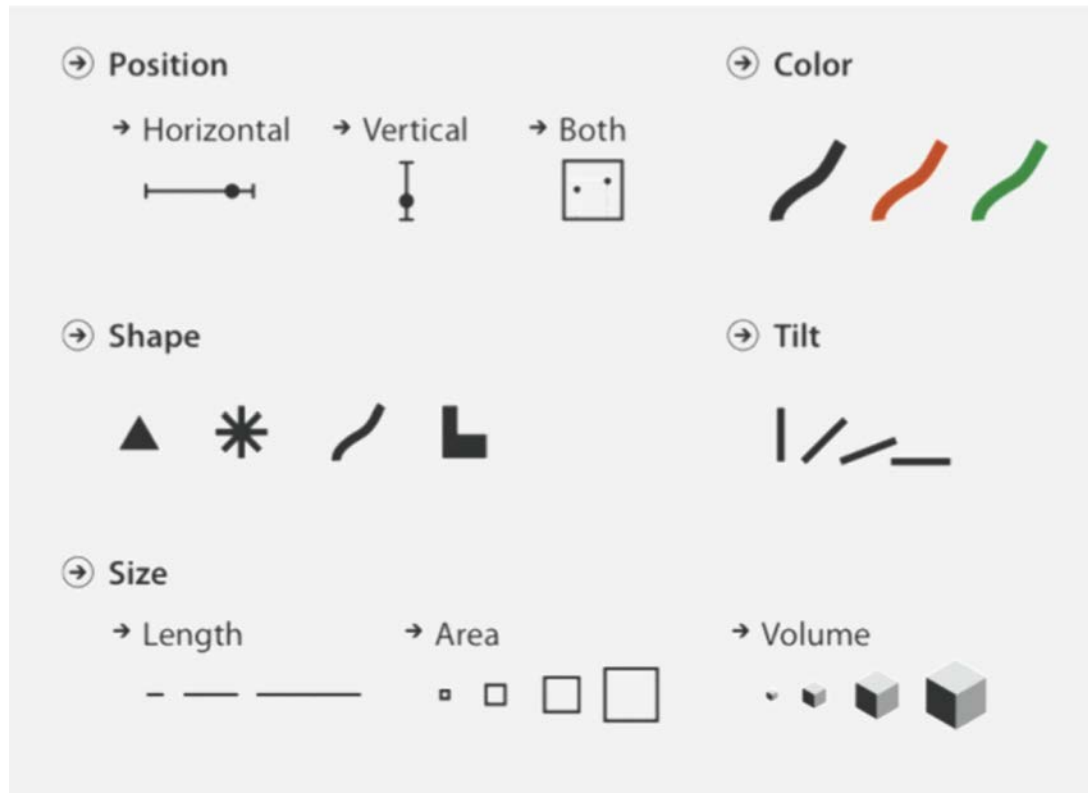
# Visual Mark

- Graphical element in an image

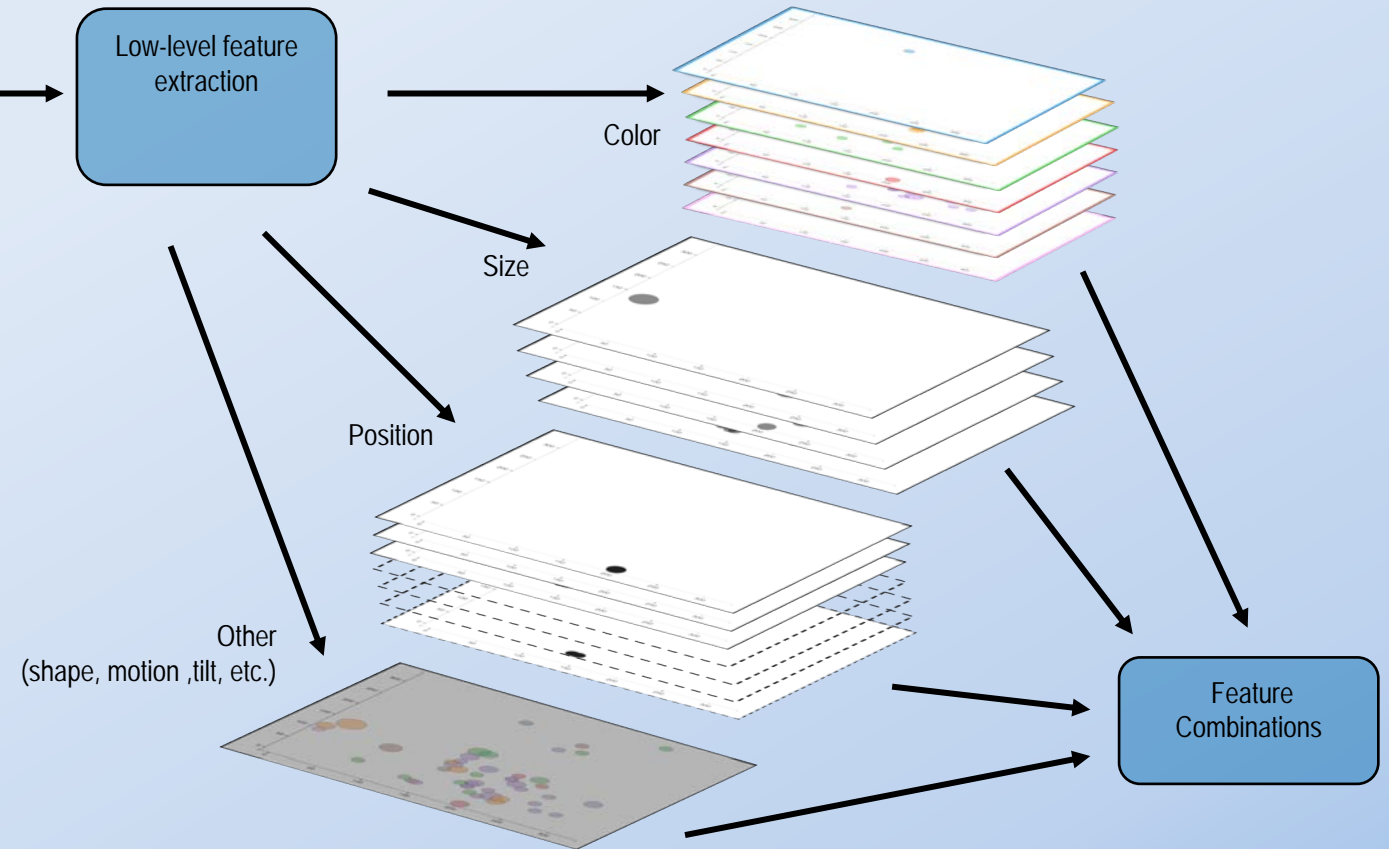
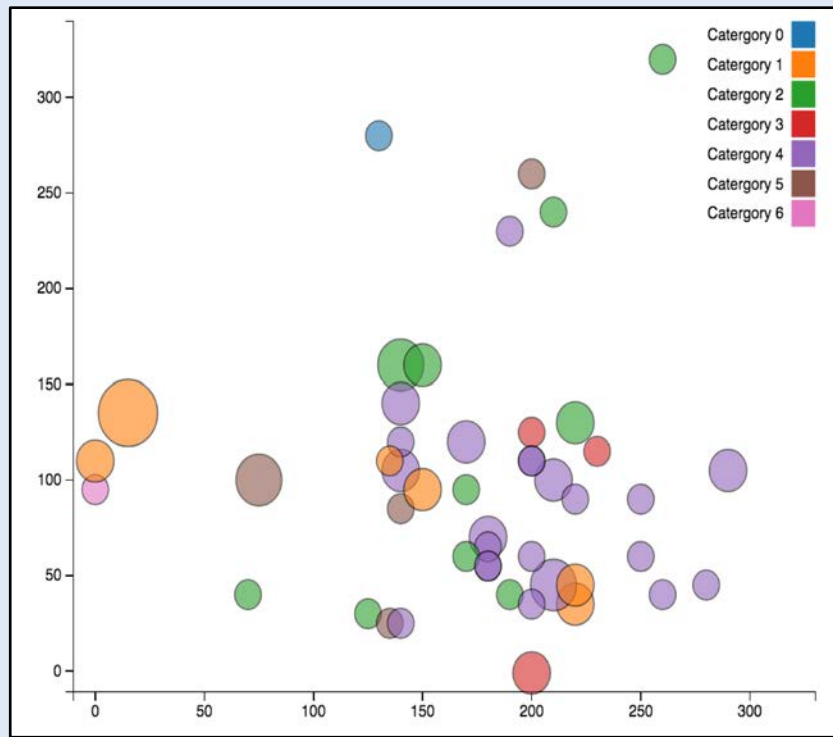


# Visual Channel

- Parameters that control the appearance of marks

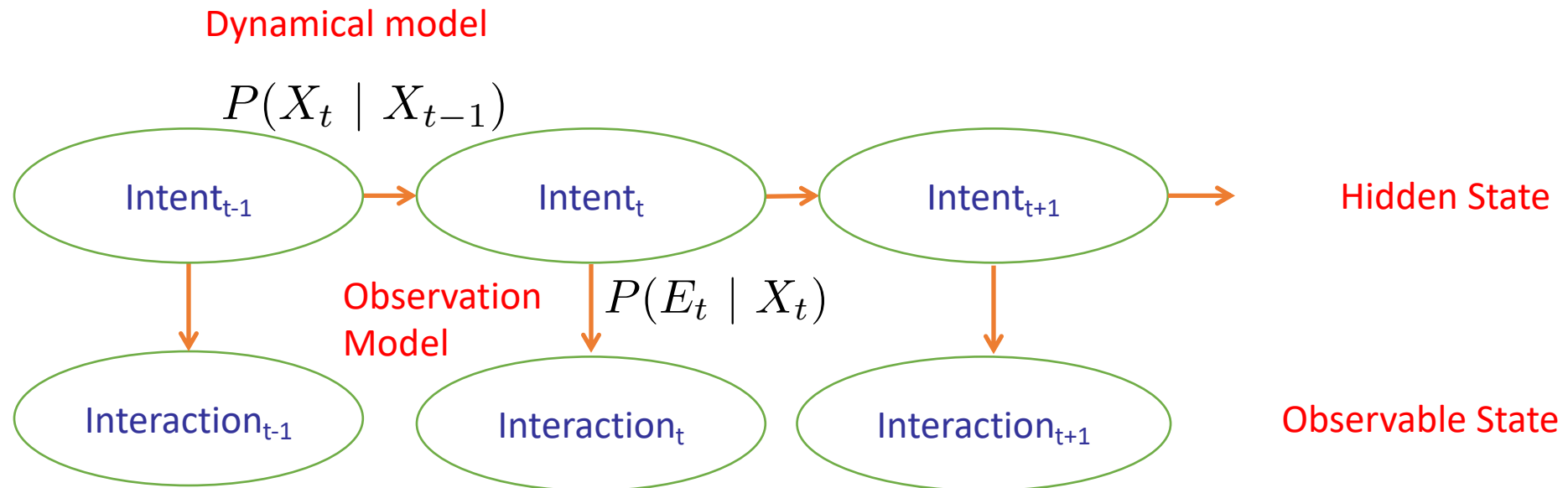


# Decomposing the visualization

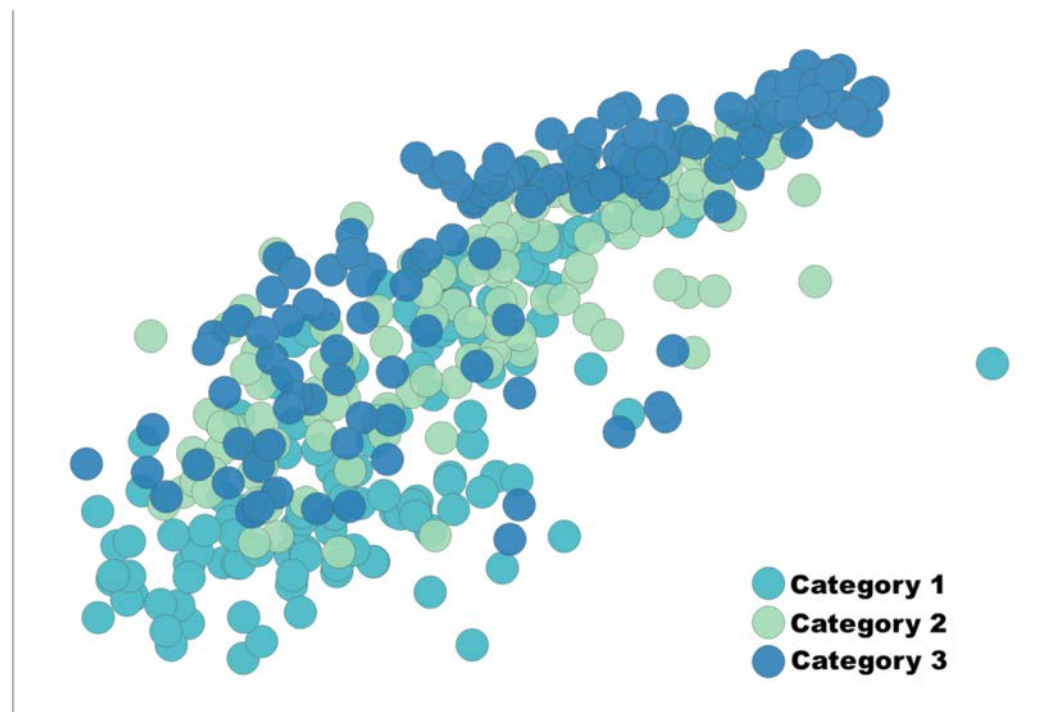




# Constructing Probabilistic model

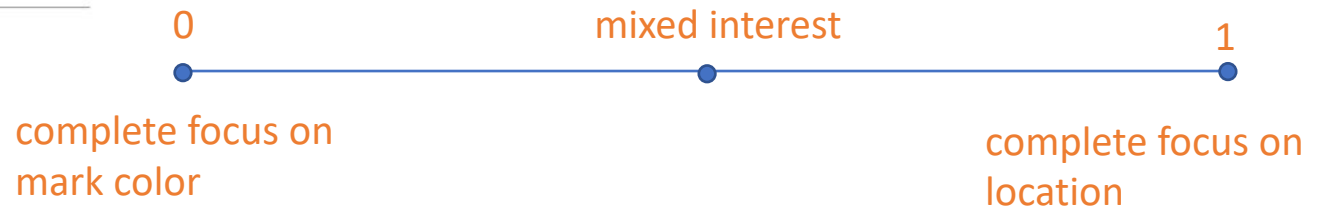
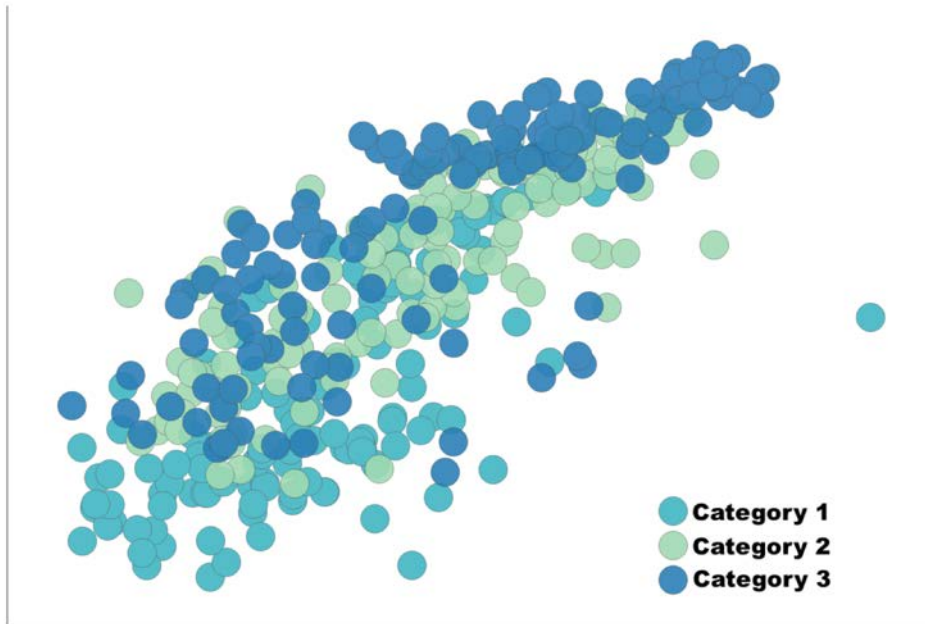


# Example

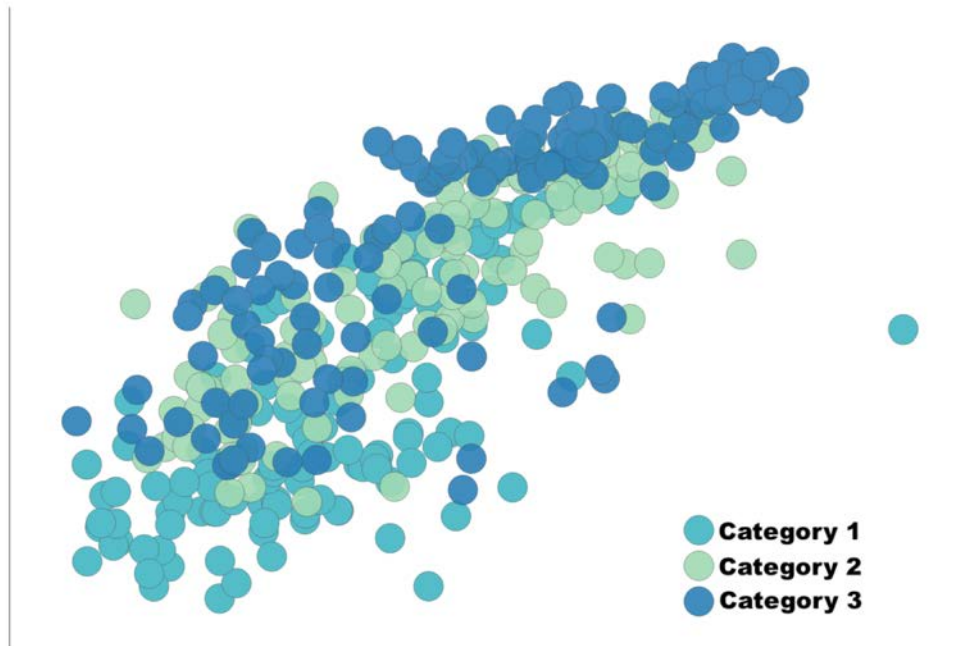


# Defining Hidden States

- $M$ : the mark space
- $I$ : hidden intent space
  - Subspace of  $M$
- *In this case, hidden space is a vector*
  - 1) location  $(x,y)$
  - 2) mark color  $k$
  - 3) trade of parameter  $\pi$
  - 4)  $z = (x,y,z,\pi)$



# Defining Observable States



- $O_t$ : an observation at time t
  - Mouse click, mouse move, eye gaze
  - represent each observable state as a vector specifying the visual attributes of  $o_t$
- *In this case,*
  - *Mouse click*
  - *A vector of  $c = (x, y, k)$*

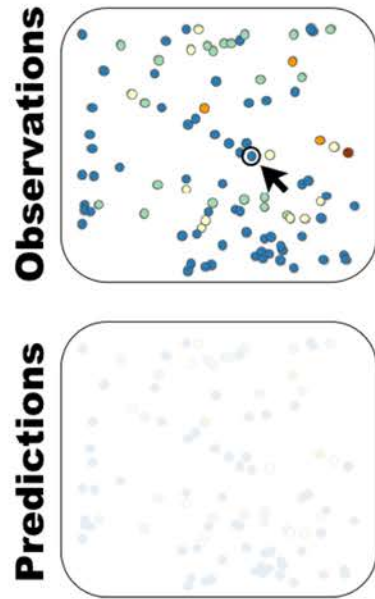
# Particle Filtering

- Robot localization example
- <https://www.youtube.com/watch?v=5nswUcByXLo>

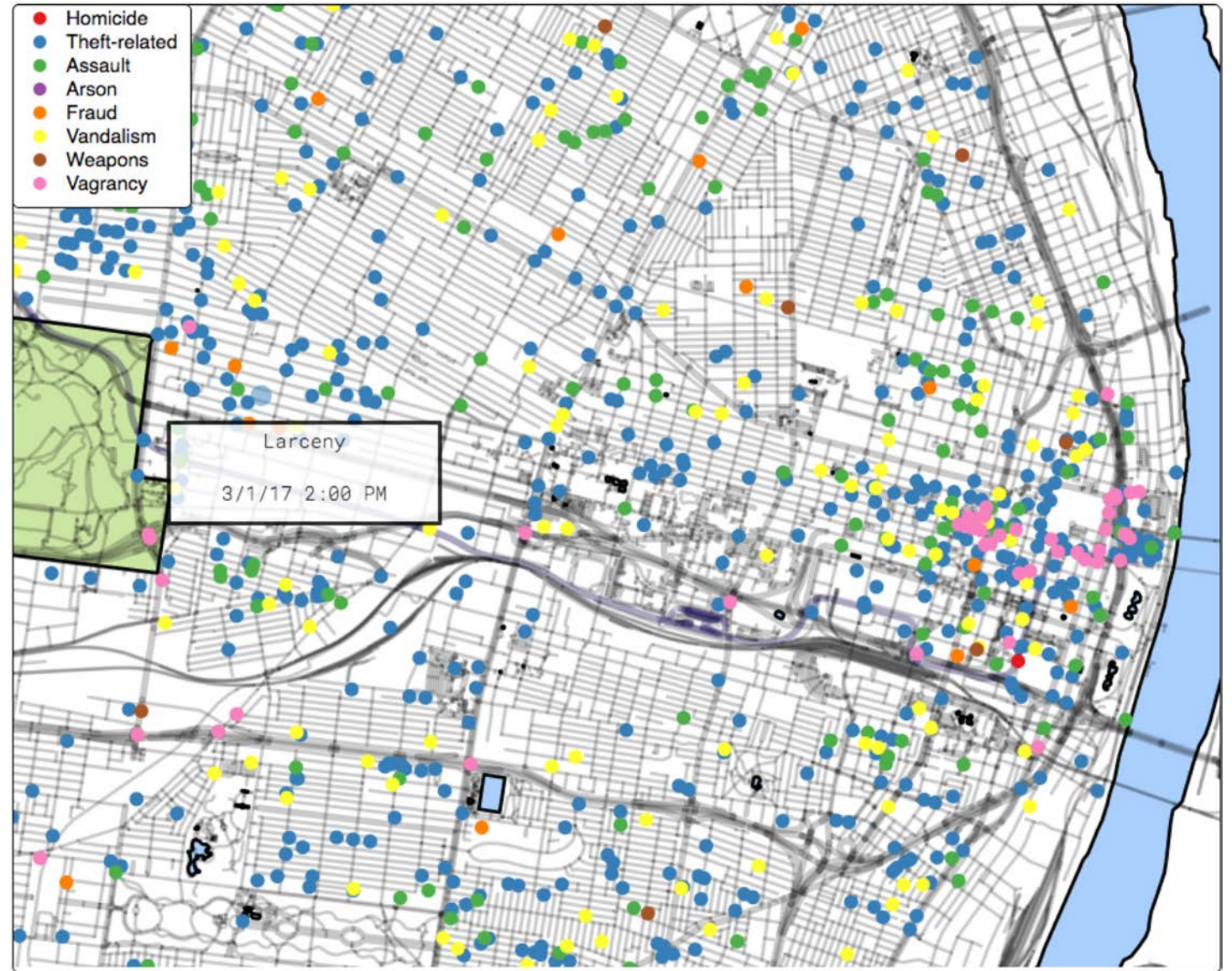
# Predicting movement

$$d^* = \arg \max_{d \in D} \sum_{p \in P} \mathbb{P}(d|p)$$

# Simulation



# Case Study

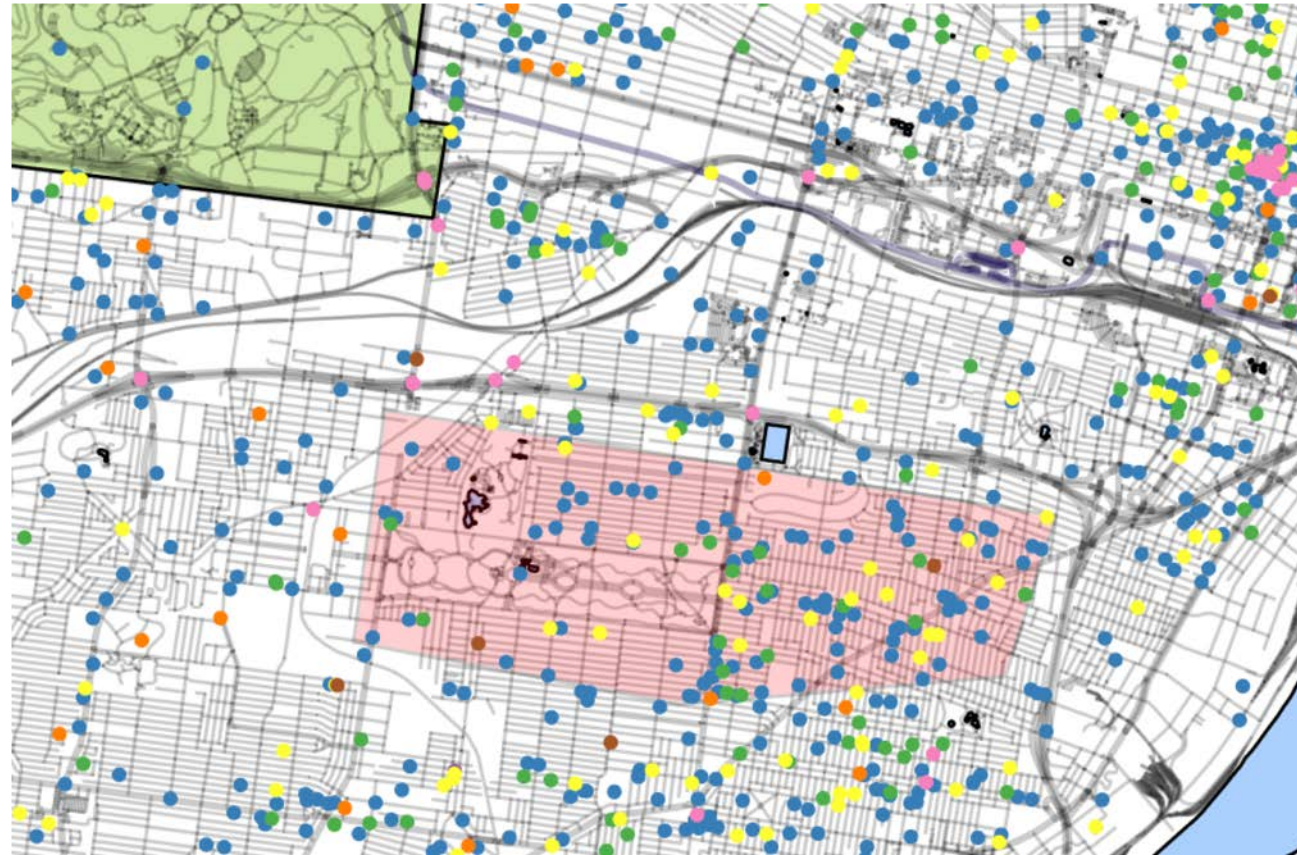




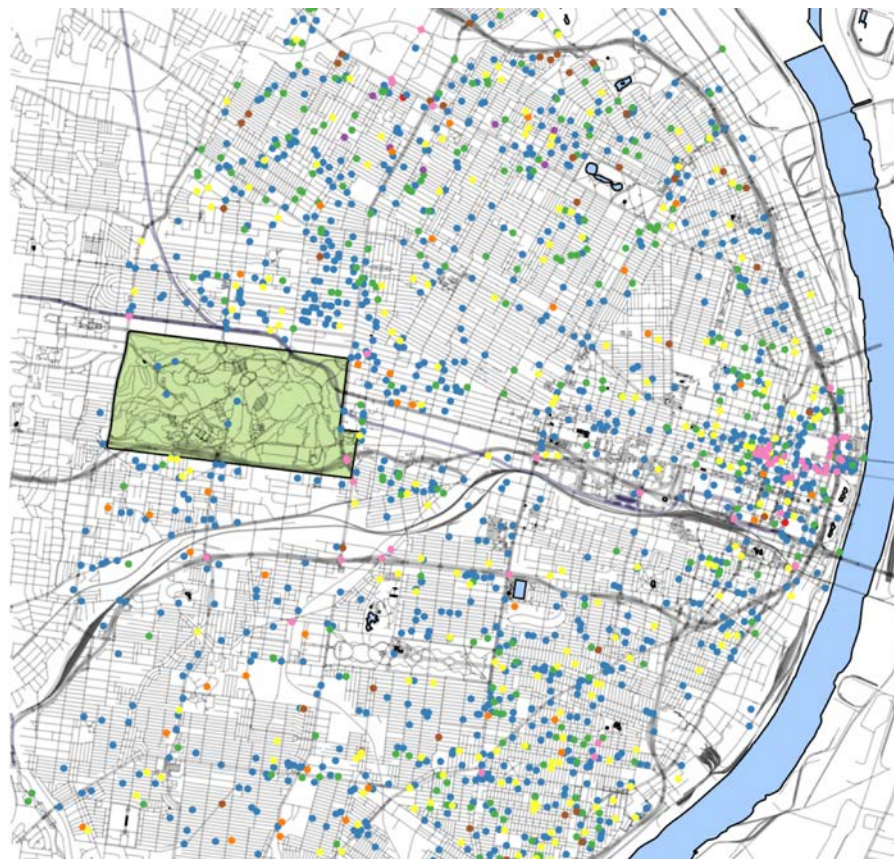
# Geo-Based Task



# Mixed Type



# Type-Based Task



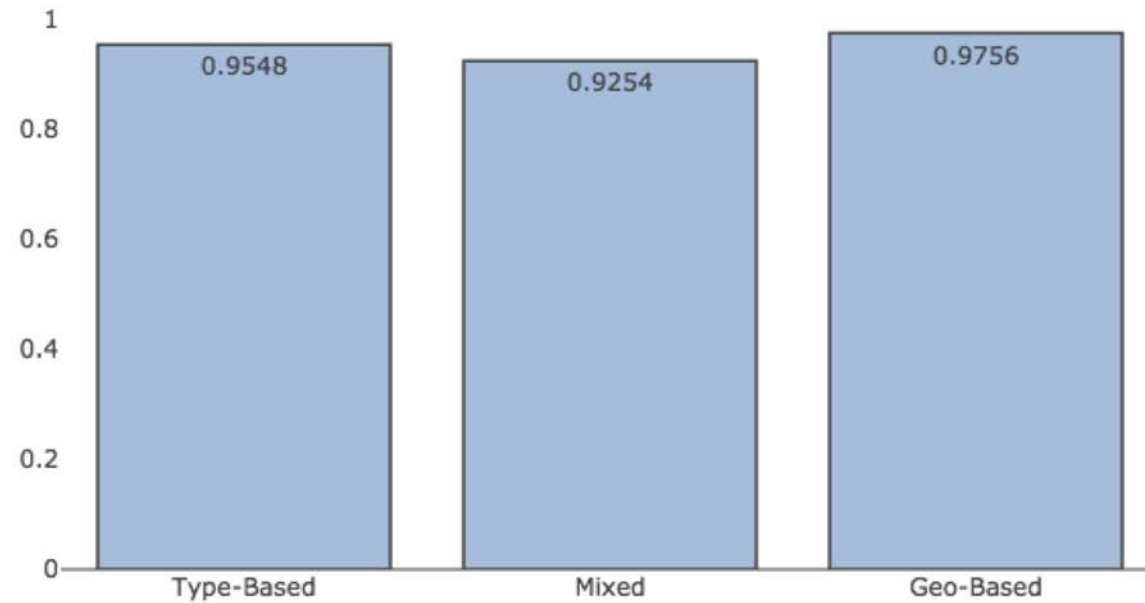
# Data Collection & cleaning

- Mechanical Turk
- 30 participants:180 trials in total
- 78 trials remained (23, 27, and 28 trials for Type-Based, Mixed and Geo-Based tasks respectively)

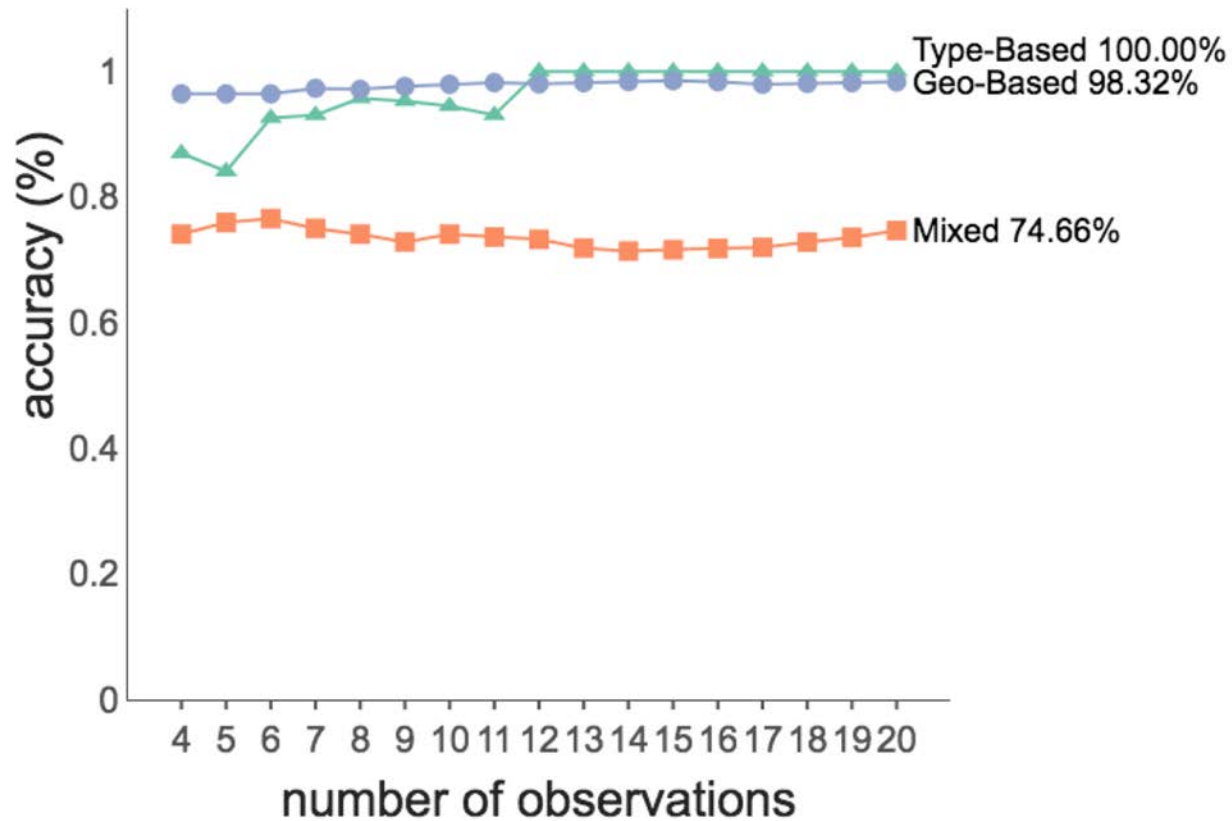
# Apply Model

- 1. Initialize particles
- 2. Dynamical model
- 3. Make prediction
- 4. Observe a click
- 5. Calculate weight and resample
- 6. Back to 2

# Prediction Accuracy



# Accuracy Over Time



# Design Implications

How would you design adaptive interface?



# Design implication

- Prompt potential options
- Eliminate irrelevant information
- Prefetching data point
- Accessibility: Bubble Cursor
  - [https://youtu.be/JUBXkD\\_8ZeQ?t=1m20s](https://youtu.be/JUBXkD_8ZeQ?t=1m20s)



Current Work: Predicting “high-level goals”

Research questions:

**WHO:** What learn personal characteristics?

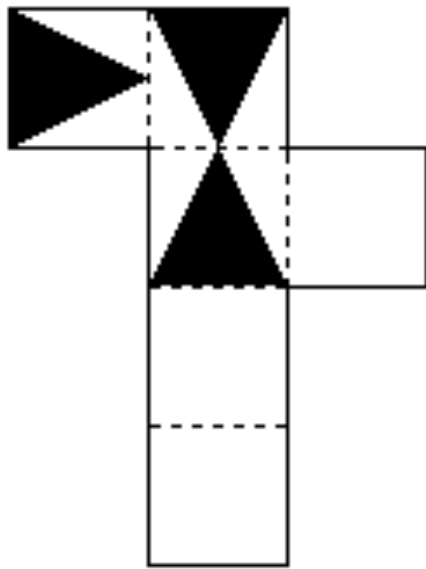
- I love to talk
- Socializing helps me feel energized and inspired
- I like to solve problems by discussing them
- People often describe me as friendly and approachable

If these describe you then you are an **Extravert**

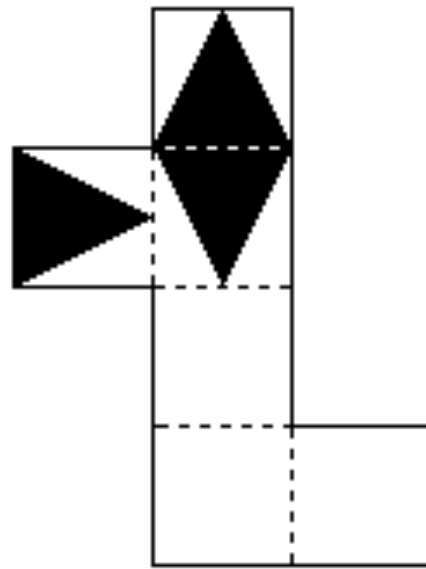
- What is going to happen will happen.
- No matter how hard you try, some people just don't like you
- Getting a good job depends mainly on being in the right place at the right time

If you believe these to be true then you have an  
**External Locus of Control**

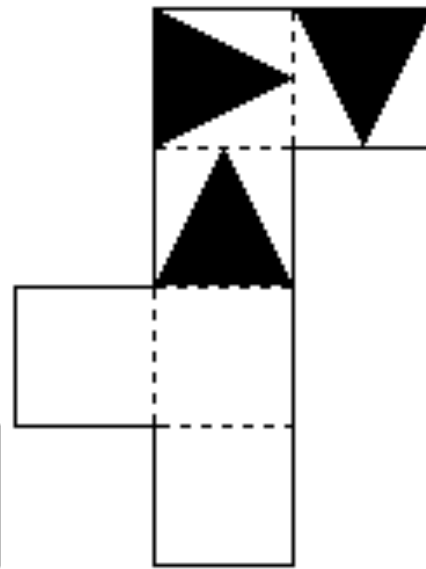
Which pattern can be folded to make the cube shown below?



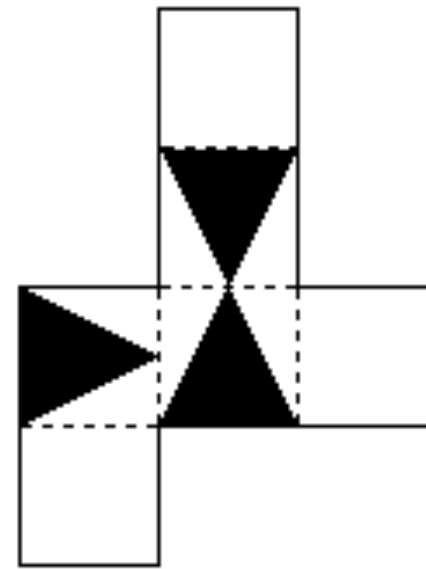
**A**



**B**

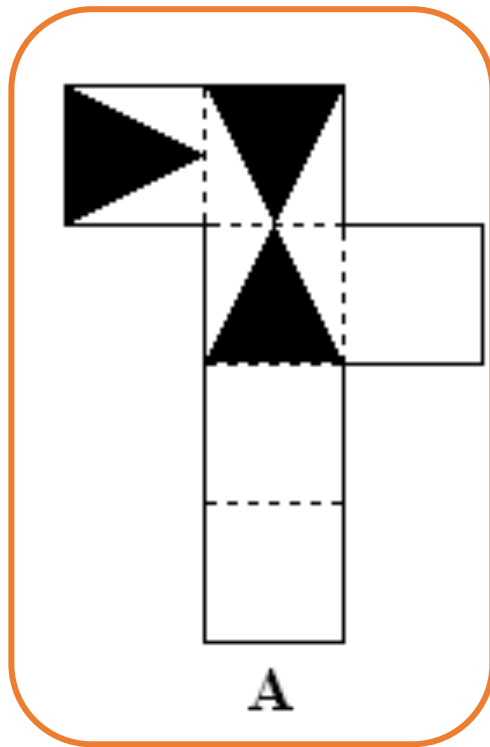
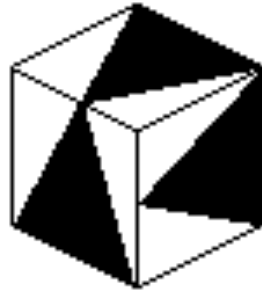


**C**

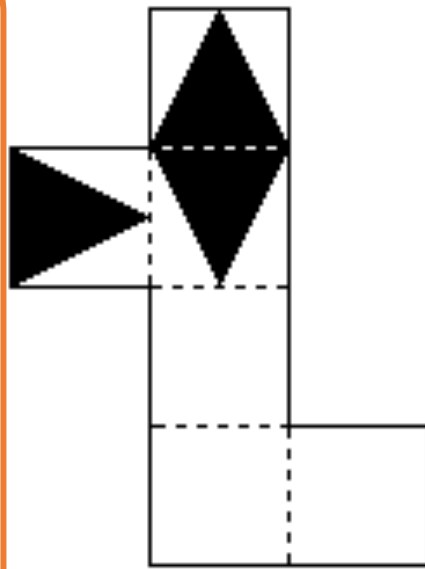


**D**

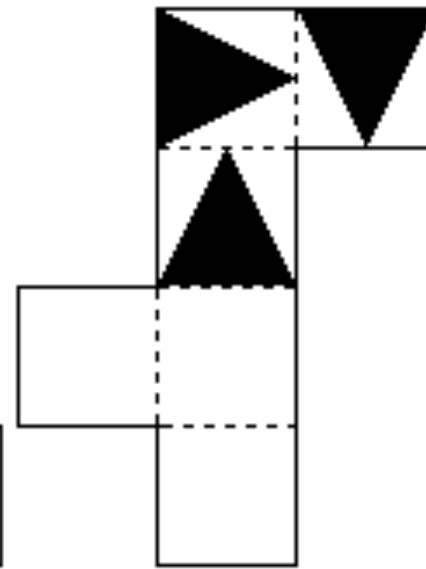
Which pattern can be folded to make the cube shown below?



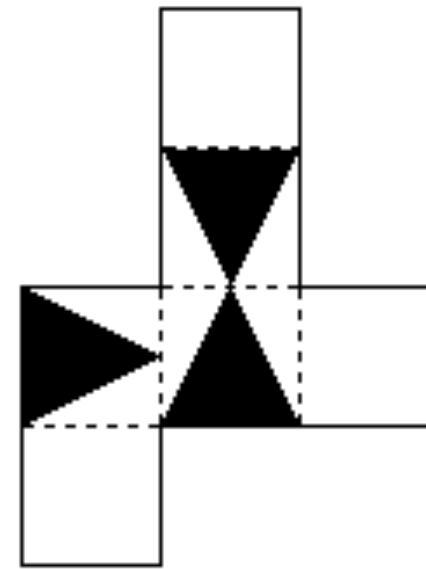
**A**



**B**

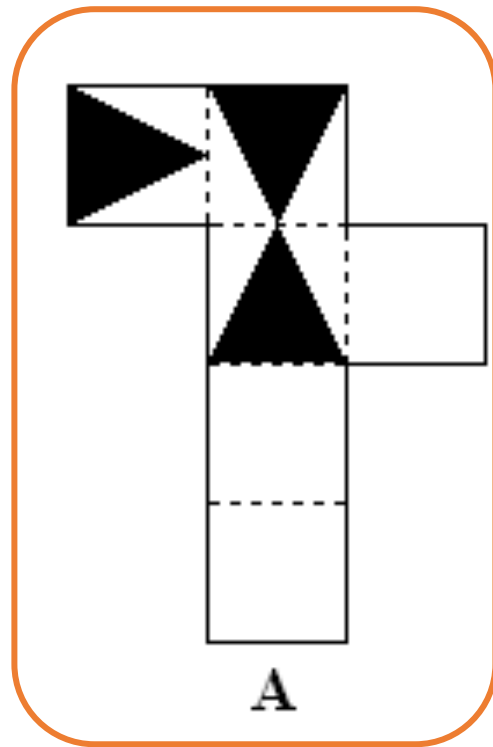


**C**

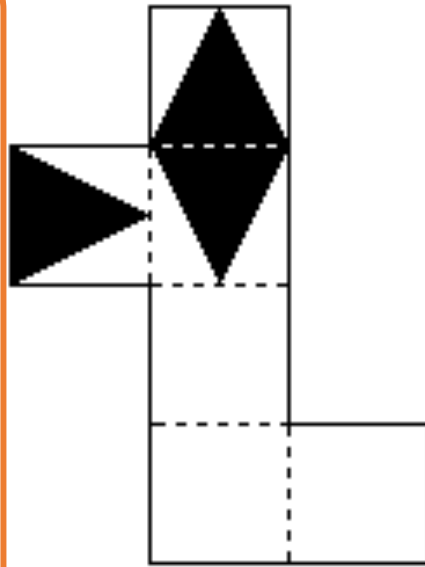


**D**

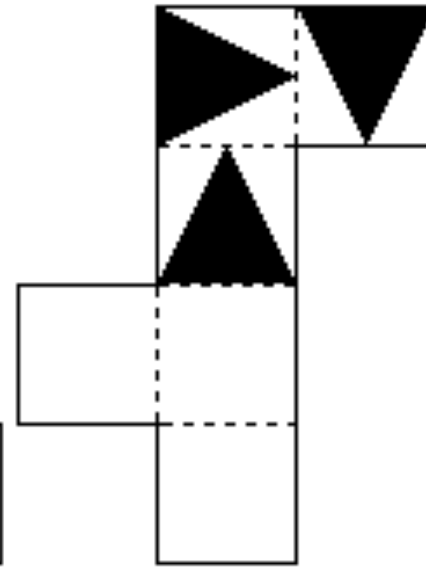
Spatial Ability measure how well we can mentally manipulate objects.



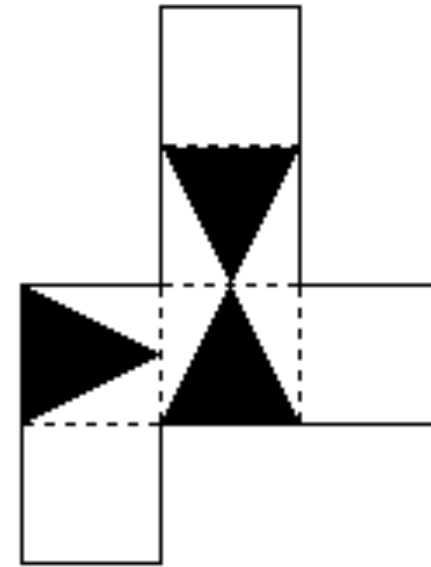
**A**



**B**



**C**



**D**



# Individual Differences

- Personality
- Views
- Cognitive Abilities

Why should we care?



Communicating Bayesian reasoning is important for medical decision-making.

Consider the following problem:

The probability of breast cancer is 1% for women at age forty who participate in routine screening. If a woman has breast cancer, the probability is 80% that she will get a positive mammography. If a woman does not have breast cancer, the probability is 9.6% that she will also get a positive mammography.

If a woman at age 40 is tested **positive**, what are her chances of **actually** having breast cancer?





The chance of **actually** having breast cancer given a **positive** mammogram:

**7.8%**



95 out of 100 **doctors**<sup>1</sup>  
estimate this probability  
to be:

**80%**

<sup>1</sup>Eddy, David M. "Probabilistic reasoning in clinical medicine: Problems and opportunities." (1982).

HEALTH

359 COMMENTS

# American Cancer Society, in a Shift, Recommends Fewer Mammograms

By DENISE GRADY OCT. 20, 2015

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One of the most respected and influential groups in the continuing breast-cancer screening debate said on Tuesday that women should begin [mammograms](#) later and have them less frequently than it had long advocated.

The [American Cancer Society](#), which has for years taken the most aggressive approach to screening, issued new guidelines on Tuesday, recommending that women with an average risk of [breast cancer](#) start having [mammograms](#) at 45 and continue once a year until 54, then every other year for as long as they are healthy and likely to live another 10 years.

The organization also said it no longer recommended clinical breast exams, in which doctors or nurses feel for lumps, for women of



A doctor reading mammograms at the University of Texas M.D. Anderson Cancer Center in Houston. The American Cancer Society said women should begin mammograms later and

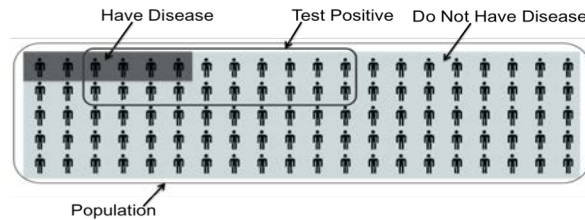
# Can visualizations help?

There is a newly discovered disease, Disease X, which is transmitted by a bacterial infection found in the population. There is a test to detect whether or not a person has the disease, but it is not perfect.

There is a total of 1000 people in the population. Out of the 1000 people in the population, 10

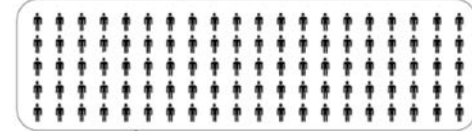
*Imagine 1000 people are tested for the disease.*  
(a) *How many people will test positive? \_\_\_\_*  
(b) *Of those who test positive, how many will actually have the disease? \_\_\_\_*

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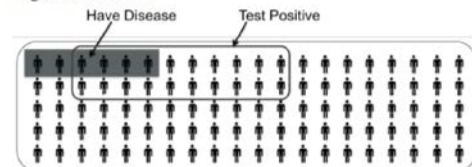
There is a total of 100 people in the population.



Out of the 100 people in the population, 6 people actually have the disease.



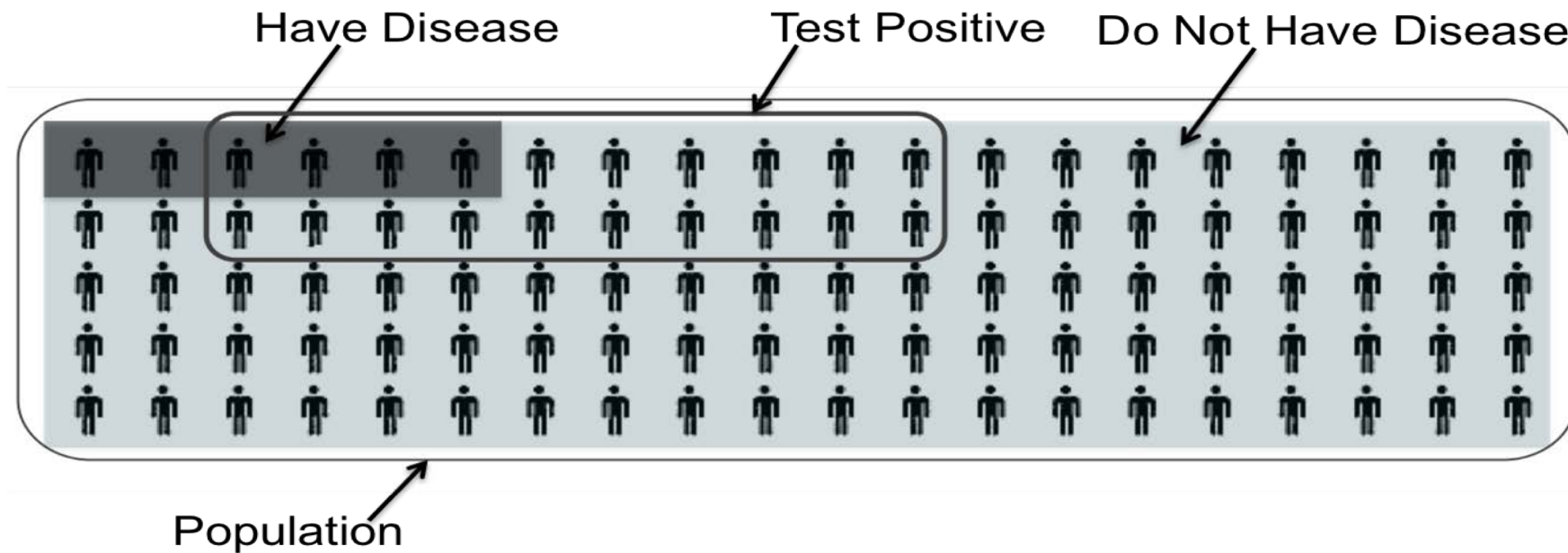
Out of these 6 people, 4 will receive a positive test result and 2 will receive a negative test result.



On the other hand, 94 people do not have the disease (i.e., they are perfectly healthy).



# Why this visual representation?

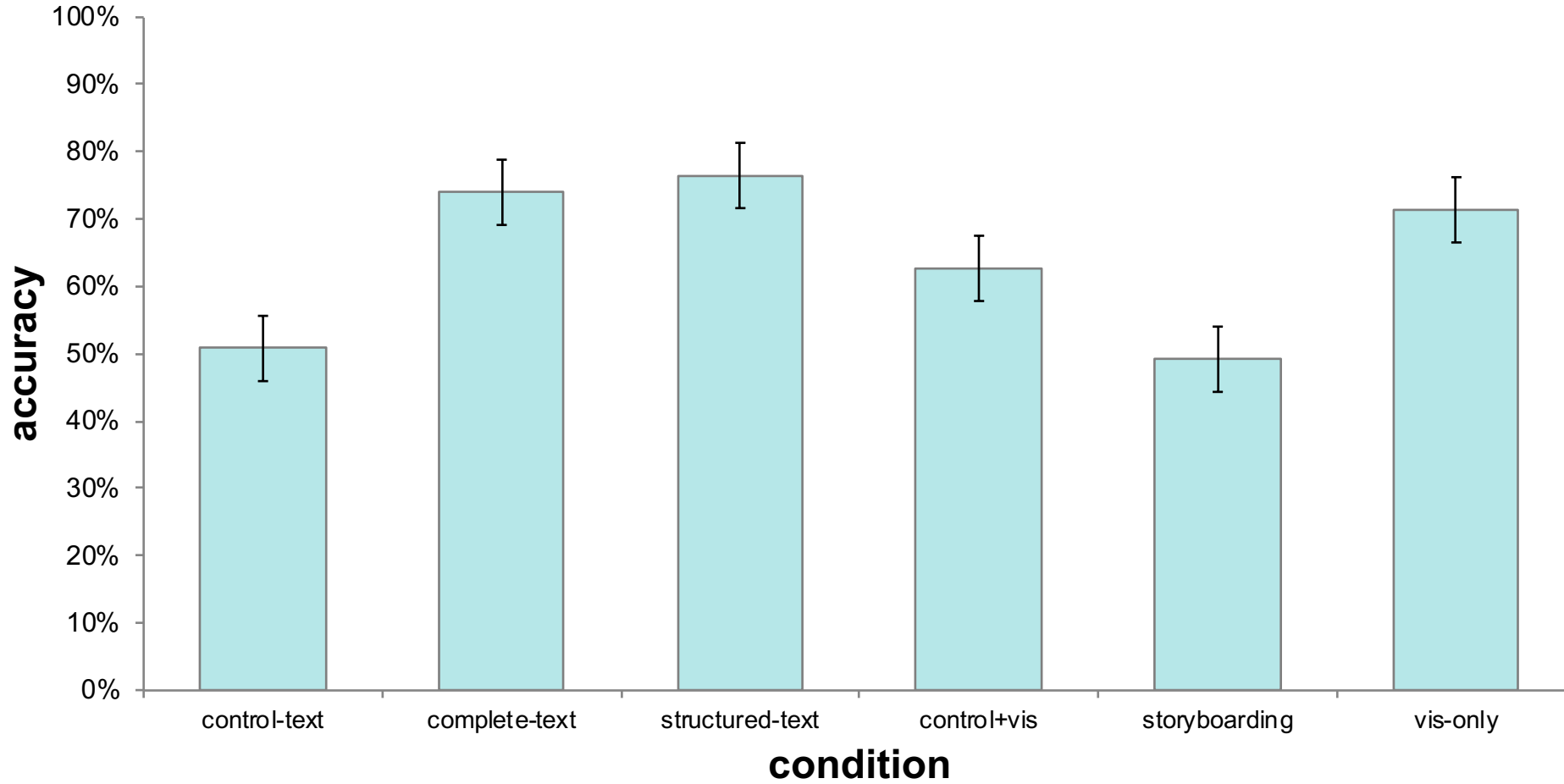


# Experiment Design

- 6 conditions
- 377 participants
- Also measured spatial ability

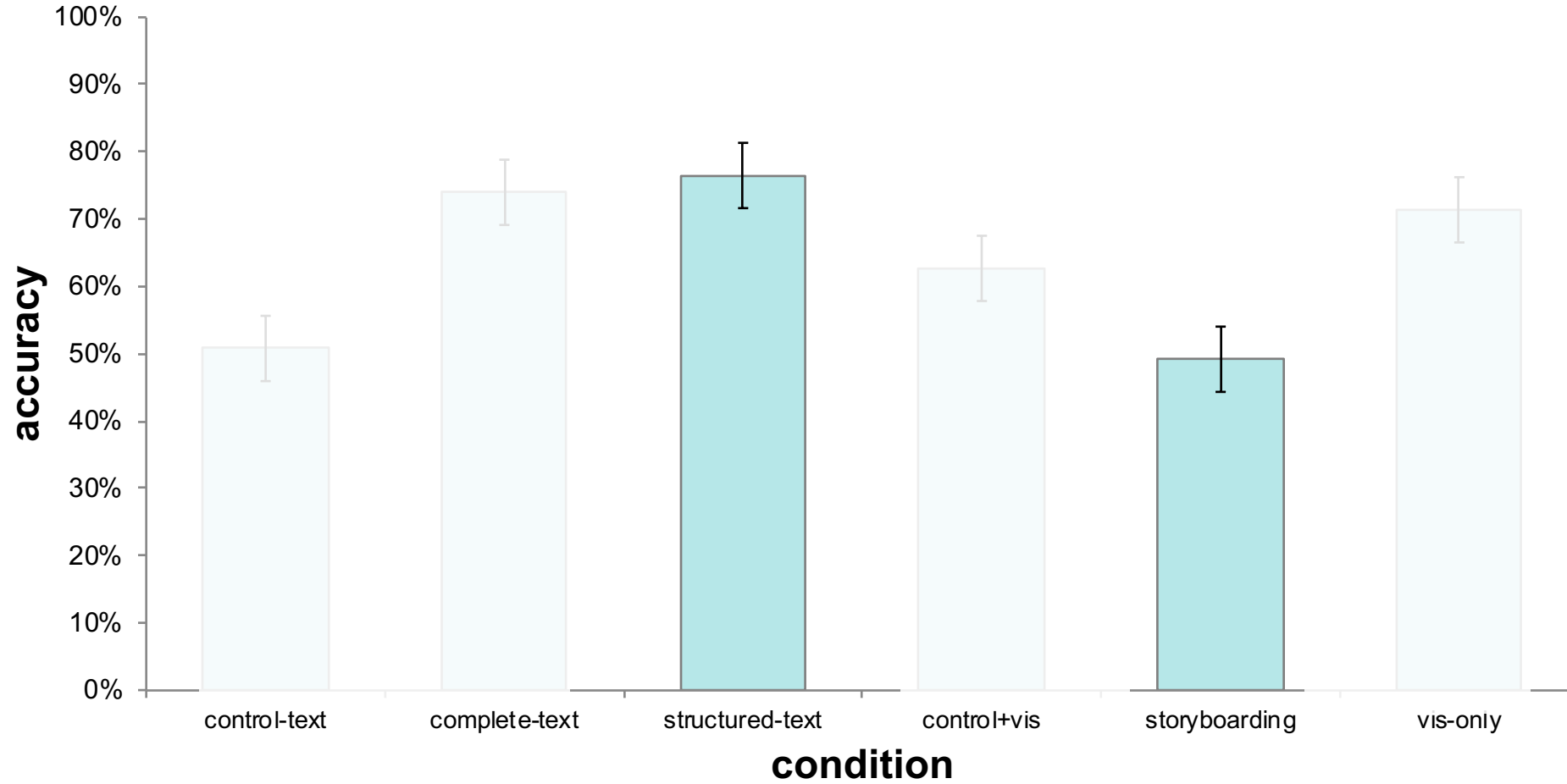


# Findings



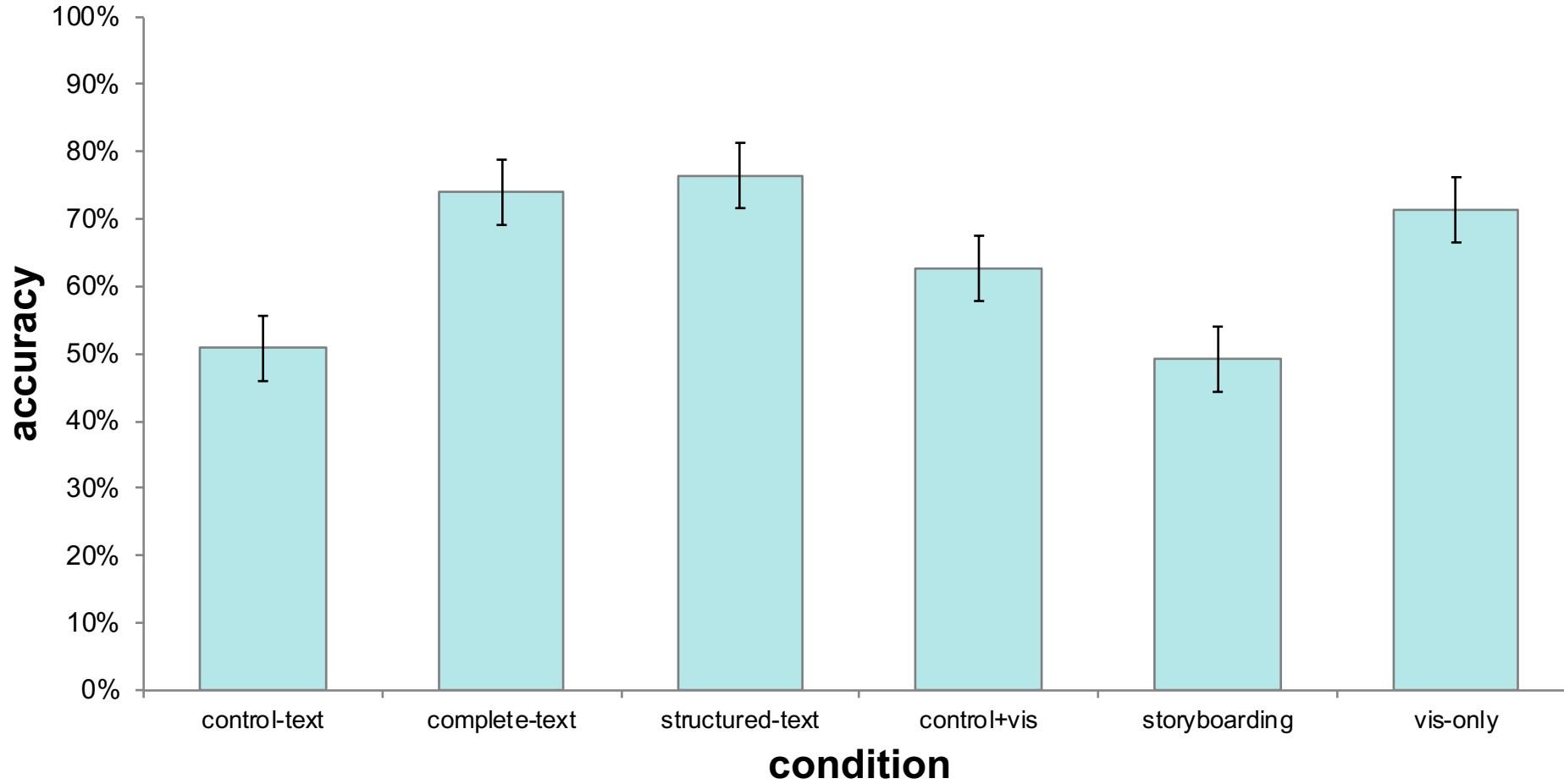
**p = 0.004**

# Findings

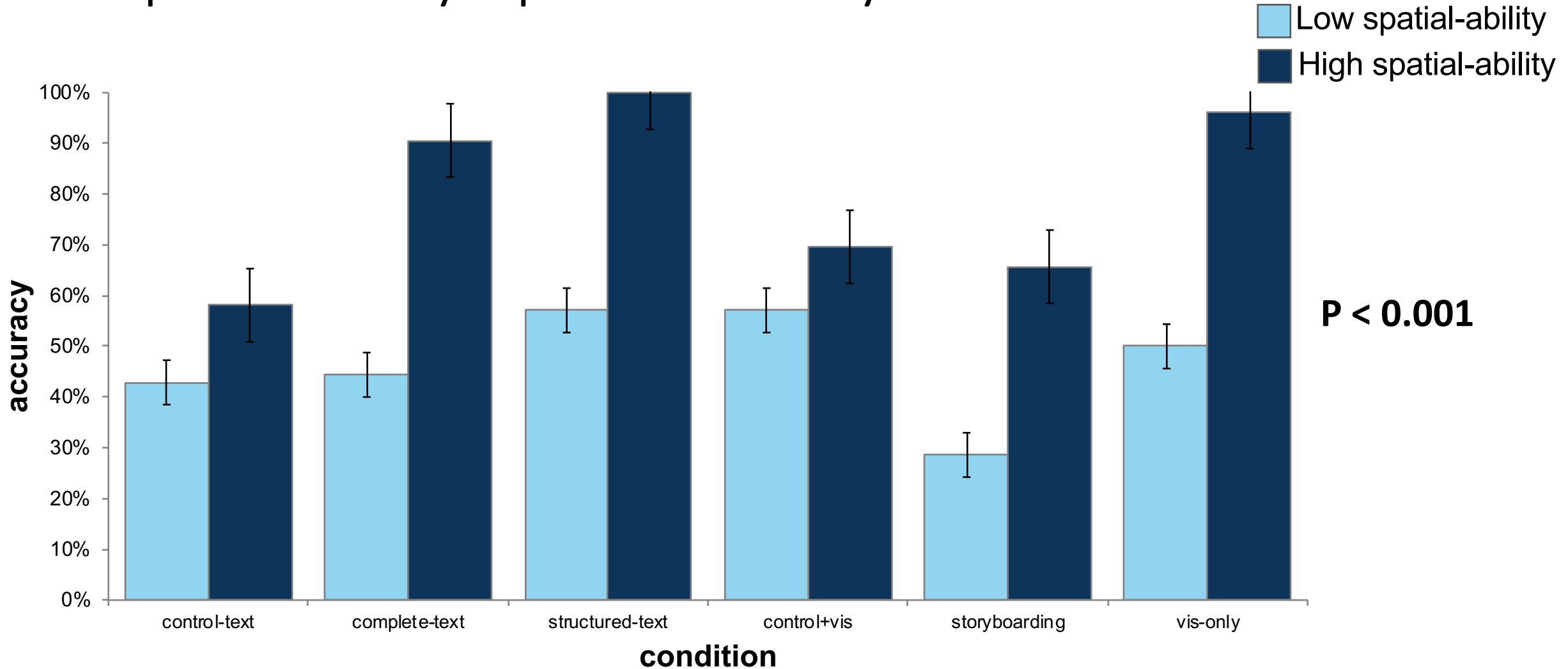


**p = 0.003**

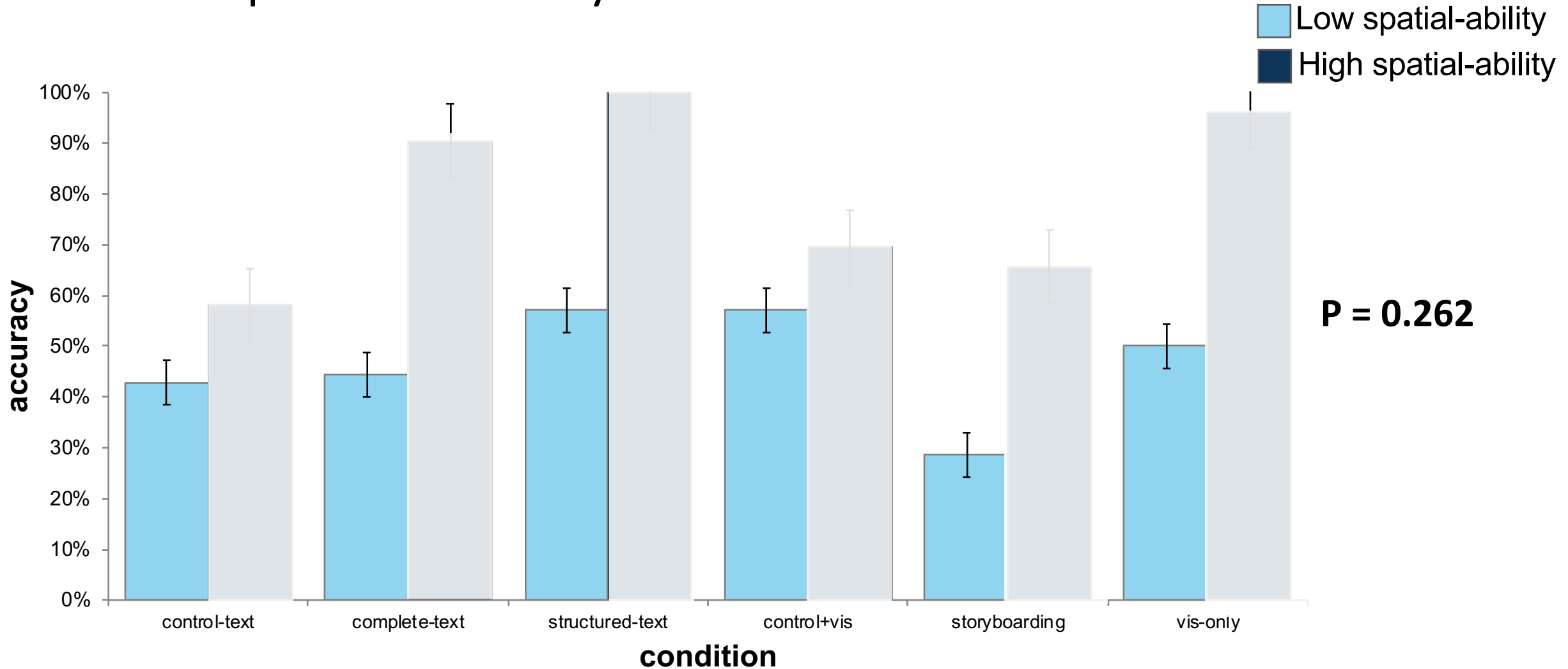
# Findings



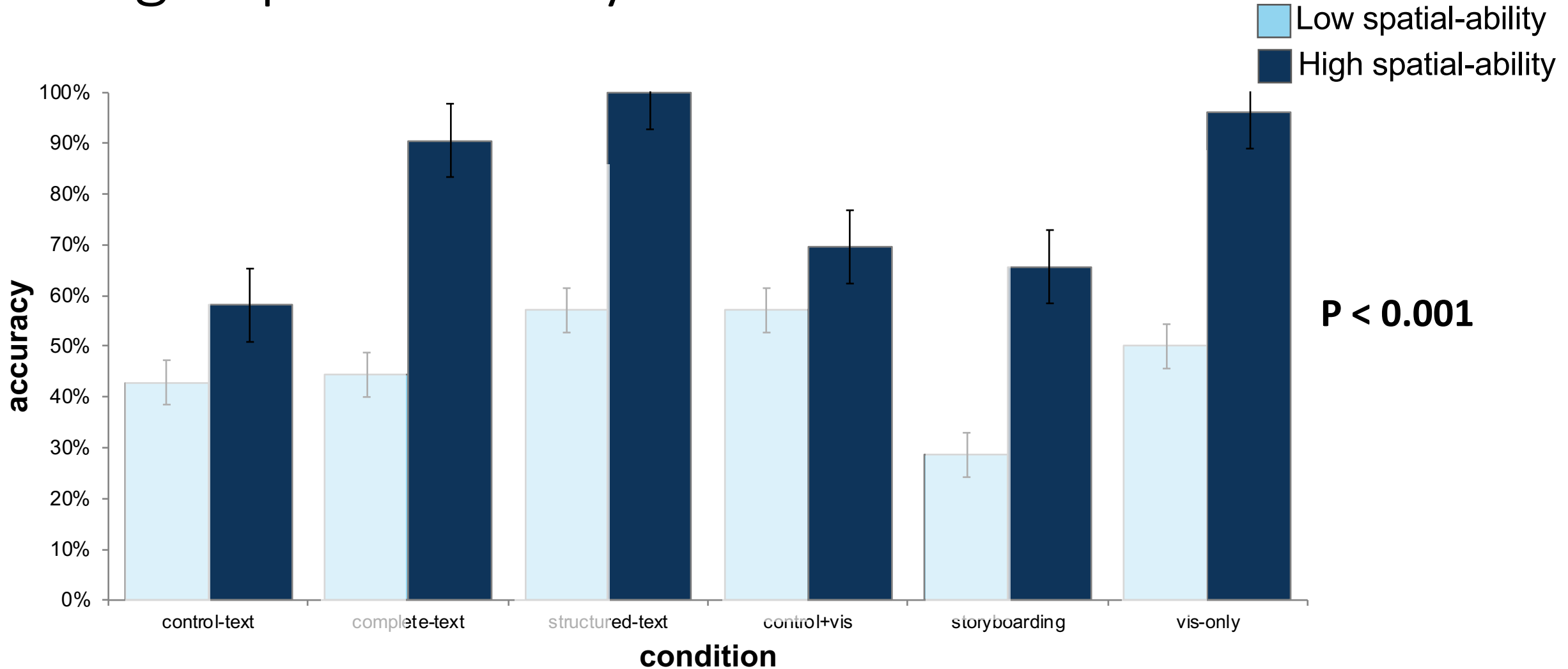
# Separated by Spatial Ability



# Low Spatial Ability Users

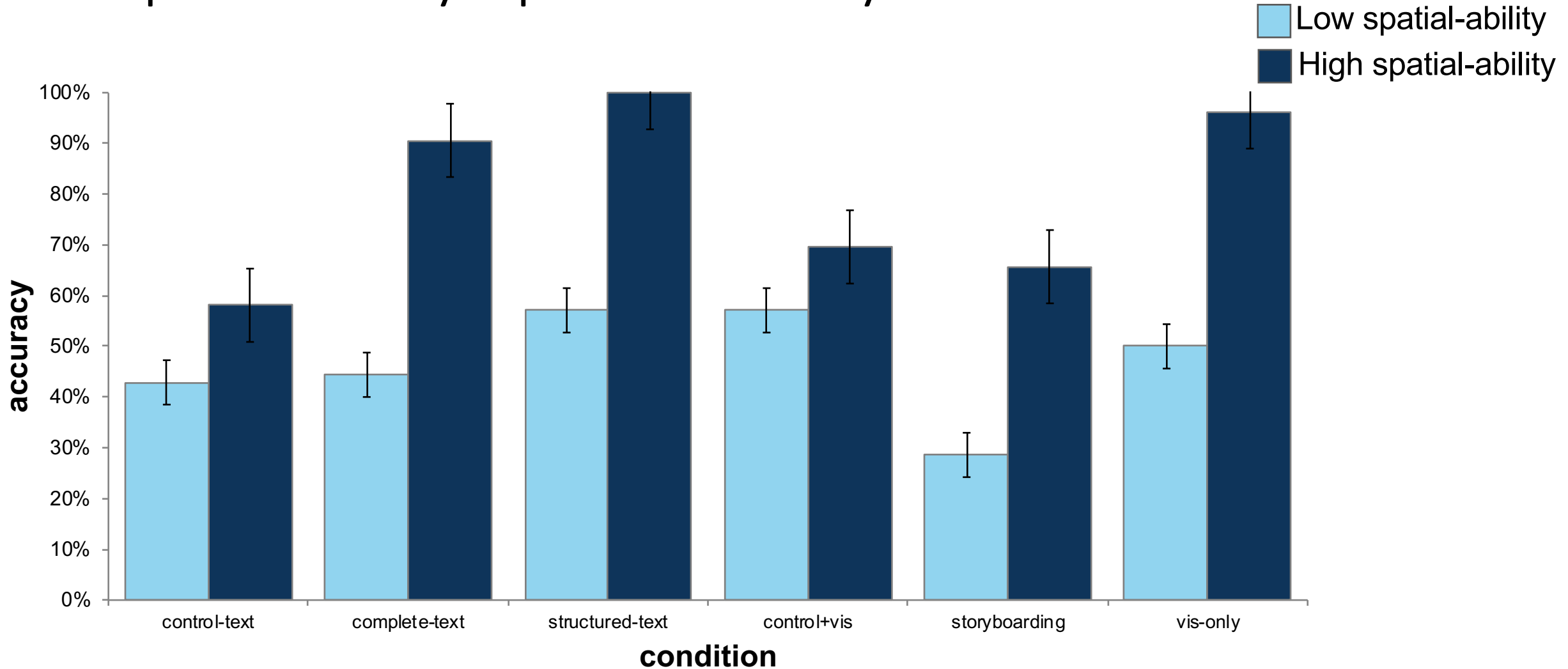


# High Spatial Ability Users





# Separated by Spatial Ability



Take away

Who we are matters

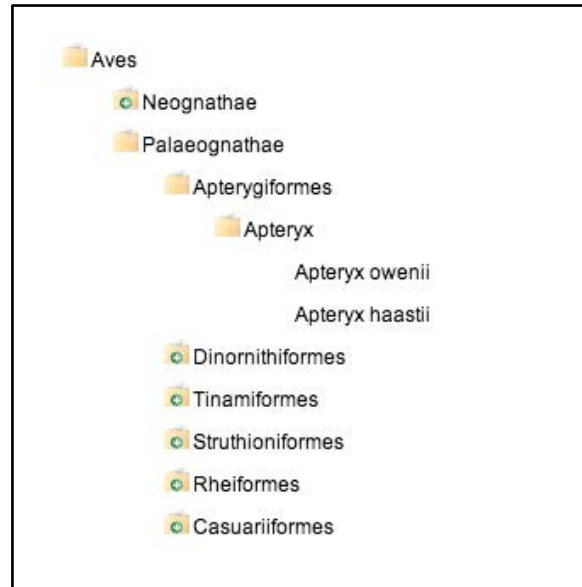


*Improving Bayesian Reasoning: The effects of phrasing, visualization, and spatial ability*

**A. Ottley**, E. M. Peck, D. Afergan, L. Harrison, H. Taylor, P. Han and R. Chang | InfoVis 2015.

What about other individual differences and tasks?

# What about other individual differences and tasks?



Extraversion, Neuroticism, and Locus of Control can predict speed and accuracy

*How visualization layout relates to locus of control and other personality factors*

C. Ziemkiewicz, **A. Ottley**, R. J. Crouser, A. Yauilla, S. Su, W. Ribarsky, R. Chang | TVCG 2012.

# Locus of Control

Recall: Locus of Control describes the extent to which someone feels in control of external events.

## External LOC

Believe that events are guided by fate, luck or powerful beings

## Internal LOC

Believe that events are guided by their own actions

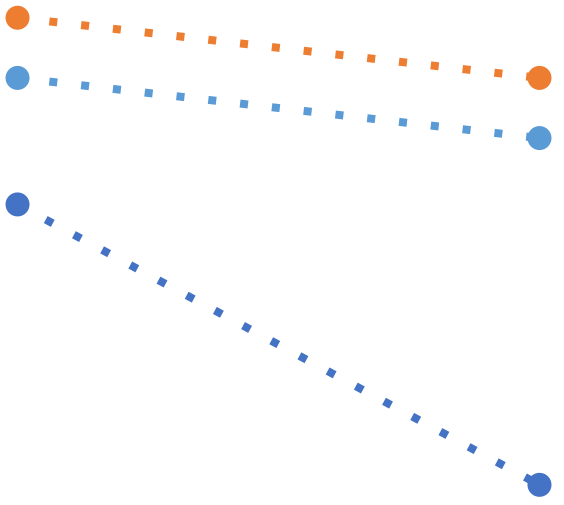


# Locus of Control Results

Performance

Good

Poor



- External LOC
- Average LOC
- Internal LOC

**P < 0.01**



Visual Form

But how robust is this effect?

# What is Priming?





# Priming Locus of Control

- **Internals** can be primed by asking them to think about times when **they did not feel in control**
- **Externals** can be primed by asking them to think about times when **they felt in control**

# Experiment Design

- 300 participants
- Primed locus of control
- Participants performed search tasks with the two hierarchical visualizations



# Priming text for reducing locus of control

“We know that one of the things that influence how well you can do everyday tasks is the number of obstacles you face on a daily basis. If you are having a particularly bad day today, you may not do as well as you might on a day when everything goes as planned. Variability is a normal part of life and you might think you can’t do much about that aspect.

In the spaces provided below, give 3 examples of times when you have felt out of control and unable to achieve something you set out to do. Each example must be at least 100 words long.”

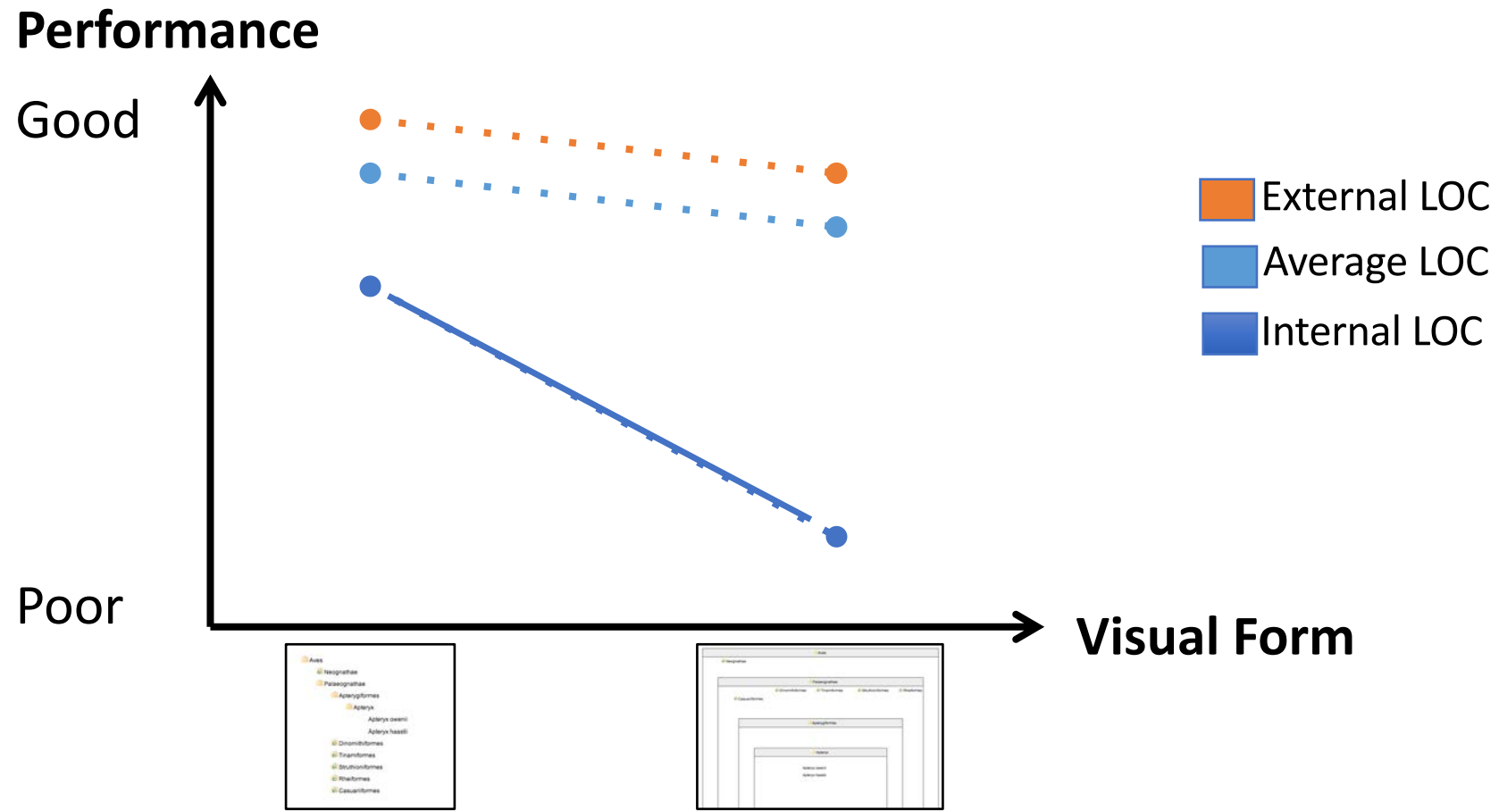
# Hypothesis/ Expectations



# Hypothesis/ Expectations



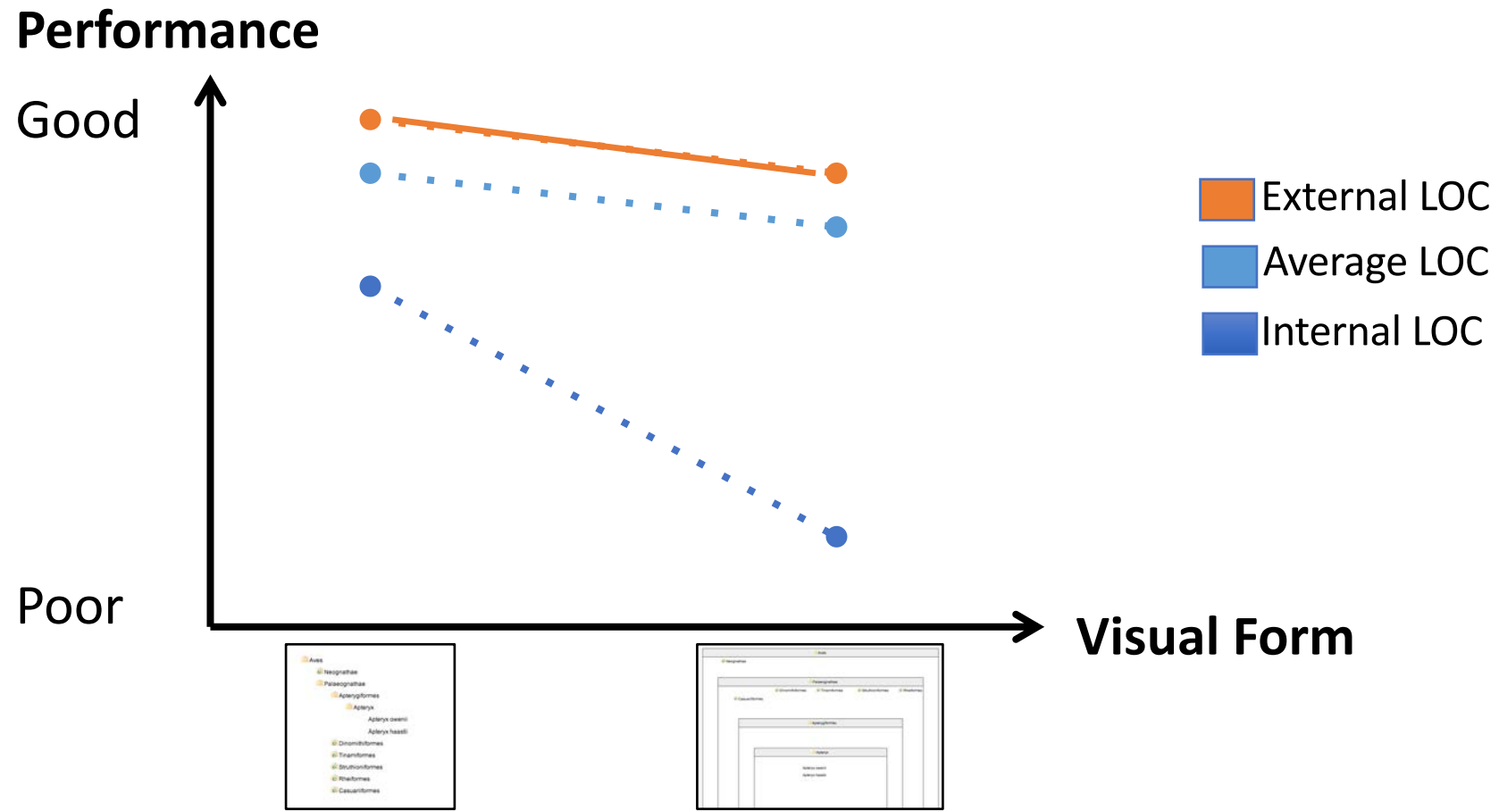
# Summary of Results



*Manipulating and Controlling for Personality Effects on Visualization Tasks*

**A. Ottley**, C. Ziemkiewicz, R. J. Crouser, R. Chang | IVI 2013

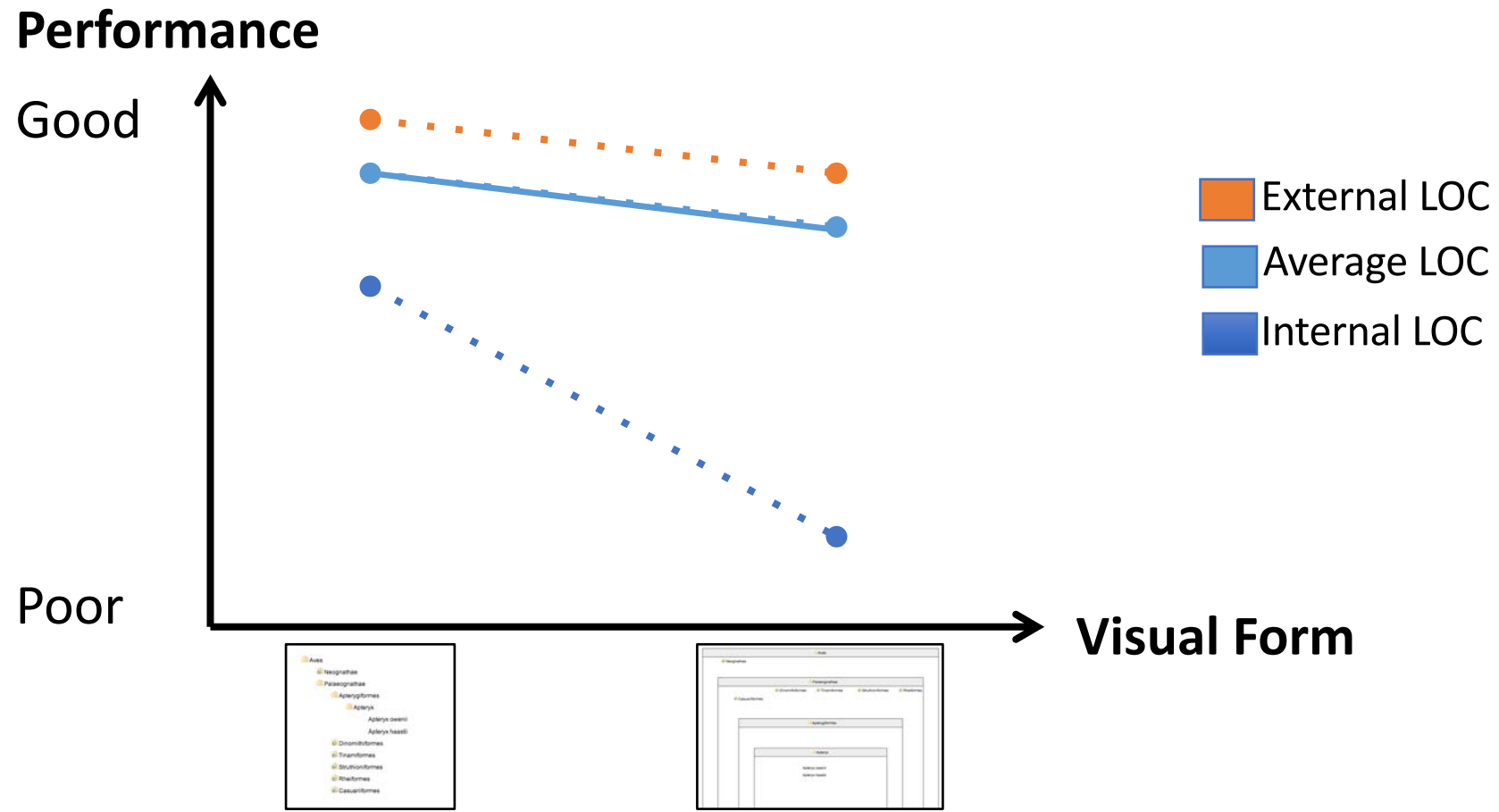
# Summary of Results



*Manipulating and Controlling for Personality Effects on Visualization Tasks*

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# Summary of Results

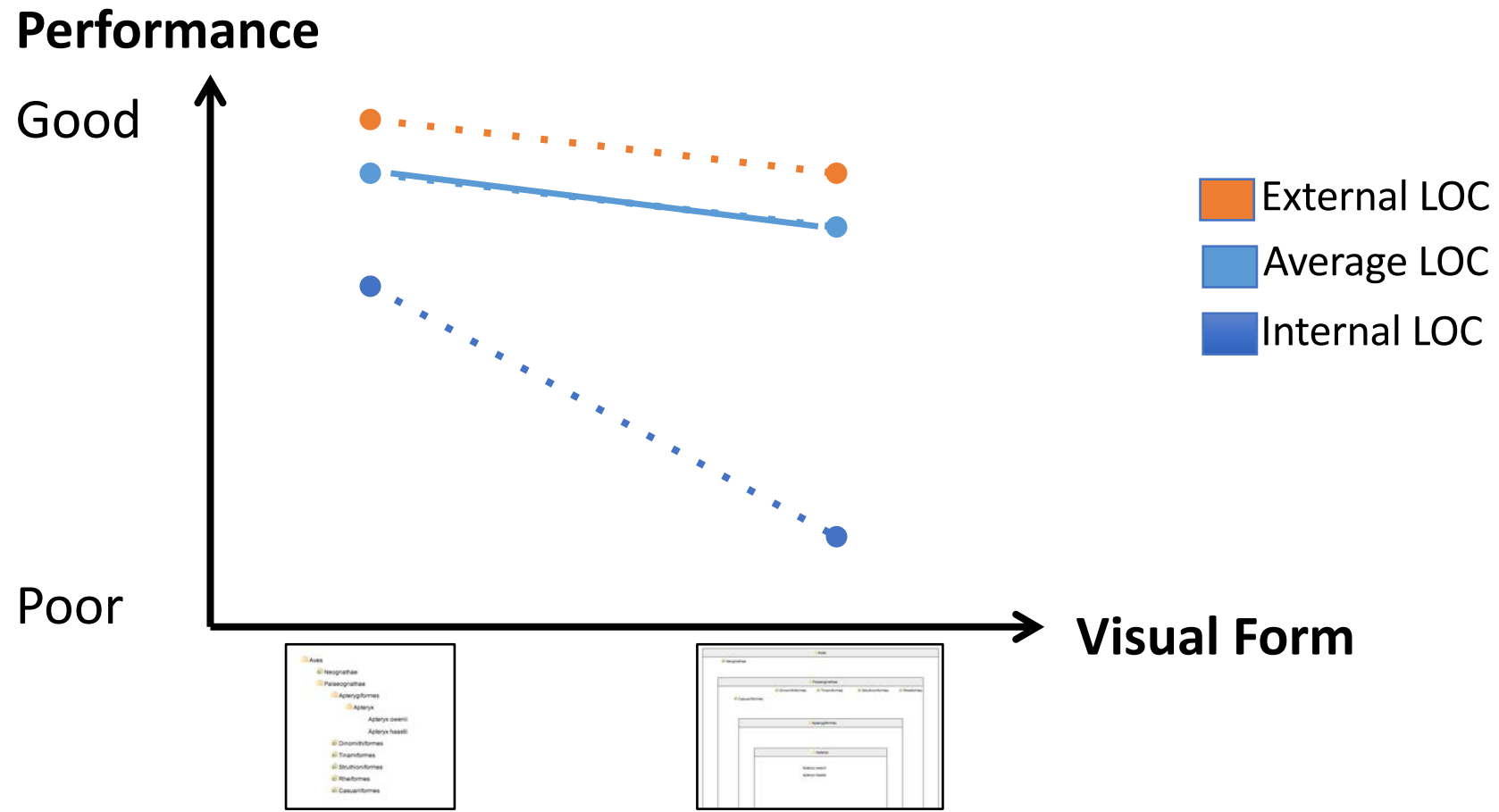


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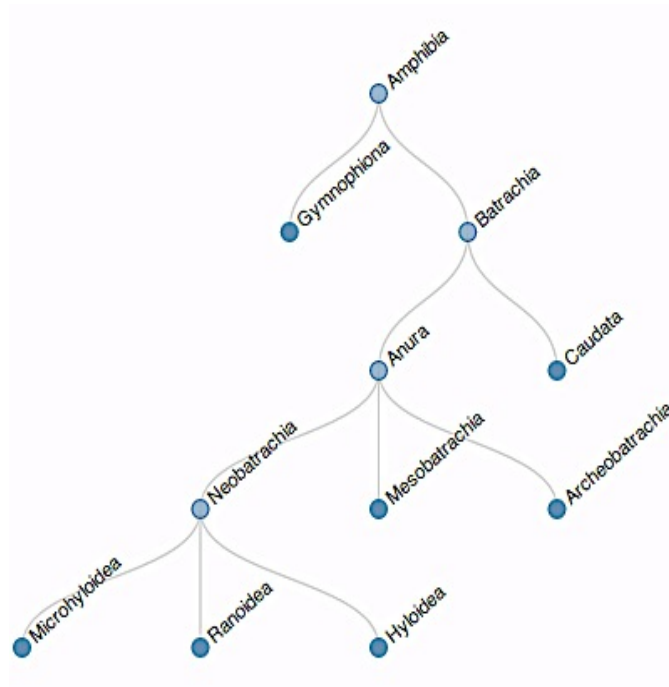
# Take away

- Individual differences matter
  - Spatial Ability
  - Extraversion
  - Neuroticism
  - Locus of Control
- There is a strong connection between locus of control and performance



Do individual differences impact strategies?

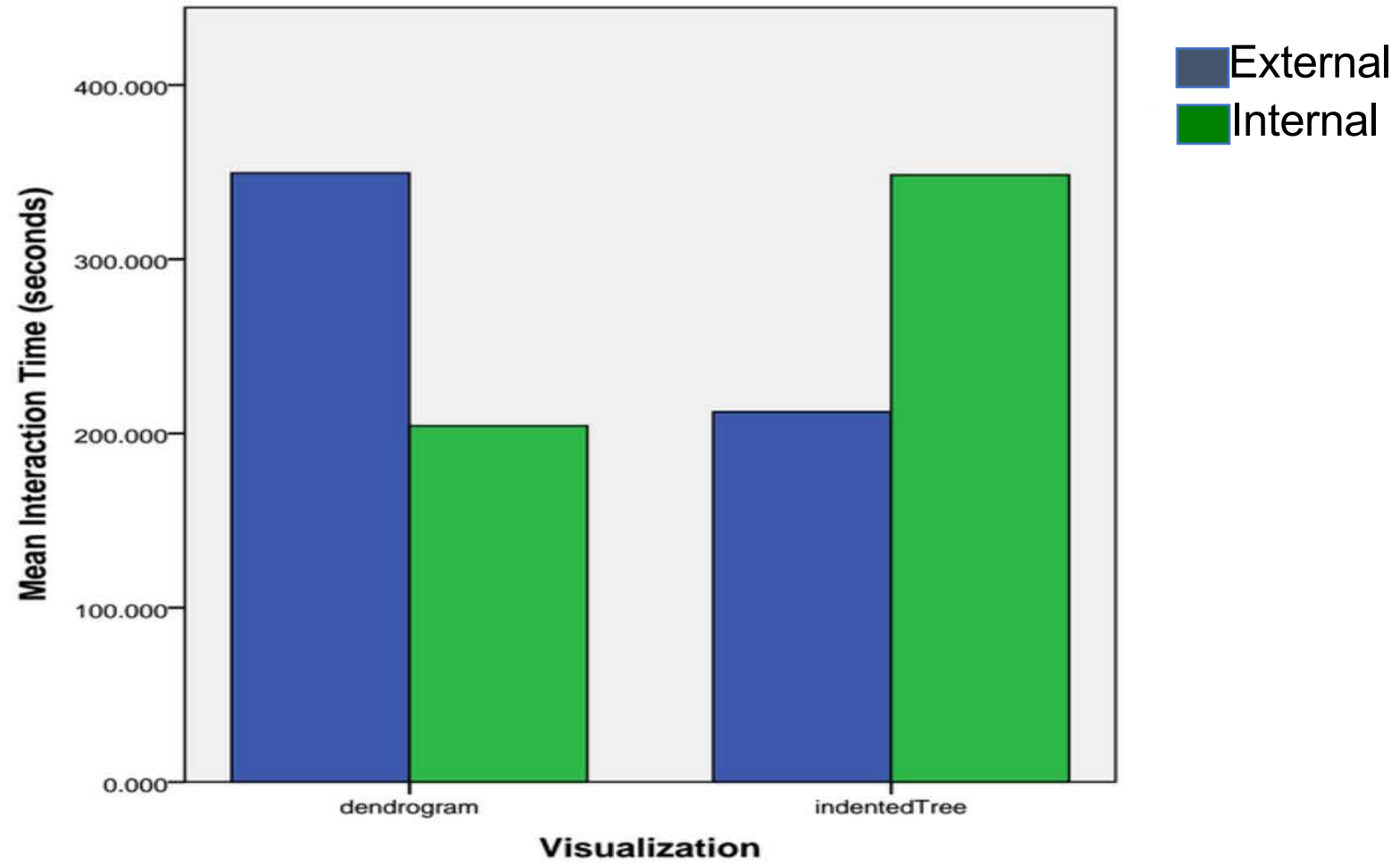
# Does Locus of Control impact user strategies?



# Experiment Design

- 54 participants
- Participants performed search tasks with the two hierarchical visualizations
- Captured mouse interaction





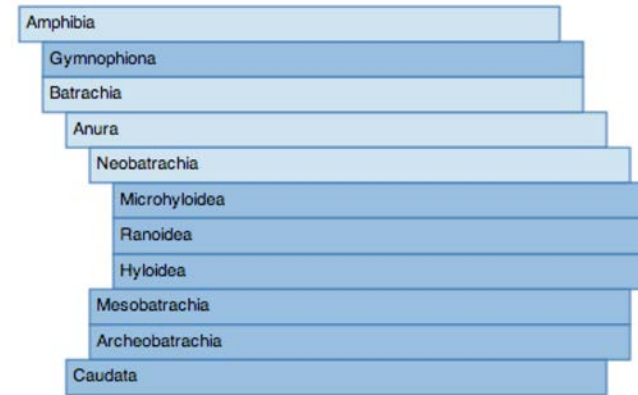
**p = 0.03**



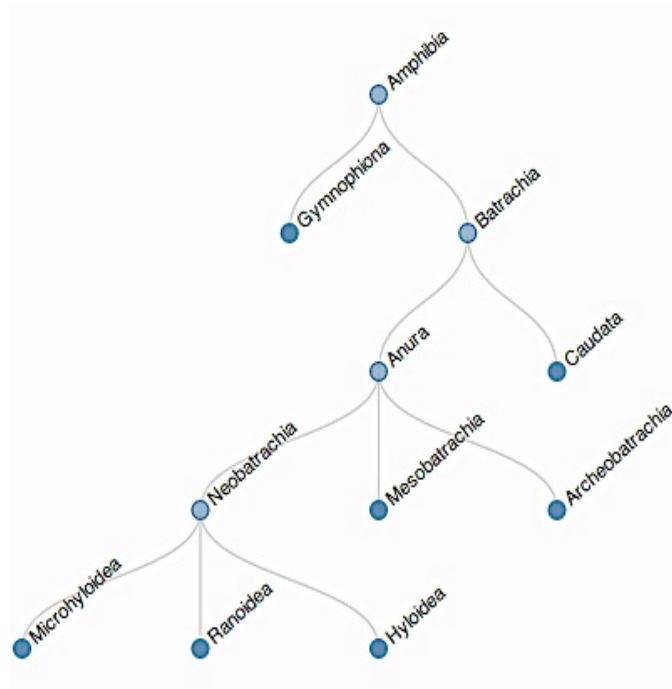
# Results Highlights

Internals were more likely to perform a breadth-first search

Externals were more likely to perform depth-first search



# Results Highlights



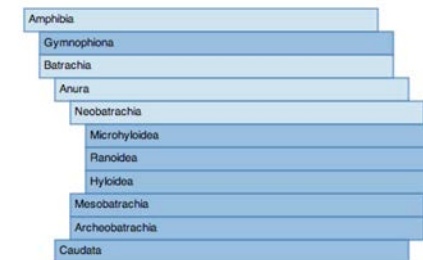
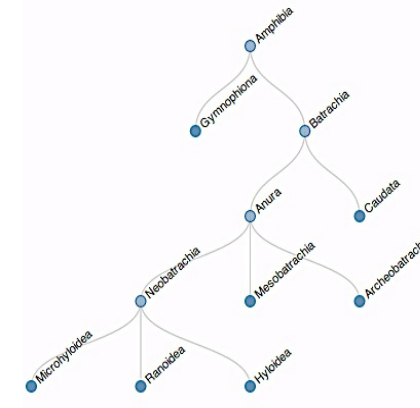
Internals were more likely to perform a combination of breadth-first and depth-first search

Externals were more likely to perform random search



# Locus of control influences strategies

- Locus of Control affects not only speed and accuracy, but also search strategies
- Interaction logs contain a great deal of information!
- Manual analysis is time consuming and not scalable.



Other Interests



ADVICE: Active  
Decision and  
Visualization  
Interface  
for Collaborative  
Environments



# Decision support for smart homes

supporting  
medical decision-  
making





# Visualization of Tomorrow

Questions?